BORK Error Code (U802 / U803)

Cause	Status Explanation	Key Movement	Display
1. No inner Pot	IH Power put into the cooker without inner pot	 Impossible to put the button (except cancel button) Every heater is shorted. 	
2. Top Sensor Open	Mark when the Top Sensor open Sensor hex is more "0xFD" (under −16℃)	 Impossible to put the button Every heater is shorted Turn to the normal mode when the sensor connected normally The normal range for Sensor hex 0x3 < Sensor Hex < 0xFD 	Err 2
3. Top Sensor Short (Same as Top Sensor high heating)	When Top Sensor is short or over-heating Sensor hex is under "0x3"(over200°C)		Err 3
4. Bottom Sensor Open	When the Bottom Sensor is opened Maintain 3 seconds when the Sensor hex is over "0xFD"(-16°Cunder)	- Impossible to put the button - Every heater is shorted - Turn to the normal mode when the sensor connected normally - The normal range for Sensor hex 0x3 < Sensor Hexat < 0xFD	Err 4
5. Bottom Sensor Short (Same as Top Sensor high heating)	When the Bottom Sensor is Short or overheated When Sensor hex in under"0x3"(over 200℃)		W
6. Environment Sensor Open	When the environment sensor is opened, Sensor hex is over "0xE4"(under -20℃)	 The environment sensor have problem, the warming algorithm is operating as basic algorithm.(default algorithm) No error mark directly and mark the environment checking of the DEMO mode The normal range for Sensor hex 0x16 <= Sensor Hex <=0xFD 	Err 6
7. Environment Sensor Short	When the environment sensor is shorted Sensor hex is under "0x16"(100℃ over)		Err 7

BORK Error Code (U802 / U803)

Cause	Status Explanation	Key Movement	Display
8. Bottom Sensor Wrong Movement	 After cooking start and some procedure is finished, the temperature of B/S is under standard, the bottom sensor recognize as wrong movement. Power code OFF -> ON operating □ turn to the regular mode 	* Time Protect will be blocking, the error is happened.	Err 8