

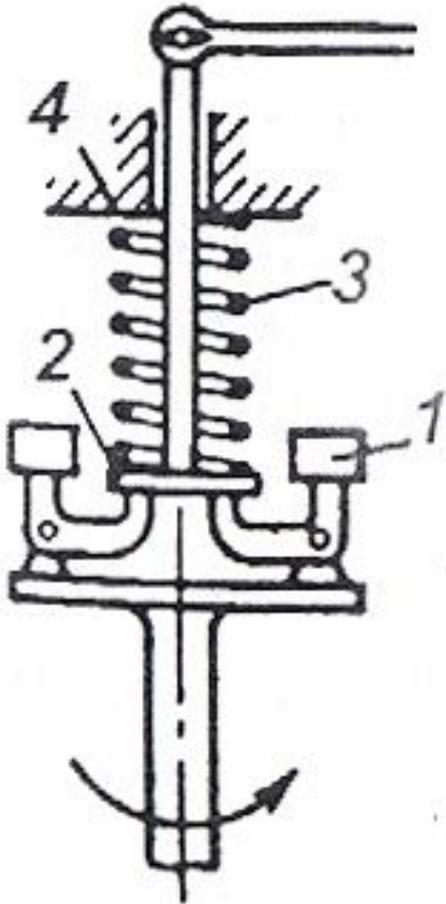
# Элементная база регуляторов

(на примере ГТД)

