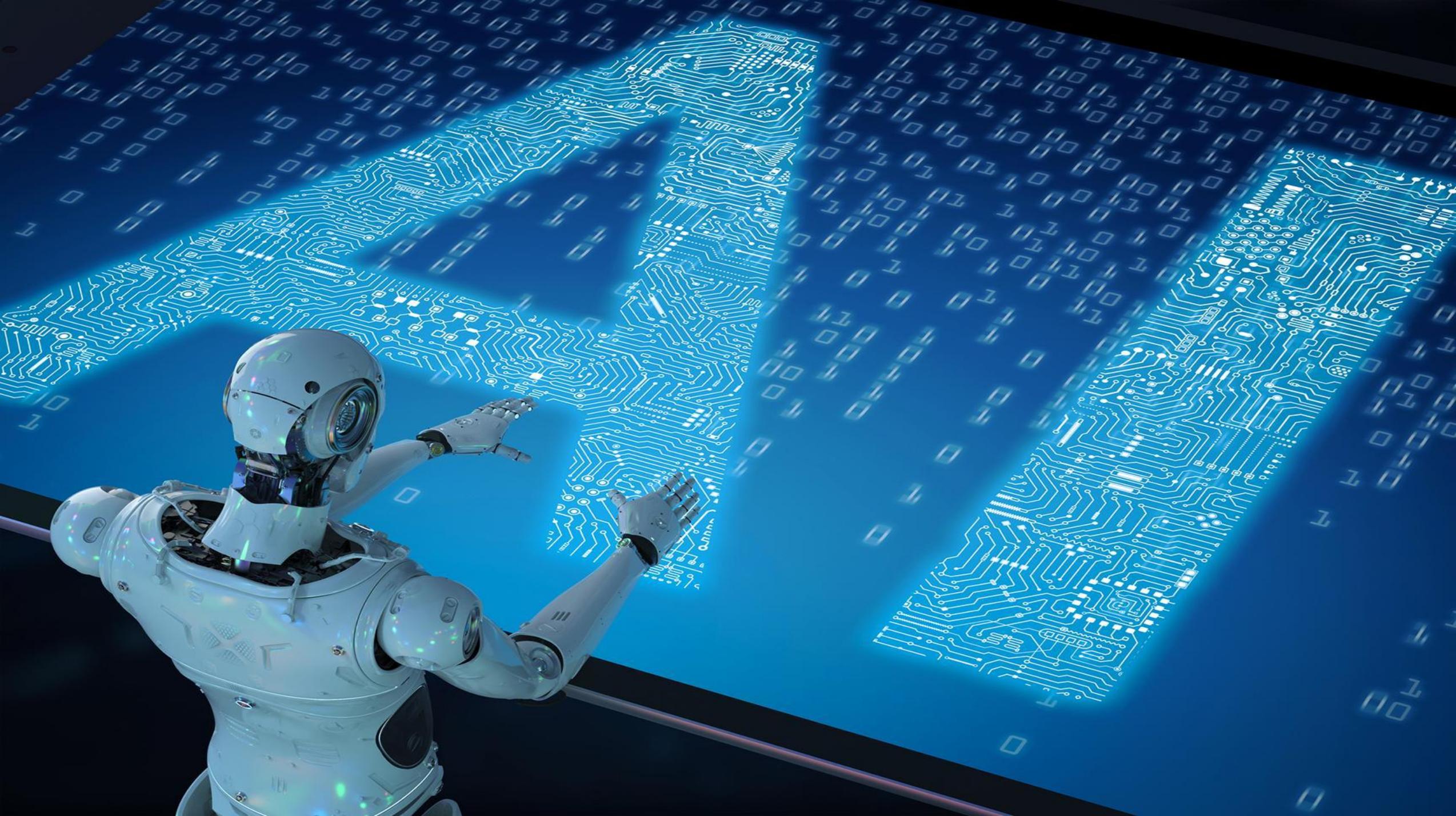




AI





Ego Speed: 45.40 MPH  
time: 1545.469101000  
CAL P 0.60 Y 1.20 R 0.00 deg

Vision fps: 18.05 Draw fps: 17.67 Display fps: 21.34  
NL(0.00), E(0.93), F(0.08), TF(0.00), S(0.00)  
NRW: FLP(0.00), FRP(0.00)  
CutInExcited (Prb 0.55)

