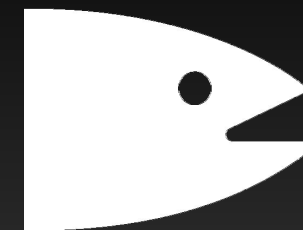


# selfFish



SELFCONTROLLED WATER POLLUTION ANALYZING SYSTEM

Абрамов Владислав

Мурашов Леонид

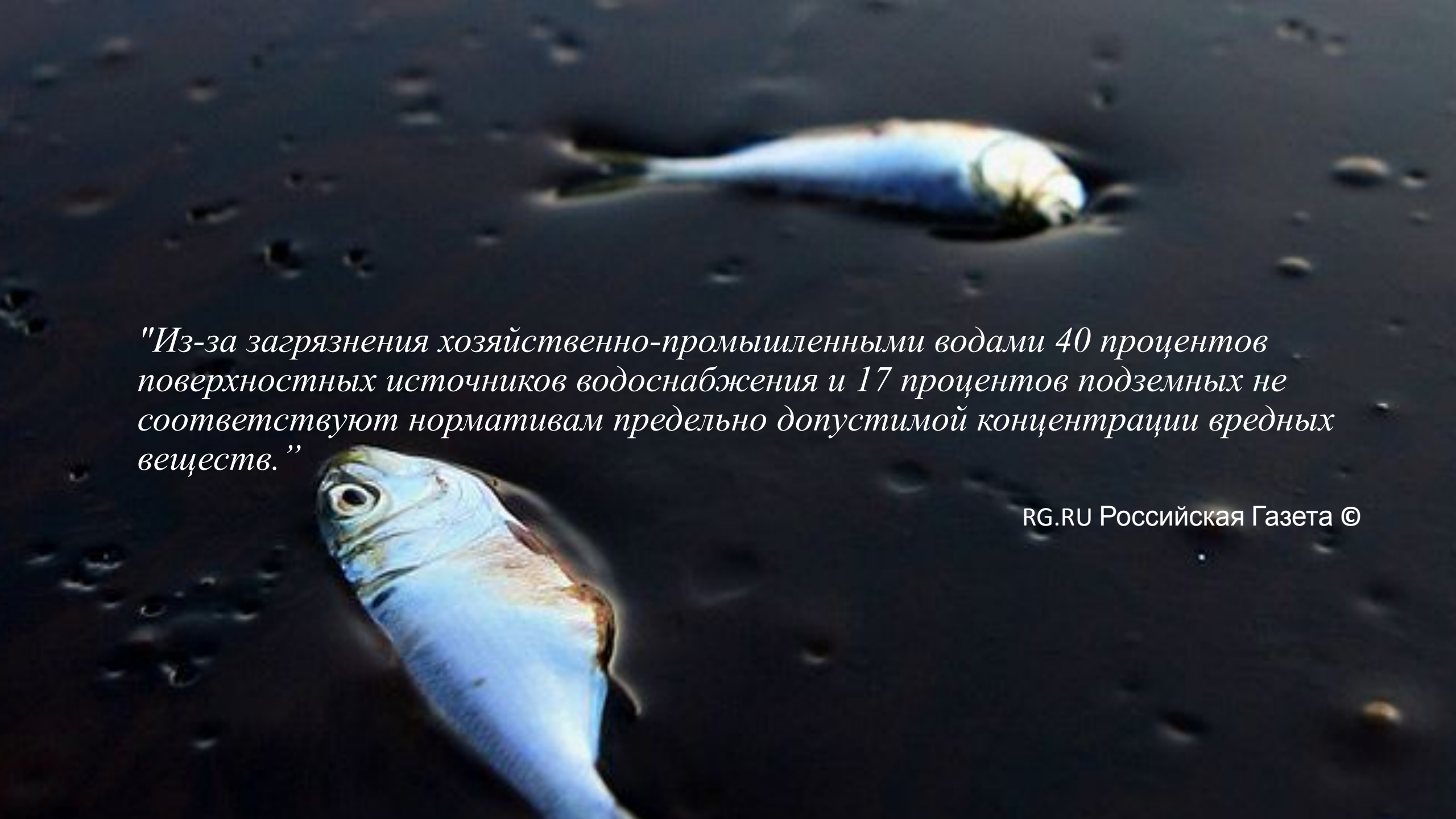
Горохов Михаил

Дмитрий Лифановский

Дарья Перегудова



**МЫ ТО,  
ЧТО МЫ ПЬЕМ**

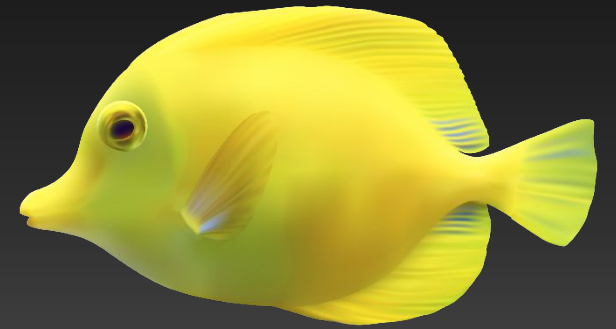
The image shows two dead fish lying on a dark, wet, and reflective surface, possibly asphalt or a wet pavement. The fish are positioned horizontally, one in the upper right and one in the lower left. The water droplets on the surface create a shimmering effect, highlighting the texture of the ground and the metallic sheen of the fish's scales. The overall mood is somber and environmental.

*"Из-за загрязнения хозяйственно-промышленными водами 40 процентов поверхностных источников водоснабжения и 17 процентов подземных не соответствуют нормативам предельно допустимой концентрации вредных веществ."*

