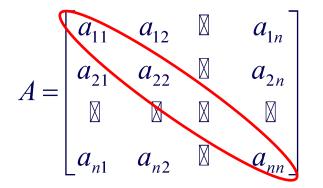
Linear Algebra



Chapter 2 Matrix Algebra

2.1 Addition, Scalar Multiplication, and Multiplication of Matrices

a_{ij}: the element of matrix *A* in row *i* and column *j*.
For a square *n×n* matrix *A*, the main diagonal is:



Definition

Two matrices are **equal** if they are of the <u>same size</u> and if their corresponding elements <u>are equal</u>.

Thus
$$A = B$$
 if $a_{ij} = b_{ij} \quad \forall i,$
j.

$$(\forall \text{ for every, for all})$$



Addition of Matrices

Definition

Let A and B be matrices of the same size.

Their sum A + B is the matrix obtained by adding together the corresponding elements of A and B.

The matrix A + B will be of the same size as A and B.

If *A* and *B* are not of the same size, they cannot be added, and we say that **the sum does not exist**.

Thus if C = A + B, then $c_{ij} = a_{ij} + b_{ij} \quad \forall i, j$.





Let
$$A = \begin{bmatrix} 1 & 4 & 7 \\ 0 & -2 & 3 \end{bmatrix}$$
, $B = \begin{bmatrix} 2 & 5 & -6 \\ -3 & 1 & 8 \end{bmatrix}$, and $C = \begin{bmatrix} -5 & 4 \\ 2 & 7 \end{bmatrix}$.

Determine A + B and A + C, if the sum exist.

Solution

(1)
$$A + B = \begin{bmatrix} 1 & 4 & 7 \\ 0 & -2 & 3 \end{bmatrix} + \begin{bmatrix} 2 & 5 & -6 \\ -3 & 1 & 8 \end{bmatrix}$$

= $\begin{bmatrix} 1+2 & 4+5 & 7-6 \\ 0-3 & -2+1 & 3+8 \end{bmatrix}$
= $\begin{bmatrix} 3 & 9 & 1 \\ -3 & -1 & 11 \end{bmatrix}$.

(2) Because A is 2×3 matrix and C is a 2×2 matrix, they are not of the same size, A + C does not exist.

Scalar Multiplication of matrices

Definition

Let A be a matrix and c be a scalar. The scalar multiple of A by c, denoted cA, is the matrix obtained by multiplying every element of A by c. The matrix cA will be the same size as A.

Thus if B = cA, then $b_{ij} = ca_{ij} \forall i, j$.

Example 2 Let $A = \begin{bmatrix} 1 & -2 & 4 \\ 7 & -3 & 0 \end{bmatrix}$. $3A = \begin{bmatrix} 3 \times 1 & 3 \times (-2) & 3 \times 4 \\ 3 \times 7 & 3 \times (-3) & 3 \times 0 \end{bmatrix} = \begin{bmatrix} 3 & -6 & 12 \\ 21 & -9 & 0 \end{bmatrix}$.

Observe that A and 3A are both 2×3 matrices.

Negation and Subtraction

Definition

We now define subtraction of matrices in such a way that makes it compatible with addition, scalar multiplication, and negative. Let

$$A - B = A + (-1)B$$

Example 3

Suppose
$$A = \begin{bmatrix} 5 & 0 & -2 \\ 3 & 6 & -5 \end{bmatrix}$$
 and $B = \begin{bmatrix} 2 & 8 & -1 \\ 0 & 4 & 6 \end{bmatrix}$.
$$A - B = \begin{bmatrix} 5 - 2 & 0 - 8 & -2 - (-1) \\ 3 - 0 & 6 - 4 & -5 - 6 \end{bmatrix} = \begin{bmatrix} 3 & -8 & -1 \\ 3 & 2 & -11 \end{bmatrix}$$
.

Multiplication of Matrices

Definition

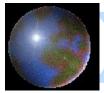
Let the number of columns in a matrix A be the same as the number of rows in a matrix B. The product AB then exists.

Let A: $m \times n$ matrix, B: $n \times k$ matrix, The **product matrix** *C*=*AB* has elements

$$c_{ij} = \begin{bmatrix} a_{i1} & a_{i2} & \boxtimes & a_{i\underline{n}} \end{bmatrix} \begin{bmatrix} b_{1j} \\ b_{2j} \\ \boxtimes \\ b_{\underline{n}j} \end{bmatrix} = a_{i1}b_{1j} + a_{i2}b_{2j} + \boxtimes + a_{i\underline{n}}b_{\underline{n}j}$$

C is a $m \times k$ matrix.