# Центробежный маятниковый ЧЭ

входная координата  $n$  – обороты ротора,

выходная  $z$  – перемещение муфты



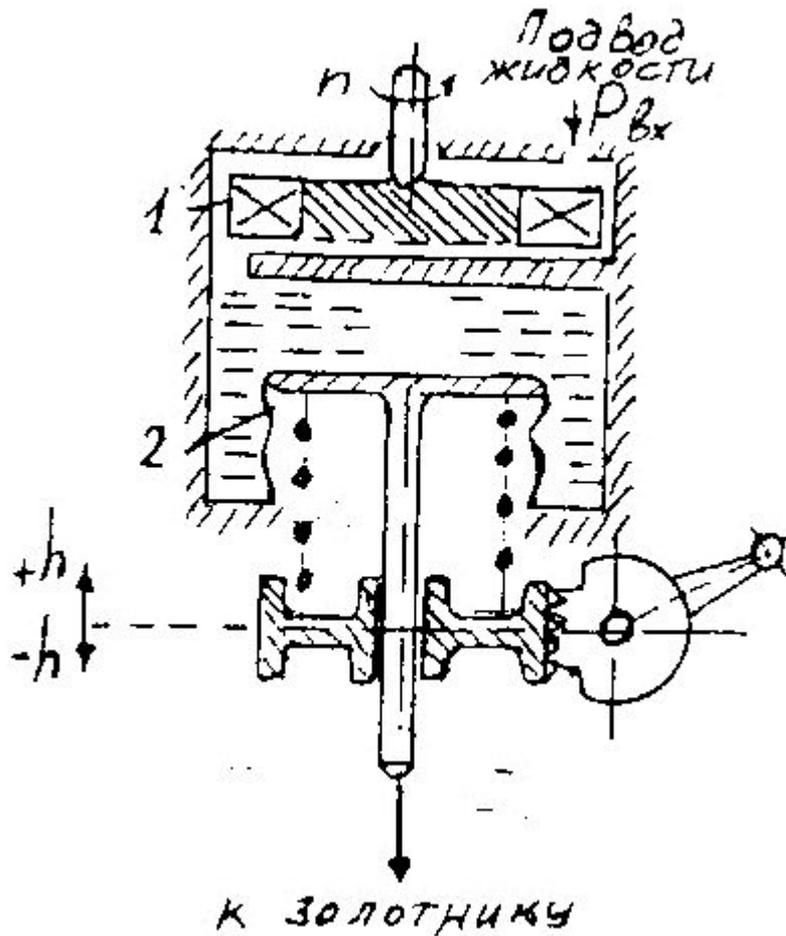
$$W(s) = \frac{k}{T^2 s^2 + Ts + 1}$$

$$k = \frac{2cn^2}{Bz}$$

$$T = \frac{\beta}{B}$$

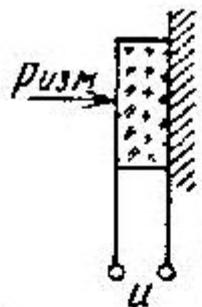
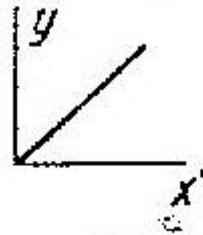
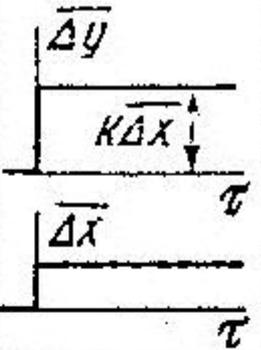
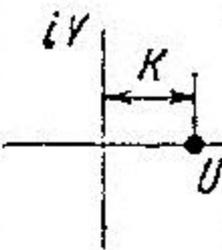
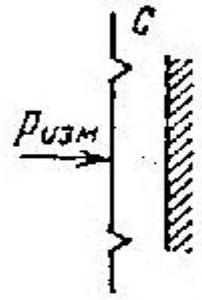
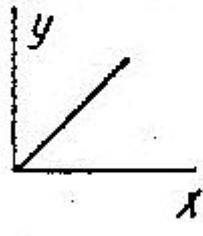
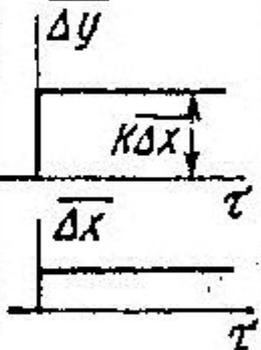
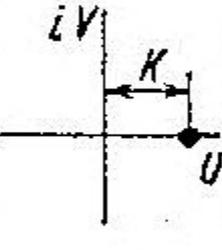
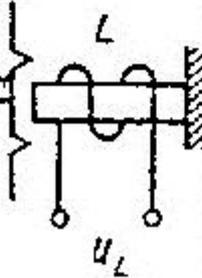
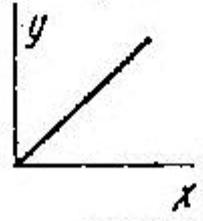
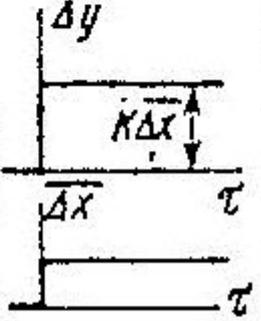
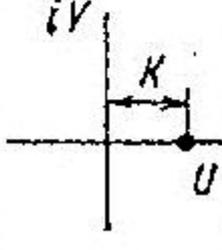
$$T^2 = \frac{\lambda}{B}$$

