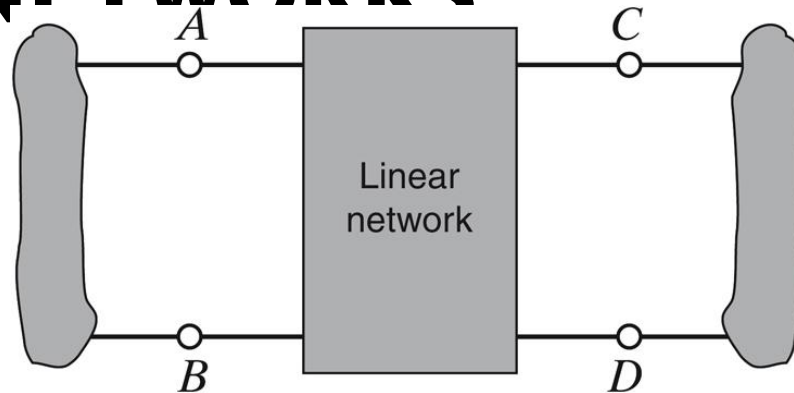


# TWO-PORT NETWORKS



In many situations one is not interested in the internal organization of a network. A description relating input and output variables may be sufficient

A two-port model is a description of a network that relates voltages and currents

at two pairs of terminals

## LEARNING

## GOALS

Study the basic types of two-port models

Admittance parameters

Impedance parameters

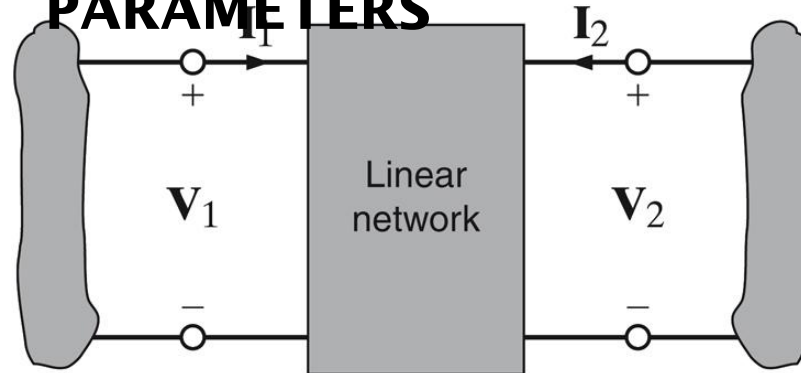
Hybrid parameters

Transmission

parameters

Understand how to convert one model into another

# ADMITTANCE PARAMETERS



**The network contains NO independent sources**

**The admittance parameters describe the currents in terms of the voltages**

$y_{21}$  determines the current flowing into port 2 when the port is short-circuited and a voltage is applied to port 1

$$I_1 = y_{11}V_1 + y_{12}V_2$$

$$I_2 = y_{21}V_1 + y_{22}V_2$$

**The first subindex identifies the output port. The second the input port.**

**The computation of the parameters follows directly from the definition**

$$y_{11} = \left. \frac{I_1}{V_1} \right|_{V_2=0}$$

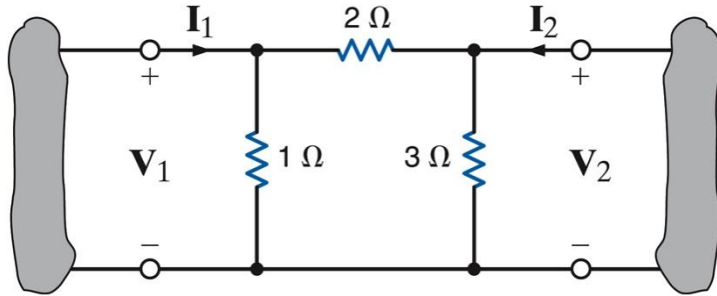
$$y_{12} = \left. \frac{I_1}{V_2} \right|_{V_1=0}$$