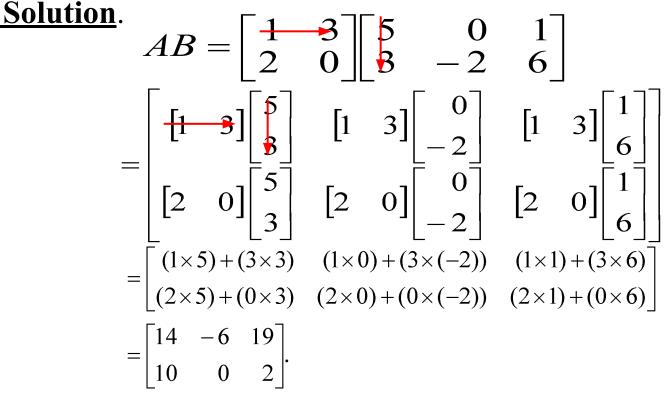
If the number of columns in *A* does not equal the number of row *B*, we say that **the product does not exist**.



Example 4

Let
$$A = \begin{bmatrix} 1 & 3 \\ 2 & 0 \end{bmatrix}$$
, $B = \begin{bmatrix} 5 & 0 & 1 \\ 3 & -2 & 6 \end{bmatrix}$, and $C = \begin{bmatrix} 6 & -2 & 5 \end{bmatrix}$.

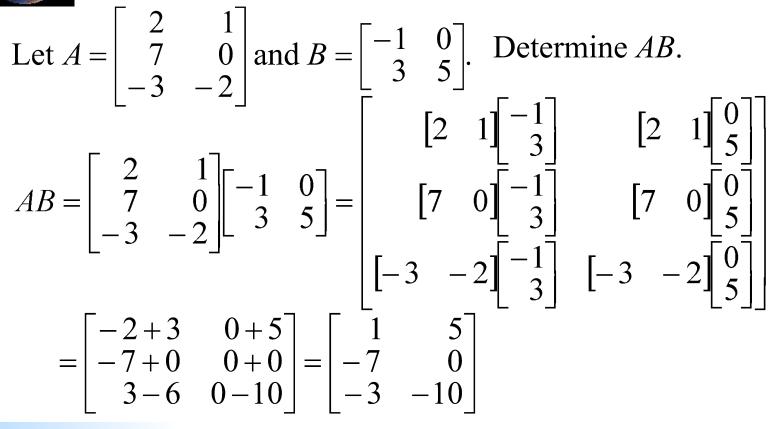
Determine AB, BA, and AC, if the products exist.



BA and *AC* do not exist.

Note. In general, $AB \neq BA$.

Example 5



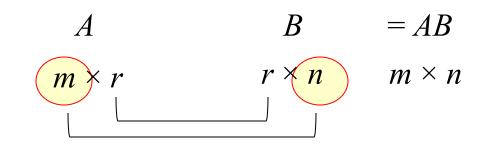
Example 6

Let
$$C = AB$$
, $A = \begin{bmatrix} 2 & 1 \\ -3 & 4 \end{bmatrix}$ and $B = \begin{bmatrix} -7 & 3 & 2 \\ 5 & 0 & 1 \end{bmatrix}$ Determine c_{23} .
 $c_{23} = \begin{bmatrix} -3 & 4 \end{bmatrix} \begin{bmatrix} 2 \\ 1 \end{bmatrix} = (-3 \times 2) + (4 \times 1) = -2$

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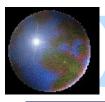
Size of a Product Matrix

If *A* is an $m \times r$ matrix and *B* is an $r \times n$ matrix, then *AB* will be an $m \times n$ matrix.



Example 7

If *A* is a 5×6 matrix and *B* is an 6×7 matrix. Because *A* has six columns and *B* has six rows. Thus *AB* exits. And *AB* will be a 5×7 matrix.



Special Matrices

Definition

A zero matrix is a matrix in which all the elements are zeros.

A **diagonal matrix** is a square matrix in which all the elements not on the main diagonal are zeros.