# Гидроцентробежный чувствительный элемент

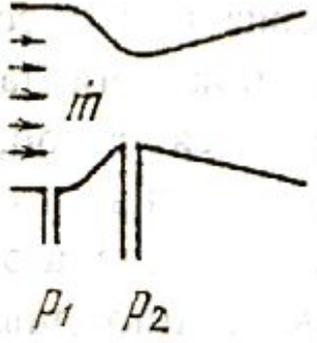
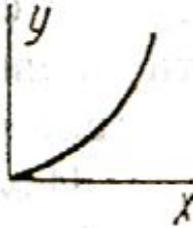
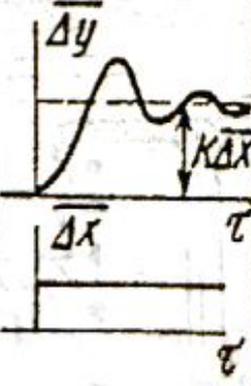
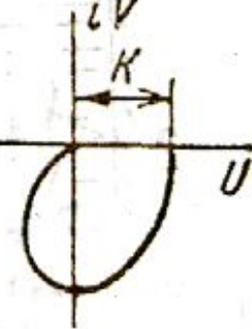
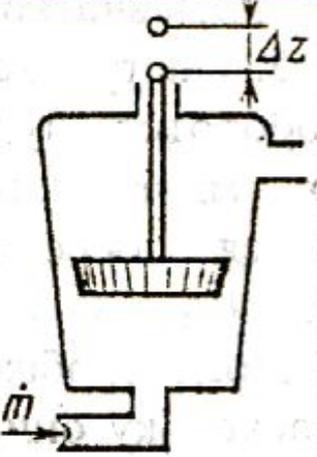
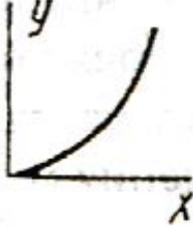
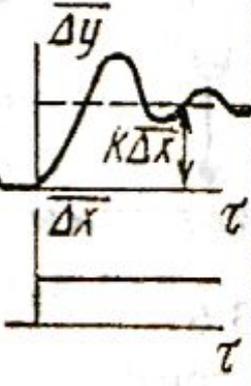
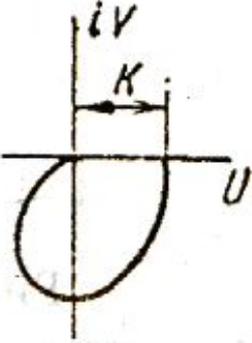


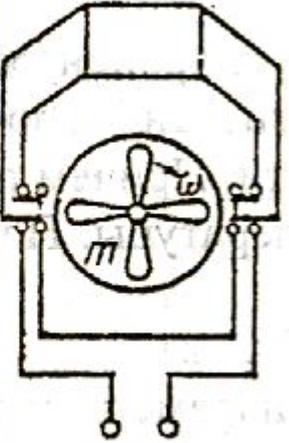
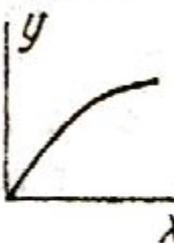
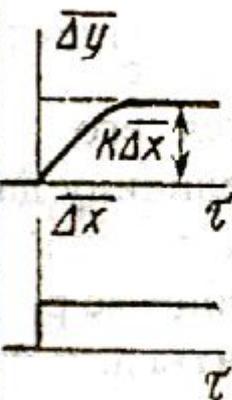
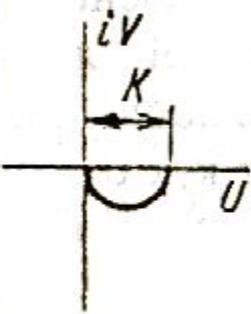
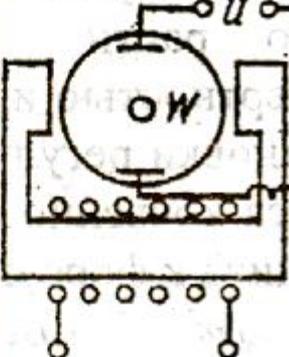
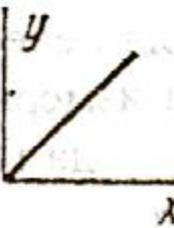
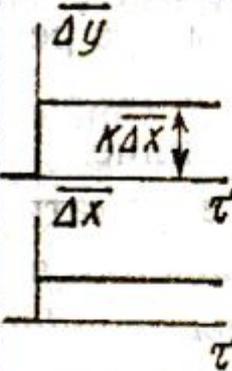
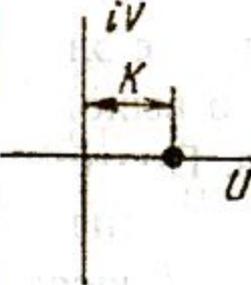
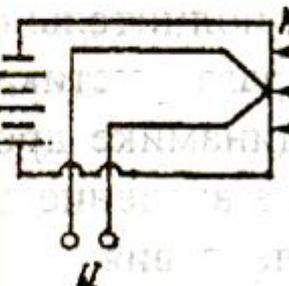
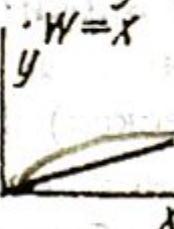
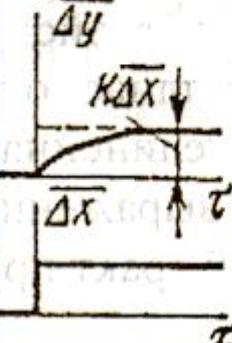
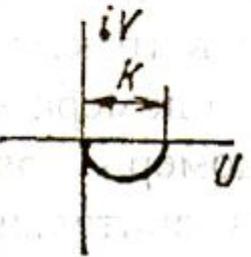
# Чувствительные и сравнивающие элементы для измерения давления