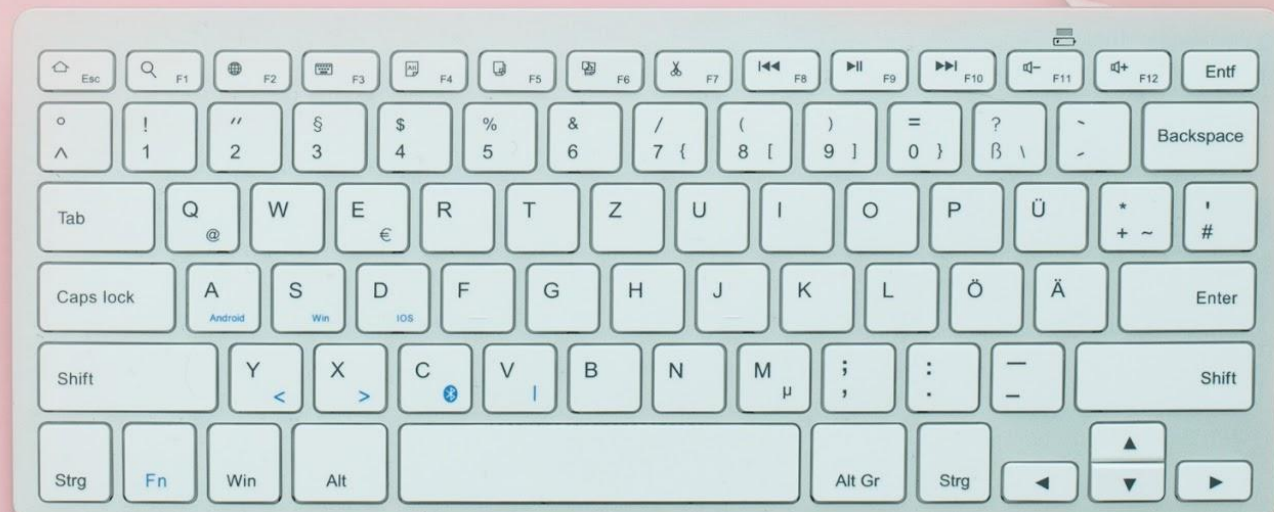
RG.RU Российская Газета ©



**ИДЕЯ?**



# ЧТО ЖЕ НА ДЕЛЕ

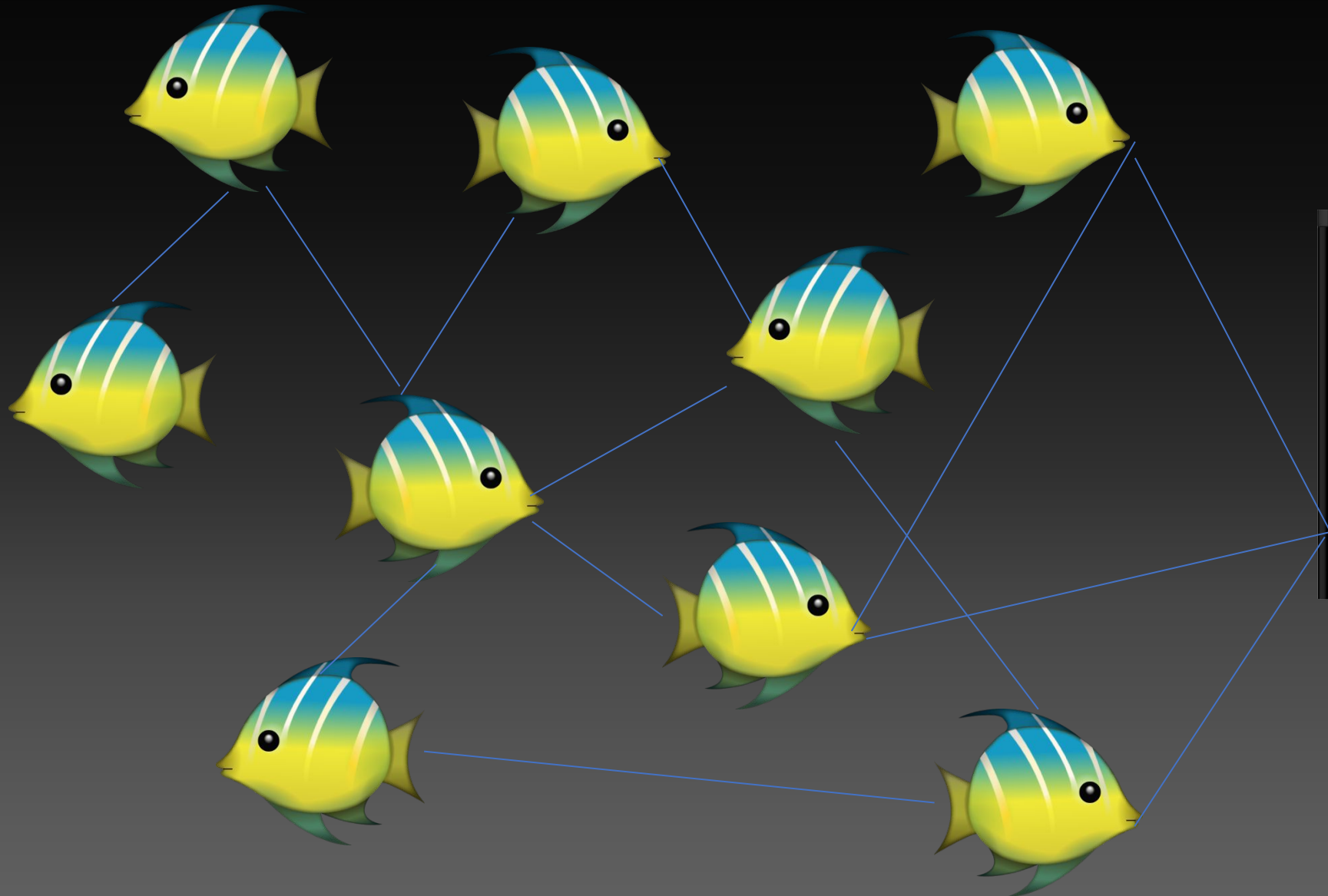


**1000 РЫБ**

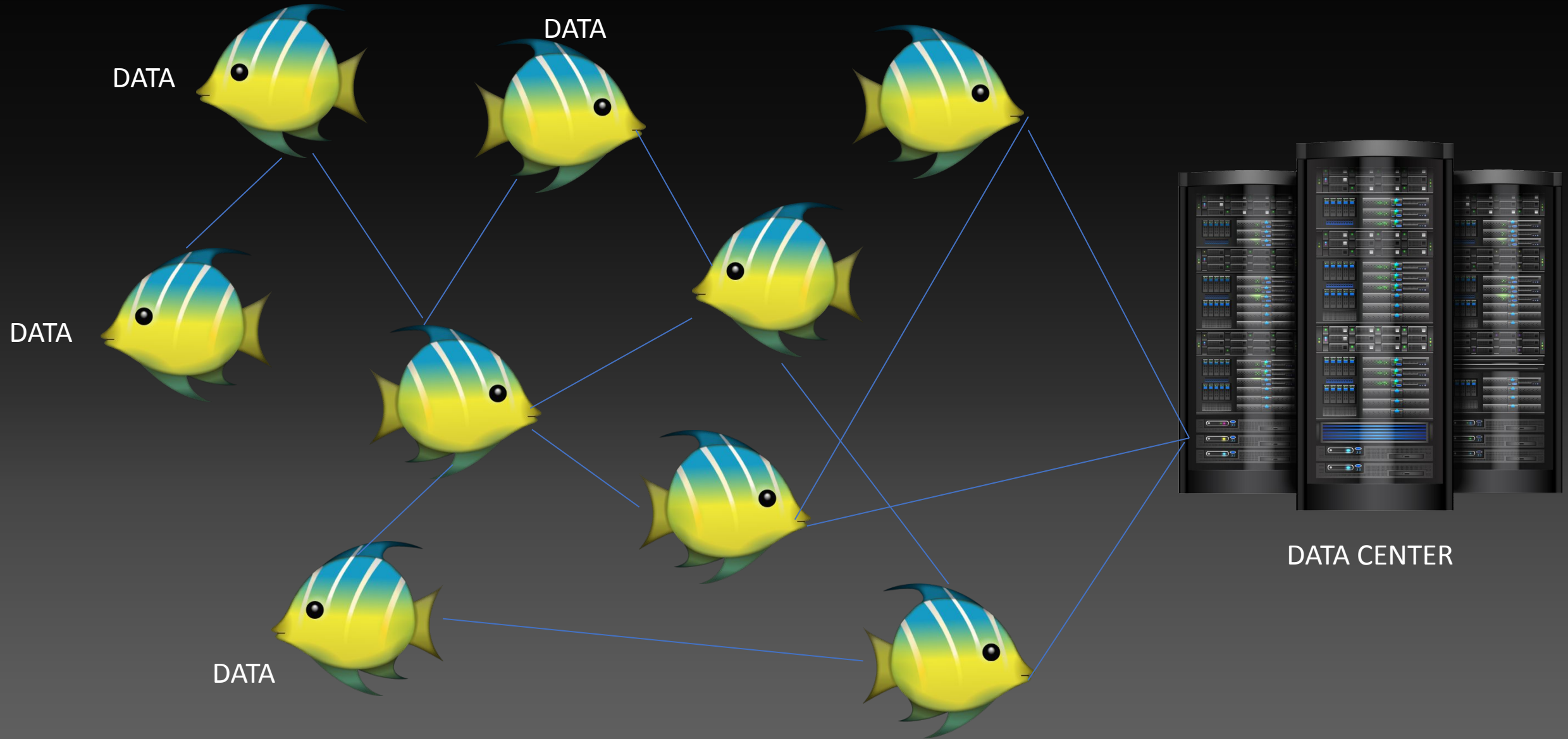
**1 ОЗЕРО**



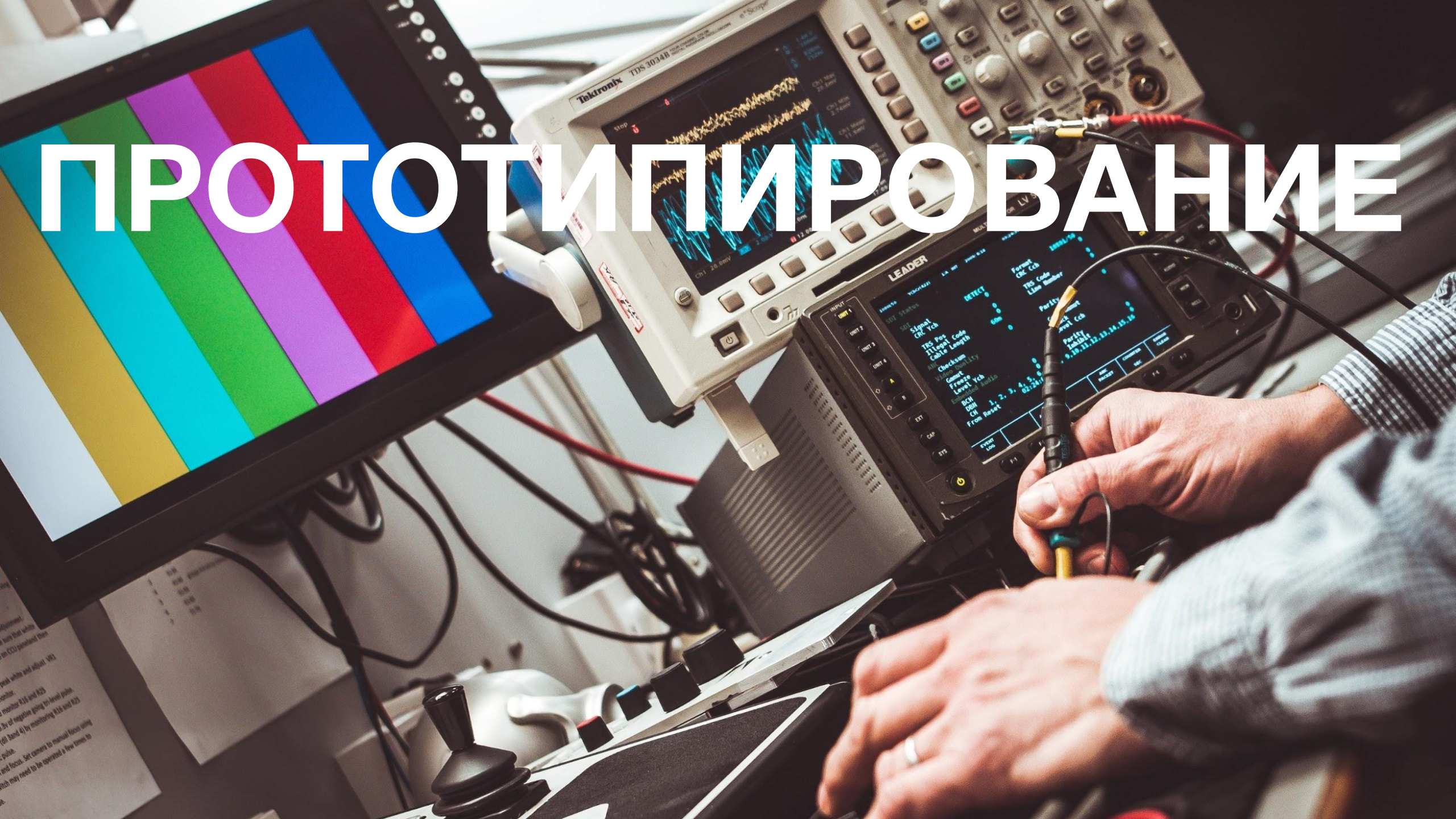


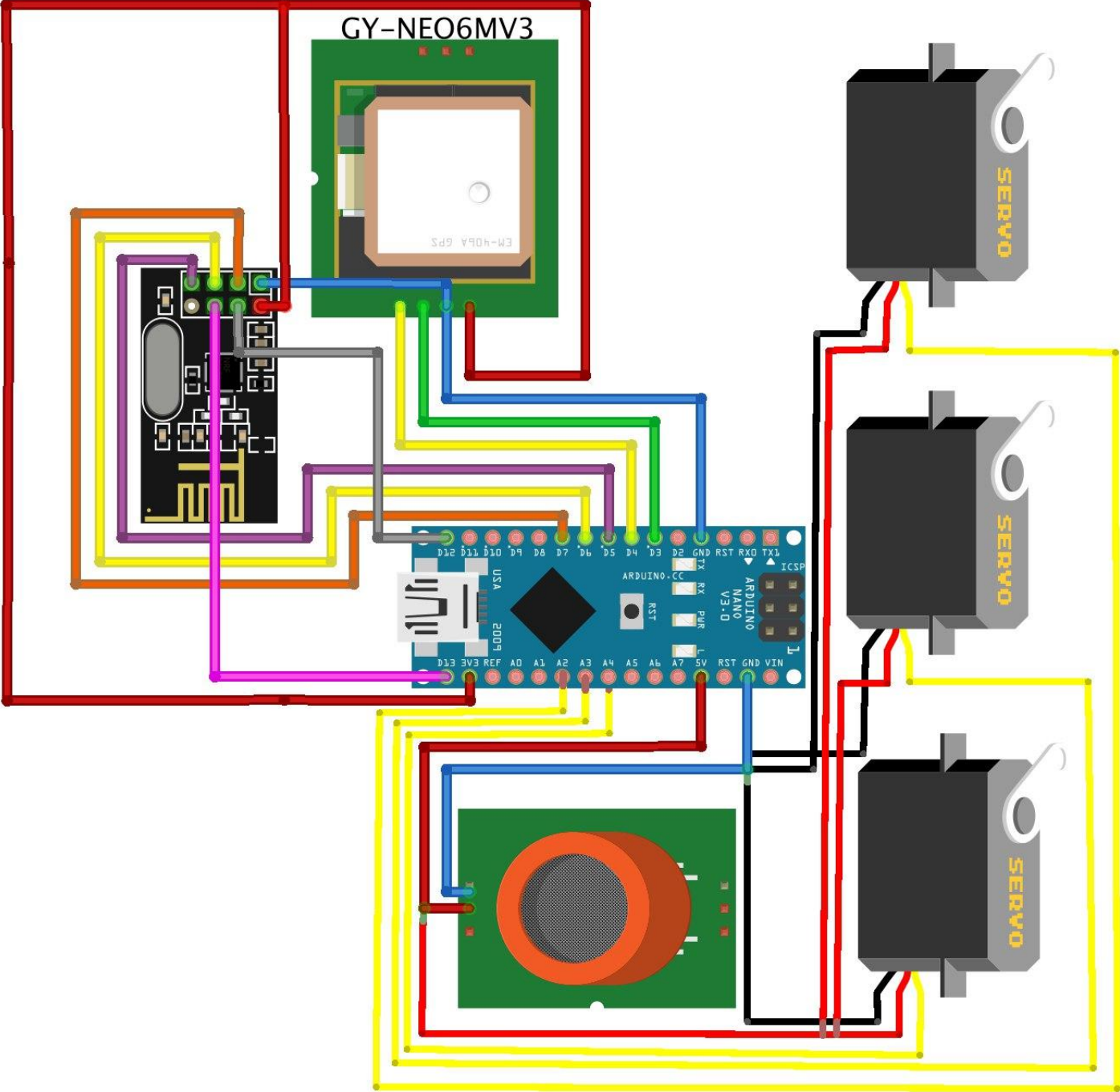


DATA CENTER



# ПРОТОТИПИРОВАНИЕ

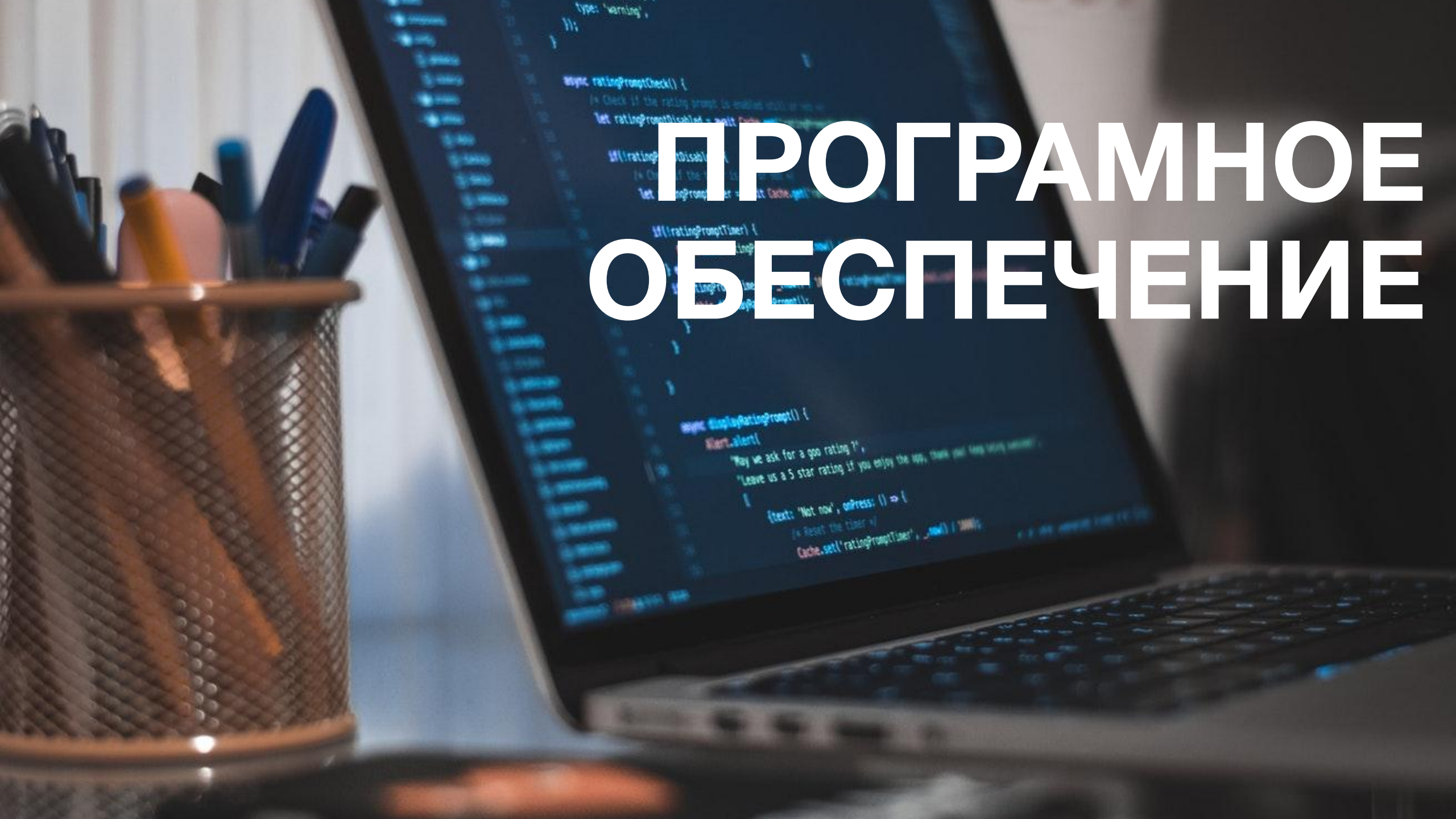