An **identity matrix** is a diagonal matrix in which every diagonal element is 1.

$$O_{mn} = \begin{bmatrix} 0 & 0 & \boxtimes & 0 \\ 0 & 0 & \boxtimes & 0 \\ \boxtimes & \boxtimes & \boxtimes & \boxtimes \\ 0 & 0 & \boxtimes & 0 \end{bmatrix} \quad A = \begin{bmatrix} a_{11} & 0 & \boxtimes & 0 \\ 0 & a_{22} & \boxtimes & 0 \\ \boxtimes & \boxtimes & \boxtimes & \boxtimes \\ 0 & 0 & \boxtimes & \infty \end{bmatrix}$$

$$I_n = \begin{bmatrix} 1 & 0 & \boxtimes & 0 \\ 0 & 1 & \boxtimes & 0 \\ \boxtimes & \boxtimes & \boxtimes & \boxtimes \\ 0 & 0 & \boxtimes & 1 \end{bmatrix}$$

identity matrix

zero matrix

diaginal matrix A

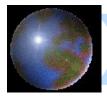
Theorem 2.1

Let *A* be $m \times n$ matrix and O_{mn} be the zero $m \times n$ matrix. Let *B* be an $n \times n$ square matrix. O_n and I_n be the zero and identity $n \times n$ matrices. Then

$$A + O_{mn} = O_{mn} + A = A$$
$$BO_{n} = O_{n}B = O_{n}$$
$$BI_{n} = I_{n}B = B$$

Example 8

Let
$$A = \begin{bmatrix} 2 & 1 & -3 \\ 4 & 5 & 8 \end{bmatrix}$$
 and $B = \begin{bmatrix} 2 & 1 \\ -3 & 4 \end{bmatrix}$.
 $A + O_{23} = \begin{bmatrix} 2 & 1 & -3 \\ 4 & 5 & 8 \end{bmatrix} + \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} 2 & 1 & -3 \\ 4 & 5 & 8 \end{bmatrix} = A$
 $BO_2 = \begin{bmatrix} 2 & 1 \\ -3 & 3 \end{bmatrix} \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} = O_2$
 $BI_2 = \begin{bmatrix} 2 & 1 \\ -3 & 4 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 2 & 1 \\ -3 & 4 \end{bmatrix} = B$



Homework

• Exercises will be given by the teachers of the practical classes.

Exercise

Let *A* be a matrix whose third row is all zeros. Let *B* be any matrix such that the product *AB* exists. Prove that the third row of *AB* is all zeros.

Solution

$$(AB)_{3i} = \begin{bmatrix} a_{31} & a_{32} \\ B_{3i} \end{bmatrix} \begin{bmatrix} b_{1i} \\ b_{2i} \\ B_{ni} \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ B_{ni} \end{bmatrix} \begin{bmatrix} b_{1i} \\ b_{2i} \\ B_{ni} \end{bmatrix} = 0, \forall i.$$

2.2 Algebraic Properties of Matrix Operations

Theorem 2.2 -1

Let A, B, and C be matrices and a, b, and c be scalars. Assume that the size of the matrices are such that the operations can be performed. **Properties of Matrix Addition and scalar Multiplication** 1. A + B = B + ACommutative property of addition 2. A + (B + C) = (A + B) + C Associative property of addition 3. A + O = O + A = A(where O is the appropriate zero matrix) 4. c(A + B) = cA + cBDistributive property of addition 5. (a+b)C = aC + bCDistributive property of addition 6. (ab)C = a(bC)



Theorem 2.2 -2

Let *A*, *B*, and *C* be matrices and *a*, *b*, and *c* be scalars. Assume that the size of the matrices are such that the operations can be performed. **Properties of Matrix Multiplication**

1. A(BC) = (AB)C Associative property of multiplication 2. A(B + C) = AB + AC Distributive property of multiplication 3. (A + B)C = AC + BC Distributive property of multiplication 4. $AI_n = I_nA = A$ (where I_n is the appropriate identity matrix) 5. c(AB) = (cA)B = A(cB)

Note: $AB \neq BA$ in general. Multiplication of matrices is not commutative.



Proof of Theorem 2.2 (A+B=B+A)

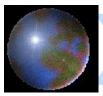
Consider the (i,j)th elements of matrices A+B and B+A:

$$(A+B)_{ij} = a_{ij} + b_{ij} = b_{ij} + a_{ij} = (B+A)_{ij}.$$

$$\therefore$$
$$A+B=B+A$$

Example 9

Let
$$A = \begin{bmatrix} 1 & 3 \\ -4 & 5 \end{bmatrix}$$
, $B = \begin{bmatrix} 3 & -7 \\ 8 & 1 \end{bmatrix}$, and $C = \begin{bmatrix} 0 & -2 \\ 5 & -1 \end{bmatrix}$.
 $A + B + C = \begin{bmatrix} 1 & 3 \\ -4 & 5 \end{bmatrix} + \begin{bmatrix} 3 & -7 \\ 8 & 1 \end{bmatrix} + \begin{bmatrix} 0 & -2 \\ 5 & -1 \end{bmatrix}$
 $= \begin{bmatrix} 1+3+0 & 3-7-2 \\ -4+8+5 & 5+1-1 \end{bmatrix} = \begin{bmatrix} 4 & -6 \\ 9 & 5 \end{bmatrix}$.