№ по пор.	Название	Схема	СХ	Уравнение динамики	Переходный процесс	АФХ
1	Мембранный		$P_{izm} - P_{kv} = X$ $\Delta z = y$	$(T_2^2 p^2 + T_1 p + 1) \Delta y = K \Delta X$ $T_1 < 2T_2$		
2	Сильфонный		$P_{izm} - P_{kv} = X$ $\Delta z = y$	$(T_2^2 p^2 + T_1 p + 1) \Delta y = K \Delta X$ $T_1 < 2T_2$		
3	Витая манометрическая трубка		$P_{izm} = X$ $\Delta \phi = y$	$(T_2^2 p^2 + T_1 p + 1) \Delta y = K \Delta X$ $T_1 < 2T_2$		

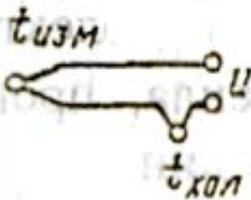
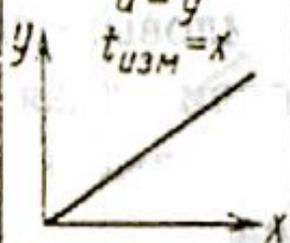
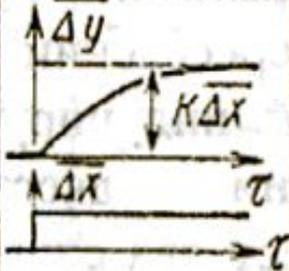
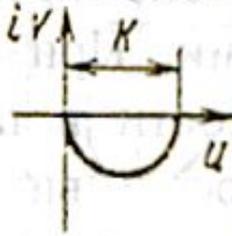
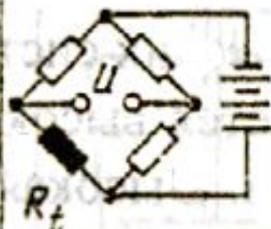
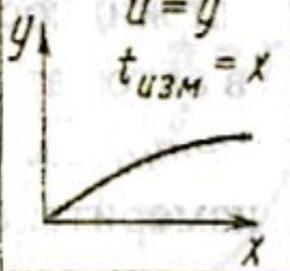
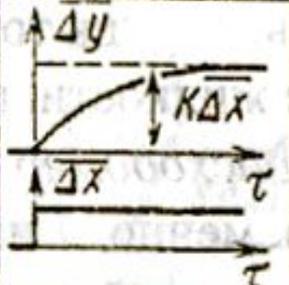
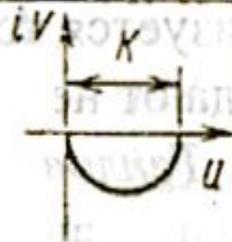
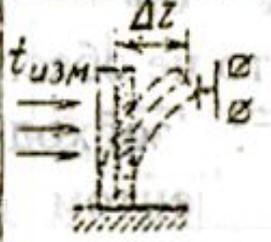
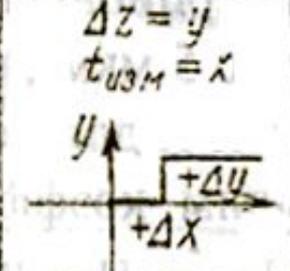
№ по пор.	Название	Схема	ОХ	Уравнение динамики	Переходный процесс	АФХ
4	Пьезоэлектрический		$P_{изм} = x$ $u = y$ 	$\overline{\Delta y} = K \overline{\Delta x}$		
5	Емкостной		$P_{изм} = x$ $C = y$ 	$\overline{\Delta y} = K \overline{\Delta x}$		
6	Индуктивный		$P_{изм} = x$ $L = y$ 	$\overline{\Delta y} = K \overline{\Delta x}$		