$$y_{21} = \left. \frac{I_2}{V_1} \right|_{V_2=0}$$

$$y_{22} = \left. \frac{I_2}{V_2} \right|_{V_1=0}$$

# LEARNING EXAMPLE

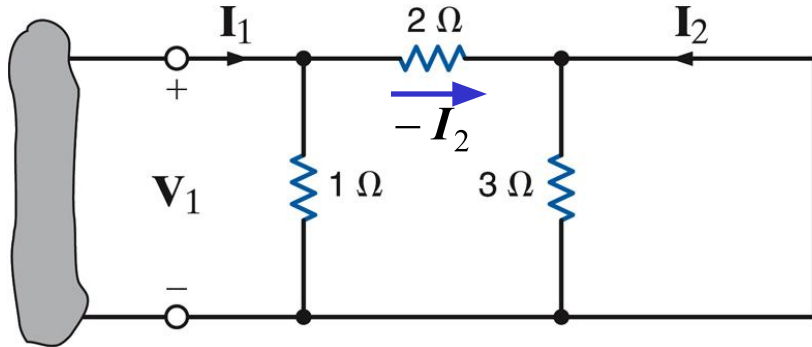
## Find the admittance parameters for the network



$$I_1 = y_{11}V_1 + y_{12}V_2$$

$$I_2 = y_{21}V_1 + y_{22}V_2$$

Circuit used to determine  $y_{11}, y_{21}$

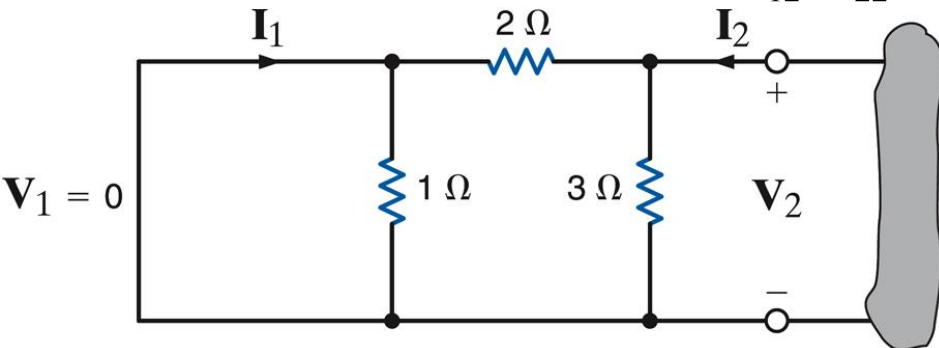


$$V_2 = 0$$

$$I_1 = \left(1 + \frac{1}{2}\right)V_1 \Rightarrow y_{11} = \frac{3}{2}[S]$$

$$-I_2 = \frac{1}{1+2}I_1 \Rightarrow I_2 = -\frac{1}{2}V_1 \Rightarrow y_{21} = -\frac{1}{2}[S]$$

Circuit used to determine  $y_{12}, y_{22}$



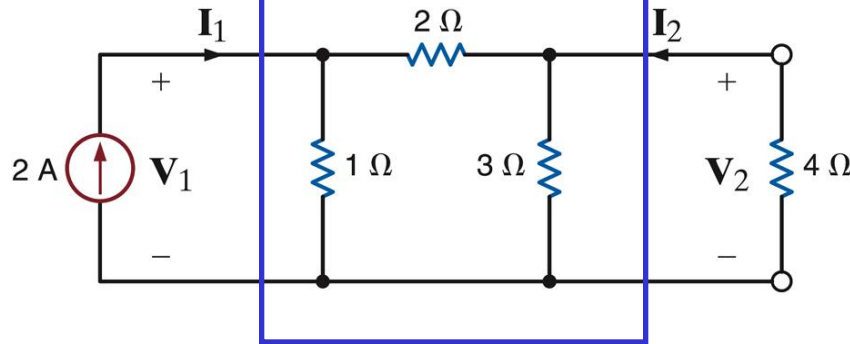
$$V_1 = 0$$

$$I_2 = \left(\frac{1}{2} + \frac{1}{3}\right)V_2 \Rightarrow y_{22} = \frac{5}{6}[S]$$

$$-I_1 = \frac{3}{2+3}I_2 = \frac{3 \times 5}{5 \times 6}V_2 \Rightarrow y_{12} = \frac{1}{2}[S]$$