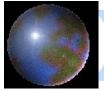


Arithmetic Operations

If *A* is an $m \times r$ matrix and *B* is $r \times n$ matrix, the number of scalar multiplications involved in computing the product *AB* is *mrn*.

Consider three matrices *A*, *B* and *C* such that the product *ABC* exists.

Compare the number of multiplications involved in the two ways (AB)C and A(BC) of computing the product ABC



Example 10

Let
$$A = \begin{bmatrix} 1 & 2 \\ 3 & -1 \end{bmatrix}$$
, $B = \begin{bmatrix} 0 & 1 & 3 \\ -1 & 0 & -2 \end{bmatrix}$, and $C = \begin{vmatrix} 4 \\ -1 \\ 0 \end{vmatrix}$. Compute ABC.

¬

Solution. (1) (AB)C $AB = \begin{bmatrix} 1 & 2 \\ 3 & -1 \end{bmatrix} \begin{bmatrix} 0 & 1 & 3 \\ -1 & 0 & -2 \end{bmatrix} = \begin{bmatrix} 1 & 3 \\ 1 & 3 & 11 \end{bmatrix}$ $(AB)C = \begin{bmatrix} -2 & 1 & -1 \\ 1 & 3 & 11 \end{bmatrix} \begin{bmatrix} 4 \\ -1 \\ 0 \end{bmatrix} = \begin{bmatrix} -9 \\ 1 \end{bmatrix}$. (2) A(BC)Which method is better? Count the number of $2 \times 6 + 3 \times 2$ = 12 + 6 = 18

 $BC = \begin{bmatrix} 0 & 1 & 3 \\ -1 & 0 & 2 \end{bmatrix} \begin{bmatrix} 4 \\ -1 \\ 0 \end{bmatrix} = \begin{bmatrix} -1 \\ -4 \end{bmatrix}$ $A(BC) = \begin{bmatrix} 1 & 2 \\ 3 & -1 \end{bmatrix} \begin{bmatrix} -1 \\ -4 \end{bmatrix} = \begin{bmatrix} -9 \\ 1 \end{bmatrix}.$

 $3 \times 2 + 2 \times 2$ =6+4=10 $\therefore A(BC)$ is

better.

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Caution

In algebra we know that the following cancellation laws apply.

- If ab = ac and $a \neq 0$ then b = c.
- If pq = 0 then p = 0 or q = 0.

However the corresponding results are not true for matrices.

- AB = AC does not imply that B = C.
- PQ = O does not imply that P = O or Q = O.

Example 11

(1) Consider the matrices
$$A = \begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix}$$
, $B = \begin{bmatrix} -1 & 2 \\ 2 & 1 \end{bmatrix}$, and $C = \begin{bmatrix} -3 & 8 \\ 3 & -2 \end{bmatrix}$.
Observe that $AB = AC = \begin{bmatrix} 3 & 4 \\ 6 & 8 \end{bmatrix}$, but $B \neq C$.
(2) Consider the matrices $P = \begin{bmatrix} 1 & -2 \\ -2 & 4 \end{bmatrix}$, and $Q = \begin{bmatrix} 2 & -6 \\ 1 & -3 \end{bmatrix}$.
Observe that $PQ = O$, but $P \neq O$ and $Q \neq O$.



Definition

If A is a square matrix, then

$$A^{k} = \underset{k \text{ times}}{\bigwedge} A$$

Theorem 2.3

If A is an $n \times n$ square matrix and r and s are nonnegative integers, then

- $1. A^r A^s = A^{r+s}.$
- 2. $(A^r)^s = A^{rs}$.
- 3. $A^0 = I_n$ (by definition)



Solution $A^{2} = \begin{bmatrix} 3 & -2 \\ -1 & 0 \end{bmatrix}, \text{ compute } A^{4}.$ $A^{2} = \begin{bmatrix} 1 & -2 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} 1 & -2 \\ -1 & 0 \end{bmatrix} = \begin{bmatrix} 3 & -2 \\ -1 & 2 \end{bmatrix}$ $A^{4} = \begin{bmatrix} 3 & -2 \\ -1 & 2 \end{bmatrix} \begin{bmatrix} 3 & -2 \\ -1 & 2 \end{bmatrix} = \begin{bmatrix} 11 & -10 \\ -5 & 6 \end{bmatrix}.$