# ПЕРВЫЙ ПРОТОТИП



# ПРОГРАММНОЕ ОБЕСПЕЧЕНИЕ



```
FullExample | Arduino 1.8.5
FullExample §

void loop()
{
  static const double LONDON_LAT = 51.508131, LONDON_LON = -0.128002;

  printInt(gps.satellites.value(), gps.satellites.isValid(), 5);
  printFloat(gps.hdop.hdop(), gps.hdop.isValid(), 6, 1);
  printFloat(gps.location.lat(), gps.location.isValid(), 11, 6);
  printFloat(gps.location.lng(), gps.location.isValid(), 12, 6);
  printInt(gps.location.age(), gps.location.isValid(), 5);
  printDateTime(gps.date, gps.time);
  printFloat(gps.altitude.meters(), gps.altitude.isValid(), 7, 2);
  printFloat(gps.course.deg(), gps.course.isValid(), 7, 2);
  printFloat(gps.speed.kmph(), gps.speed.isValid(), 6, 2);
  printStr(gps.course.isValid() ? TinyGPSPlus::cardinal(gps.course.deg())

  unsigned long distanceKmToLondon =
    (unsigned long)TinyGPSPlus::distanceBetween(
      gps.location.lat(),
      gps.location.lng(),
      LONDON_LAT,
      LONDON_LON) / 1000;
  printInt(distanceKmToLondon, gps.location.isValid(), 9);

  double courseToLondon =
    TinyGPSPlus::courseTo(
      gps.location.lat(),
      gps.location.lng(),
      LONDON_LAT,
      LONDON_LON);

  printFloat(courseToLondon, gps.location.isValid(), 7, 2);
```



Arduino IDE





The image shows the interior of a space station, likely the International Space Station, looking out through a large circular window. The view outside shows the Earth's blue oceans and white clouds. In the upper left window, another satellite or module is visible in orbit. The interior of the station is dark, with various equipment and panels visible around the window frames.

# СФЕРА ПРИМЕНЕНИЯ

A man in a dark blue suit and red patterned tie is seated at a desk. He is gesturing with his right hand, palm up, while his left hand rests on the desk. In front of him is a laptop, a glass of water, and several documents with charts and graphs. The word "ЭКОНОМИКА" is overlaid in large white letters across the center of the image.

**ЭКОНОМИКА**

**ВСЕМ СПАСИБО**