Next we show one use of this model

## An application of the admittance parameters



Determine the current through the 4 Ohm resistor

$$I_1 = y_{11}V_1 + y_{12}V_2$$

$$I_2 = y_{21}V_1 + y_{22}V_2$$

$$I_1 = \frac{3}{2}V_1 - \frac{1}{2}V_2$$

$$I_2 = -\frac{1}{2}V_1 + \frac{5}{6}V_2$$

$$I_1 = 2A, \quad V_2 = -4I_2 \quad I_2 = -\frac{1}{4}V_2$$

The model plus the conditions at the ports are sufficient to determine the other variables

$$0 = \frac{3}{2}V_1 - \frac{1}{2}V_2$$

$$0 = -\frac{1}{2}V_1 + \left(\frac{5}{6} + \frac{1}{4}\right)V_2$$

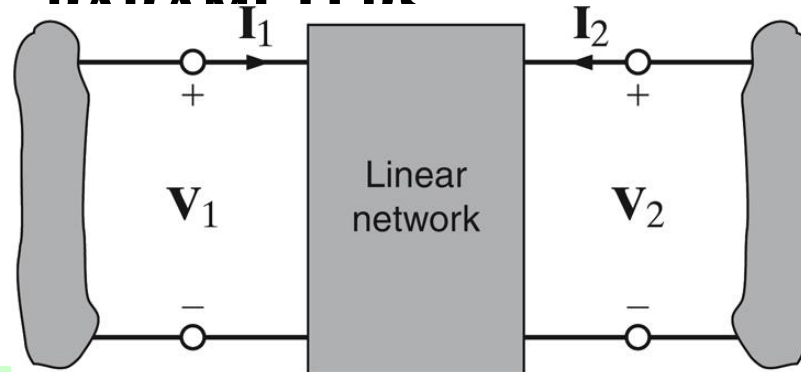
$$V_1 = \frac{13}{6}V_2$$

$$V_2 = \frac{8}{11}[V]$$

$$I_2 = -\frac{2}{11}[A]$$

# IMPEDANCE

## PARAMETERS



**The network contains NO independent sources**

$$V_1 = z_{11}I_1 + z_{12}I_2$$

$$V_2 = z_{21}I_1 + z_{22}I_2$$

**The '*z parameters*' can be derived in a manner similar to the Y parameters**

$$z_{11} = \left. \frac{V_1}{I_1} \right|_{I_2=0}$$

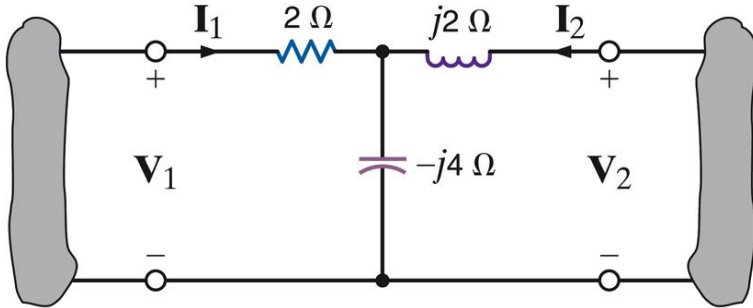
$$z_{21} = \left. \frac{V_2}{I_1} \right|_{I_2=0}$$