# Чувствительные элементы для измерения расхода

№ по пор.	Название	Схема	СХ	Уравнение динамики	Переходный процесс	АФХ
1	Трубка Вентури		$p_1 - p_2 = y$ $\dot{m} = x$ 	$(T_2^2 \rho^2 + T_1 \rho + 1) \Delta y = K \Delta x$		
2	Ротаметрический		$\Delta z = y$ $\dot{m} = x$ 	$(T_2^2 \rho^2 + T_1 \rho + 1) \Delta y = K \Delta x$		

3	Турбинный электро- магнитный		$\omega = y$ $m = x$ 	$(T_1 \rho + 1) \overline{\Delta y} = K \Delta x$		
4	Электро- магнитный индукцион- ный		$u = y$ $W = x$ 	$\overline{\Delta y} = K \Delta x$		
5	Тепловой		$u = y$ $W = x$ 	$(T_1 \rho + 1) \overline{\Delta y} = K \Delta x$		

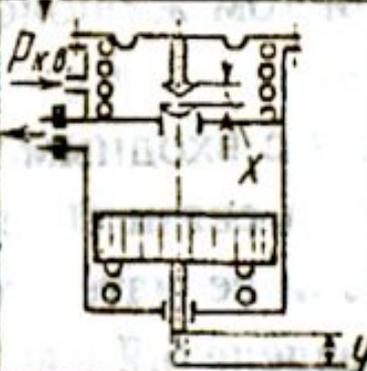
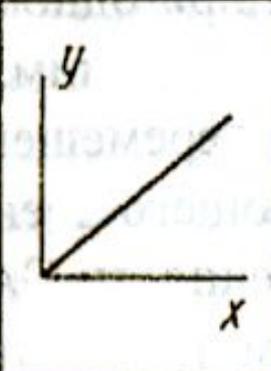
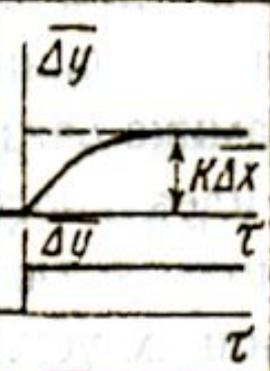
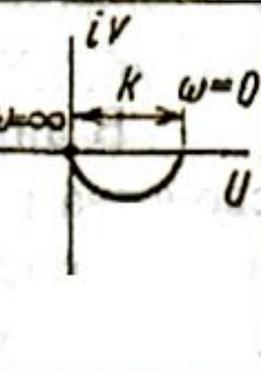
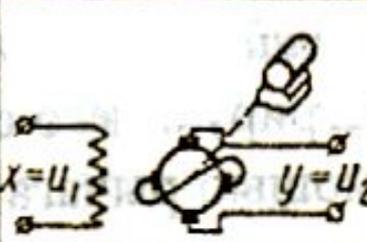
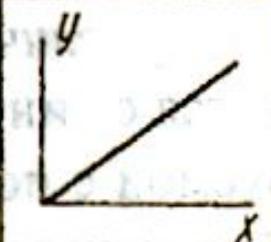
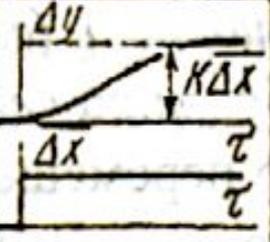
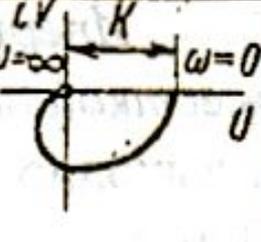
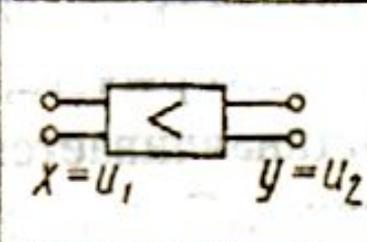
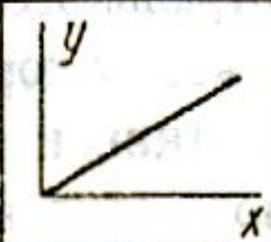
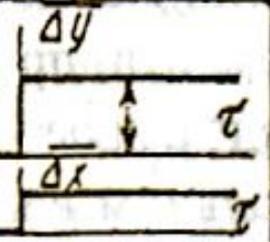
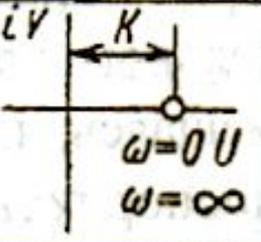
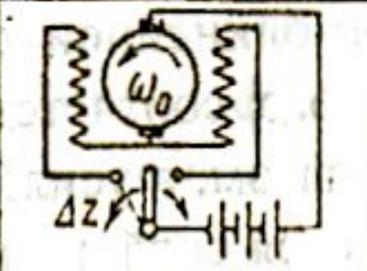
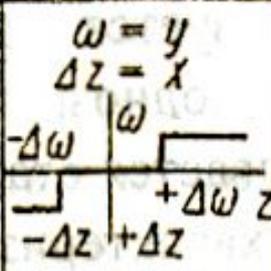
# Элементы для измерения температуры