Example 13 Simplify the following matrix expression. $A(A+2B)+3B(2A-B)-A^2+7B^2-5AB$ **Solution** $A(A+2B)+3B(2A-B)-A^2+7B^2-5AB$ $= A^2+2AB+6BA-3B^2-A^2+7B^2-5AB$ $= -3AB+6BA+4B^2$

We can't add the two matrices



A system of m linear equations in n variables as follows

$$a_{11}x_1 + \boxtimes + a_{1n}x_n = b_1$$
$$\boxtimes \boxtimes \boxtimes \boxtimes$$
$$a_{m1}x_1 + \boxtimes + a_{mn}x_n = b_m$$

Let

$$A = \begin{bmatrix} a_{11} & \boxtimes & a_{1n} \\ \boxtimes & \boxtimes & \boxtimes \\ a_{m1} & \boxtimes & a_{mn} \end{bmatrix}, X = \begin{bmatrix} x_1 \\ \boxtimes \\ x_n \end{bmatrix}, \text{ and } B = \begin{bmatrix} b_1 \\ \boxtimes \\ b_m \end{bmatrix}$$

We can write the system of equations in the matrix form

AX = B

Idempotent and Nilpotent Matrices

Definition

- (1) A square matrix A is said to be **idempotent** if $A^2 = A$.
- (2) A square matrix A is said to **nilpotent** if there is a positive integer p such that $A^p=0$. The least integer p such that $A^p=0$ is called the **degree of nilpotency** of the matrix.

Example 14

(1)
$$A = \begin{bmatrix} 3 & -6 \\ 1 & -2 \end{bmatrix}, A^2 = \begin{bmatrix} 3 & -6 \\ 1 & -2 \end{bmatrix} = A.$$

(2)
$$B = \begin{bmatrix} 3 & -9 \\ 1 & -3 \end{bmatrix}, B^2 = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$
. The degree of nilpotency : 2



• Exercises will be given by the teachers of the practical classes.

2.3 Symmetric Matrices

Definition

The **transpose** of a matrix A, denoted A^t , is the matrix whose columns are the rows of the given matrix A.

i.e.,
$$A: m \times n \implies A^t: n \times m, (A^t)_{ij} = A_{ji} \quad \forall i, j.$$

Example 15

$$A = \begin{bmatrix} 2 & 7 \\ -8 & 0 \end{bmatrix}, B = \begin{bmatrix} 1 & 2 & -7 \\ 4 & 5 & 6 \end{bmatrix}, \text{ and } C = \begin{bmatrix} -1 & 3 & 4 \end{bmatrix}.$$
$$A^{t} = \begin{bmatrix} 2 & -8 \\ 7 & 0 \end{bmatrix} \qquad B^{t} = \begin{bmatrix} 1 & 4 \\ 2 & 5 \\ -7 & 6 \end{bmatrix} \qquad C^{t} = \begin{bmatrix} -1 \\ 3 \\ 4 \end{bmatrix}.$$

Theorem 2.4: Properties of Transpose

Let *A* and *B* be matrices and *c* be a scalar. Assume that the sizes of the matrices are such that the operations can be performed. 1. $(A + B)^t = A^t + B^t$ Transpose of a sum 2. $(cA)^t = cA^t$ Transpose of a scalar multiple 3. $(AB)^t = B^tA^t$ Transpose of a product 4. $(A^t)^t = A$



Definition

A symmetric matrix is a matrix that is equal to its transpose.

$$A = A^{t}, \text{ i.e., } a_{ij} = a_{ji} \forall i, j$$
Example 16

$$\begin{bmatrix} 2 & 5\\ 5 & -4 \end{bmatrix} \begin{bmatrix} 0 & 1 & -4\\ 1 & 7 & 8\\ -4 & 8 & -3 \end{bmatrix} \begin{bmatrix} 1 & 0 & -2 & 4\\ 0 & 7 & 3 & 9\\ -2 & 3 & 2 & -3\\ 4 & 9 & -3 & 6 \end{bmatrix} \text{ match}$$

Remark: If and only if

• Let *p* and *q* be statements. Suppose that *p* implies *q* (if *p* then *q*), written $p \Rightarrow q$, and that also $q \Rightarrow p$, we say that

"p if and only if q" (in short iff)

Example 17

Let *A* and *B* be symmetric matrices of the same size. Prove that the product *AB* is symmetric if and only if AB = BA.

Proof

*We have to show (a) AB is symmetric $\Rightarrow AB = BA$, and the converse, (b) AB is symmetric $\Leftarrow AB = BA$.