+0.0001 AUTO\_HIGH\_BEAM  
+0.0000 BLINDED  
+0.0001 RAINING  
+0.0000 TIRE\_SPRAY  
+0.0013 WET\_ROAD  
**0.7902 RESTRICTED**  
0.1539 CONTROLLED\_ACCESS

L:0 R:0 F:2 ON:0  
W:8.4 AP:0.4 I:0  
VS: 46.7 MPH St: 1  
merge: 1.0 1 161.7 R



MAIN -

AP

40m



$$\int a^2 - x^2 dx = \frac{\pi a^2}{4}$$

$$[f(x) \pm g(x)] = l \pm m$$

$$[f(x) \cdot g(x)] = l \cdot m$$

$$\frac{1}{f(x)} = \frac{1}{l}$$

$$\frac{1+3+3+6+8+9}{6} = 5$$

$$\frac{2+4+4^6+8+12}{6} = 30$$

$$a^2 = c^2$$

$$\sin B = \frac{4\sqrt{3}}{x}$$



$$\sin 60^\circ = \frac{x}{4\sqrt{3}}$$

$$n(C) = 84$$

$$n(BUC) = n(B) + n(C)$$

$$f(x) \leq 5$$

$$x^2 - 4x + 5 \leq 5$$

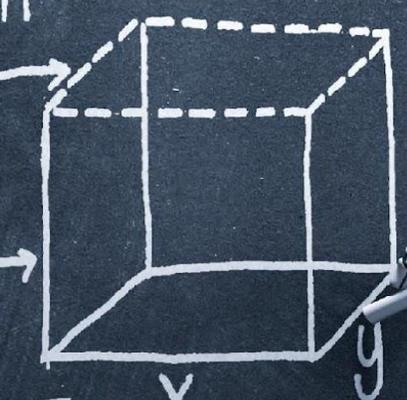
$$x^2 - 4x \leq 0$$

$$126 = 6xy$$

$$2x + 2y = 20$$

$$\cos(B) = \frac{y}{x}$$

$$\cos(60^\circ) = \frac{y}{x}$$



$$\sqrt[n]{a^m} = a^{\frac{m}{n}}$$

$$\sqrt[3]{a^3 \sqrt{a}} = \sqrt[3]{a \cdot a^{\frac{1}{3}}}$$

$$= \sqrt[3]{a^{\frac{3}{3}} \cdot a^{\frac{1}{3}}}$$

$$= \sqrt[3]{5 + \sqrt{4 \cdot 6}}$$

$$a_n = \frac{1}{2^{n-1}}$$

$$= \frac{1}{2^9} = \frac{1}{512}$$

$$A = \pi r^2 h$$

$$(100^2)a + 100b$$

$$10000a + 100b$$



$$f = \{(x, y) \in \mathbb{R}^+ \times \mathbb{R} \mid x = a, y = \dots\}$$

$$z_1 = a \begin{vmatrix} D_1 & B_1 \\ D_2 & B_2 \end{vmatrix} - b \begin{vmatrix} D_1 & A_1 \\ D_2 & A_2 \end{vmatrix}$$

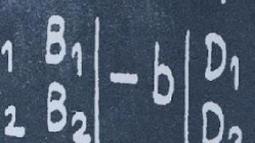
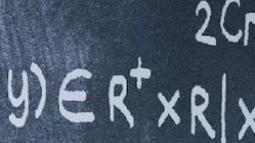
$$a^2 + b^2 + c^2$$

$$\frac{g_1}{g_2} = \left(\frac{R_2}{R_1}\right)^2 = \left(\frac{R_1 + h}{R_1}\right)^2$$

$$E = mc^2$$



$$\frac{25}{25}$$



$$E = mc^2$$

$$\frac{g_1}{g_2} = \left(\frac{R_2}{R_1}\right)^2 = \left(\frac{R_1 + h}{R_1}\right)^2$$

$$E = mc^2$$

$$A = \pi r^2 h$$

$$(100^2)a + 100b$$

$$10000a + 100b$$

$$10000a + 100b$$