№ по пор.	Название	Схема	СХ	Уравнение динамики	Переходный процесс	АФХ
1	Термопара			$(T, p-1)\overline{\Delta y} = K\overline{\Delta x}$		
2	Термометр сопротивления			$(T, p+1)\overline{\Delta y} = K\overline{\Delta x}$		
3	Тепловое реле			$y = 0$ $+ \Delta y \begin{cases} \text{при } x < 0 \\ \text{при } x < +\Delta x \\ \text{при } x > +\Delta x \end{cases}$		

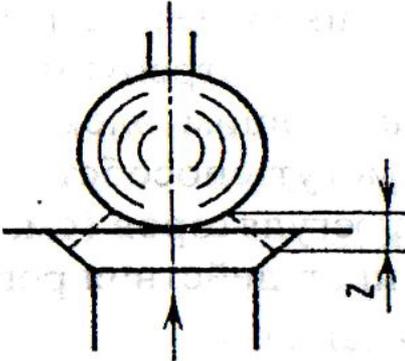
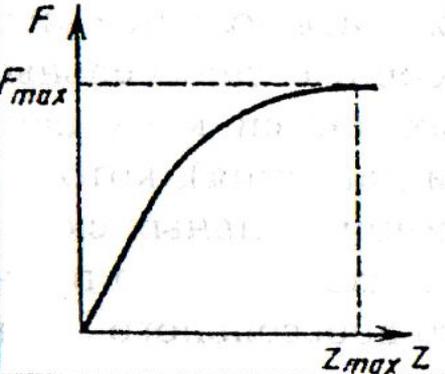
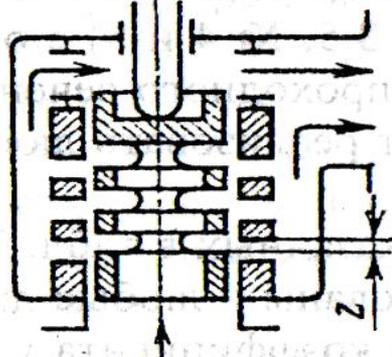
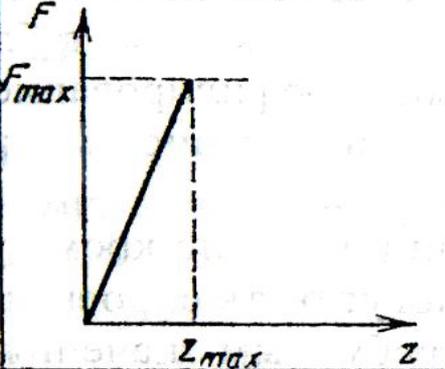
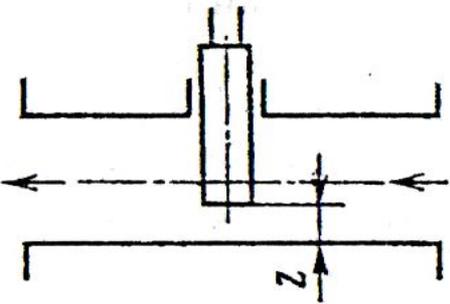
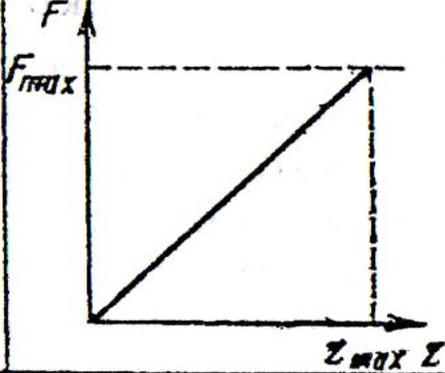
# Усилительные элементы