 (\Rightarrow) Let *AB* be symmetric, then

 $AB = (AB)^t$ by definition of symmetric matrix $= B^t A^t$ by Thm 2.4 (3)= BAsince A and B are symmetric

(\Leftarrow) Let AB = BA, then $(AB)^t = (BA)^t$ $= A^t B^t$ by Thm 2.4 (3) = AB since A and B are symmetric



Let A be a symmetric matrix. Prove that A^2 is symmetric.

Proof

$$(A^{2})^{t} = (AA)^{t} = (A^{t}A^{t}) = AA = A^{2}$$



• Exercises will be given by the teachers of

the practical classes.

2.4 The Inverse of a Matrix

Definition

Let *A* be an $n \times n$ matrix. If a matrix *B* can be found such that $AB = BA = I_n$, then *A* is said to be **invertible** and *B* is called the **inverse** of *A*. If such a matrix *B* does not exist, then *A* has no inverse. (denote $B = A^{-1}$, and $A^{-k} = (A^{-1})^k$)

Example 19 Prove that the matrix $A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$ has inverse $B = \begin{bmatrix} -2 & 1 \\ \frac{3}{2} & -\frac{1}{2} \end{bmatrix}$. **Proof** $AB = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \begin{bmatrix} -2 & 1 \\ \frac{3}{2} & -\frac{1}{2} \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = I_2$ $BA = \begin{bmatrix} -2 & 1 \\ \frac{3}{2} & -\frac{1}{2} \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = I_2$ Thus $AB = BA = I_2$, proving that the matrix A has inverse B.

Theorem 2.5

The inverse of an invertible matrix is unique.

Proof

Let *B* and *C* be inverses of *A*. Thus $AB = BA = I_n$, and $AC = CA = I_n$. Multiply both sides of the equation $AB = I_n$ by *C*. $C(AB) = CI_n$ (CA)B = C \leftarrow Thm2.2 $I_nB = C$ B = C

Thus an invertible matrix has only one inverse.

Gauss-Jordan Elimination for finding the Inverse of a Matrix

Let A be an $n \times n$ matrix.

- 1. Adjoin the identity $n \times n$ matrix I_n to A to form the matrix $[A : I_n]$.
- 2. Compute the reduced echelon form of [A : I_n].
 If the reduced echelon form is of the type [I_n : B], then B is the inverse of A.

If the reduced echelon form is not of the type $[I_n : B]$, in that the first $n \times n$ submatrix is not I_n , then A has no inverse.

An $n \times n$ matrix A is invertible if and only if its reduced echelon form is I_n .

Example 20

Determine the inverse of the matrix $A = \begin{bmatrix} 1 & -1 & -2 \\ 2 & -3 & -5 \\ -1 & 3 & 5 \end{bmatrix}$ Solution

$$[A:I_{3}] = \begin{bmatrix} 1 & -1 & -2 & 1 & 0 & 0 \\ 2 & -3 & -5 & 0 & 1 & 0 \\ -1 & 3 & 5 & 0 & 0 & 1 \end{bmatrix} \stackrel{\approx}{\operatorname{R2}+(-2)\operatorname{R1}} \begin{bmatrix} 1 & -1 & -2 & 1 & 0 & 0 \\ 0 & -1 & -1 & -2 & 1 & 0 \\ 0 & 2 & 3 & 1 & 0 & 1 \end{bmatrix} \stackrel{\approx}{\operatorname{R3}+\operatorname{R1}} \begin{bmatrix} 1 & 0 & -1 & 3 & -1 & 0 \\ 0 & 1 & 1 & 2 & -1 & 0 \\ 0 & 1 & 1 & 2 & -1 & 0 \\ 0 & 1 & 1 & 2 & -1 & 0 \\ 0 & 2 & 3 & 1 & 0 & 1 \end{bmatrix} \stackrel{\approx}{\operatorname{R1}+\operatorname{R2}} \stackrel{\left[\begin{array}{c} 1 & 0 & -1 & 3 & -1 & 0 \\ 0 & 1 & 1 & 2 & -1 & 0 \\ 0 & 0 & 1 & -3 & 2 & 1 \end{bmatrix}} \stackrel{\approx}{\operatorname{R3}+(-2)\operatorname{R2}} \begin{bmatrix} 1 & 0 & -1 & 3 & -1 & 0 \\ 0 & 1 & 1 & 2 & -1 & 0 \\ 0 & 0 & 1 & -3 & 2 & 1 \end{bmatrix} \stackrel{\approx}{\operatorname{R1}+\operatorname{R3}} \stackrel{\left[\begin{array}{c} 1 & 0 & 0 & 0 & 1 & 1 \\ 0 & 1 & 0 & 5 & -3 & -1 \\ 0 & 0 & 1 & -3 & 2 & 1 \end{bmatrix}} \stackrel{\operatorname{R1}+\operatorname{R3}}{\operatorname{R2}+(-1)\operatorname{R3}} \stackrel{\left[\begin{array}{c} 0 & 1 & 1 \\ 5 & -3 & -1 \\ -3 & 2 & 1 \end{bmatrix}} \stackrel{\left[\begin{array}{c} 0 & 1 & 1 \\ 5 & -3 & -1 \\ -3 & 2 & 1 \end{bmatrix}}.$$



