

Camera.csv

n_frame	x	y	z	yaw	roll	pitch	cam_yaw	cam_roll	cam_pitch
0	1000	2000	3000	45	0	10	0	0	2
1	1001	2001	3001	46	0	10	0	0	2

Object_00.csv

n_frame	x	y	z	yaw	roll	pitch
0	5000	2000	3000	45	0	10
1	5001	2001	3001	46	0	10