№ по лор.	Название усилителя	Схема	СХ	Уравнение динамики	Переходный процесс	АФХ
1	Поршневой гидравлический (интегрирующий)			$T_y \rho \Delta \bar{y} = \Delta x$		
2	Поршневой гидравлический с жесткой обратной связью (инерционный)			$(T_y \rho + 1) \Delta \bar{y} = K \Delta x$		
3	Поршневой гидравлический с гибкой обратной связью (изотропный)			$(T_2^2 \rho^2 + T_1 \rho) \Delta \bar{y} = K (T_1 \rho - 1) \Delta x$		

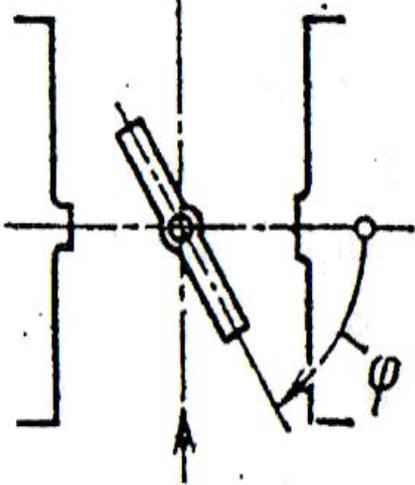
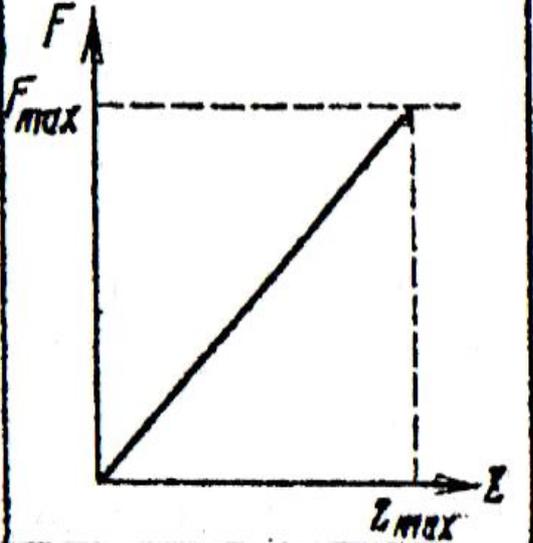
# Усилительные элементы

4	<p>Поршневой пневматический</p>			$(\tau_y \rho + 1) \overline{\Delta y} = K \Delta x$		
5	<p>Электро-машинный</p>			$(\tau_z^2 \rho^2 + \tau_1 \rho + 1) \overline{\Delta y} = K \Delta x$		
6	<p>Электрон-ный</p>			$\overline{\Delta y} = K \overline{\Delta x}$		
7	<p>Реверсивный электрический с контактным управлением</p>		$\omega = y$ $\Delta z = x$ 	$\omega = 0 \begin{cases} \text{при } x < +\Delta x \\ \text{при } x > -\Delta x \end{cases}$ $+\Delta\omega \text{ при } x > +\Delta x$ $-\Delta\omega \text{ при } x < -\Delta x$		

# Исполнительные элементы

1	Шаровой		
2	С большим коэффициентом усиления		
3	Шиберный		

# Исполнительные элементы

4	Поворотный дроссель		
5	Поворотный секционный дроссель	