Determine the inverse of the following matrix, if it exist.

$$A = \begin{bmatrix} 1 & 1 & 5 \\ 1 & 2 & 7 \\ 2 & -1 & 4 \end{bmatrix}$$

Solution

$$[A:I_{3}] = \begin{bmatrix} 1 & 1 & 5 & 1 & 0 & 0 \\ 1 & 2 & 7 & 0 & 1 & 0 \\ 2 & -1 & 4 & 0 & 0 & 1 \end{bmatrix} \overset{\approx}{\operatorname{R2}} \begin{bmatrix} 1 & 1 & 5 & 1 & 0 & 0 \\ 0 & 1 & 2 & -1 & 1 & 0 \\ 0 & -3 & -6 & -2 & 0 & 1 \end{bmatrix} \overset{\approx}{\operatorname{R3}} \underset{\operatorname{R3}}{\approx} \begin{bmatrix} 1 & 0 & 3 & 2 & -1 & 0 \\ 0 & 1 & 2 & -1 & 0 \\ 0 & 1 & 2 & -1 & 1 & 0 \\ 0 & 1 & 2 & -1 & 1 & 0 \\ 0 & 0 & 0 & -5 & 3 & 1 \end{bmatrix}$$

There is no need to proceed further.

The reduced echelon form cannot have a one in the (3, 3) location. The reduced echelon form cannot be of the form $[I_n : B]$. Thus A^{-1} does not exist.

Properties of Matrix Inverse

Let A and B be invertible matrices and c a nonzero scalar, Then

1.
$$(A^{-1})^{-1} = A$$

2. $(cA)^{-1} = \frac{1}{c}A^{-1}$
3. $(AB)^{-1} = B^{-1}A^{-1}$
4. $(A^{n})^{-1} = (A^{-1})^{n}$
5. $(A^{t})^{-1} = (A^{-1})^{t}$

Proof

1. By definition,

$$AA^{-1} = A^{-1} (AA^{-1} = A^{-1}) (AA^{-1}) = I = (\frac{1}{c} A^{-1})(cA)$$

3. $(AB)(B^{-1}A^{-1}) = A(BB^{-1})A^{-1} = AA^{-1} = I = (B^{-1}A^{-1})(AB)$
4. $A^{n}(A^{-1})^{n} = AA^{-1} AA^{-1} = I = (A^{-1})^{n} A^{n}$
 $A^{n} (A^{-1})^{n} = AA^{-1} AA^{-1} = I = (A^{-1})^{n} A^{n}$
 $A^{-1}A = I, (AA^{-1})^{t} = (A^{-1})^{t} A^{t} = I,$
 $A^{-1}A = I, (A^{-1}A)^{t} = A^{t}(A^{-1})^{t} = I,$

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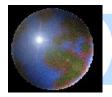


Example 22

If $A = \begin{bmatrix} 4 & 1 \\ 3 & 1 \end{bmatrix}$, then it can be shown that $A^{-1} = \begin{bmatrix} 1 & -1 \\ -3 & 4 \end{bmatrix}$. Use this information to compute $(A^t)^{-1}$.

Solution

$$(A^{t})^{-1} = (A^{-1})^{t} = \begin{bmatrix} 1 & -1 \\ -3 & 4 \end{bmatrix}^{t} = \begin{bmatrix} 1 & -3 \\ -1 & 4 \end{bmatrix}.$$



Theorem 2.6

Let AX = B be a system of *n* linear equations in *n* variables. If A^{-1} exists, the solution is unique and is given by $X = A^{-1}B$.

Proof

 $(X = A^{-1}B \text{ is a solution.})$ Substitute $X = A^{-1}B$ into the matrix equation. $AX = A(A^{-1}B) = (AA^{-1})B = I_n B = B.$

(The solution is unique.) Let *Y* be any solution, thus AY = B. Multiplying both sides of this equation by A^{-1} gives

$$A^{-1}A Y = A^{-1}B$$
$$I_n Y = A^{-1}B$$
$$Y = A^{-1}B. Then Y = X$$

Example 22

Solve the system of equations
$$x_1 - x_2 - 2x_3 = 1$$

 $x_1 - 3x_2 - 5x_3 = 3$
 $-x_1 + 3x_2 + 5x_3 = -2$

Solution

This system can be written in the following matrix form:

$$\begin{bmatrix} 1 & -1 & -2 \\ 2 & -3 & -5 \\ -1 & 3 & 5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 1 \\ 3 \\ -2 \end{bmatrix}$$

If the matrix of coefficients is invertible, the unique solution is

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 1 & -1 & -2 \\ 2 & -3 & -5 \\ -1 & 3 & 5 \end{bmatrix}^{-1} \begin{bmatrix} 1 \\ 3 \\ -2 \end{bmatrix}$$

This inverse has already been found in Example 20. We get

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & 1 \\ 5 & -3 & -1 \\ -3 & 2 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 3 \\ -2 \end{bmatrix} = \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}$$

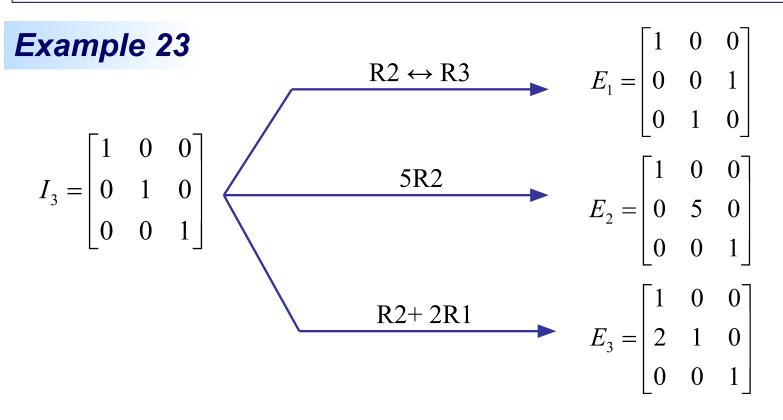
The unique solution is $x_1 = 1, x_2 = -2, x_3 = 1$.

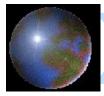
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Definition

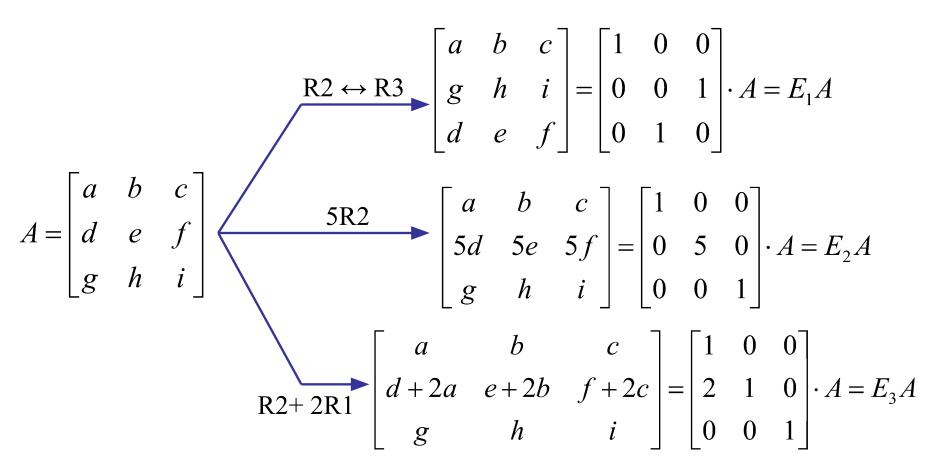
An **elementary matrix** is one that can be obtained from the identity matrix I_n through a single elementary row operation.





Elementary Matrices

- $_{\circ}$ Elementary row operation
- Elementary matrix



Notes for elementary matrices

• Each elementary matrix is invertible.

Example 24

$$I \approx_{R1+2R2} E_1 \Rightarrow E_1 \approx_{R1-2R2} I$$
, i.e., $E_2 E_1 = I$
 $I = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$
 $E_1 = \begin{bmatrix} 1 & 2 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$
 $E_2 = \begin{bmatrix} 1 & -2 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

• If *A* and *B* are row equivalent matrices and *A* is invertible, then *B* is invertible.

Proof

If $A \approx ... \approx B$, then $B = E_n \dots E_2 E_1 A$ for some elementary matrices E_n, \dots, E_2 and E_1 . So $B^{-1} = (E_n \dots E_2 E_1 A)^{-1} = A^{-1} E_1^{-1} E_2^{-1} \dots E_n^{-1}$.

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• Exercises will be given by the teachers of the practical classes.

Exercise If $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$, show that $A^{-1} = \frac{1}{(ad - bc)} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$.