$$z_{12} = \left. \frac{V_1}{I_2} \right|_{I_1=0}$$

$$z_{22} = \left. \frac{V_2}{I_2} \right|_{I_1=0}$$

## LEARNING EXAMPLE

## Find the Z parameters



$$V_1 = z_{11}I_1 + z_{12}I_2$$

$$V_2 = z_{21}I_1 + z_{22}I_2$$

$$z_{11} = \left. \frac{V_1}{I_1} \right|_{I_2=0}$$

$$z_{21} = \left. \frac{V_2}{I_1} \right|_{I_2=0}$$

$$z_{12} = \left. \frac{V_1}{I_2} \right|_{I_1=0}$$

$$z_{22} = \left. \frac{V_2}{I_2} \right|_{I_1=0}$$

## Write the loop equations

$$V_1 = 2I_1 - j4(I_1 + I_2)$$

$$V_2 = j2I_2 - j4(I_2 + I_1)$$

## rearrangin

g

$$V_1 = (2 - j4)I_1 - j4I_2 \quad \Rightarrow \quad z_{11} = 2 - j4\Omega$$

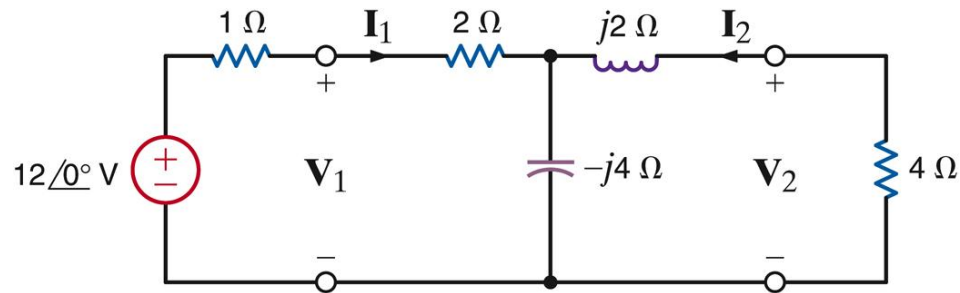
$$z_{12} = -j4\Omega$$

$$V_2 = -j4I_1 - j2I_2 \quad z_{21} = -j4\Omega$$

$$z_{22} = -j2\Omega$$

## LEARNING EXAMPLE

Use the Z parameters to find the current through the 4 Ohm resistor



$$V_1 = z_{11}I_1 + z_{12}I_2$$

$$V_2 = z_{21}I_1 + z_{22}I_2$$

Output port  
constraint

$$V_2 = -4I_2$$

Input port  
constraint

$$V_1 = 12\angle 0^\circ - (1)I_1$$

$$V_1 = (2 - j4)I_1 - j4I_2$$

$$V_2 = -j4I_1 - j2I_2$$

$$0 = -j4I_1 + (4 - j2)I_2 \quad \times (3 - j4)$$

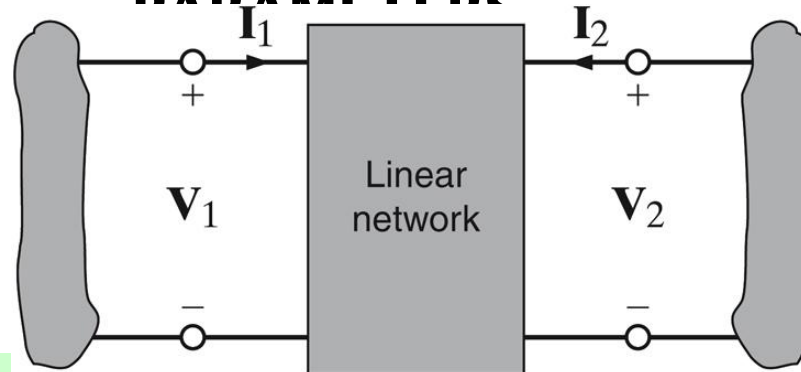
$$12 = (3 - j4)I_1 - j4I_2 \quad \times j4$$

---

$$48j = (16 + (4 - j2)(3 - j4))I_2 \Rightarrow I_2 = 1.61\angle 137.73^\circ$$

# HYBRID

## PARAMETERS



**The network contains NO independent sources**

$$V_1 = h_{11}I_1 + h_{12}V_2$$

$$I_2 = h_{21}I_1 + h_{22}V_2$$

$$h_{11} = \left. \frac{V_1}{I_1} \right|_{V_2=0}$$

$$h_{21} = \left. \frac{I_2}{I_1} \right|_{V_2=0}$$

$h_{11}$  = short - circuit input impedance

$h_{12}$  = open - circuit reverse voltage gain

$$h_{12} = \left. \frac{V_1}{V_2} \right|_{I_1=0}$$

$$h_{22} = \left. \frac{I_2}{V_2} \right|_{I_1=0}$$

$h_{21}$  = short - circuit forward current gain

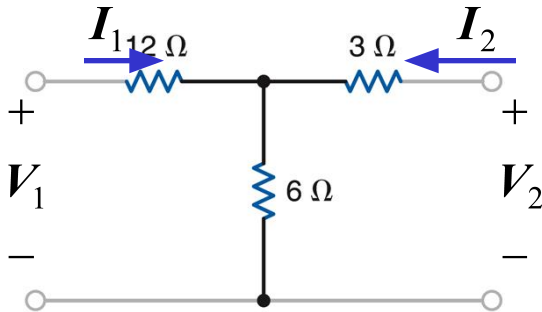
$h_{22}$  = open - circuit output admittance

**These parameters are very common in modeling transistors**



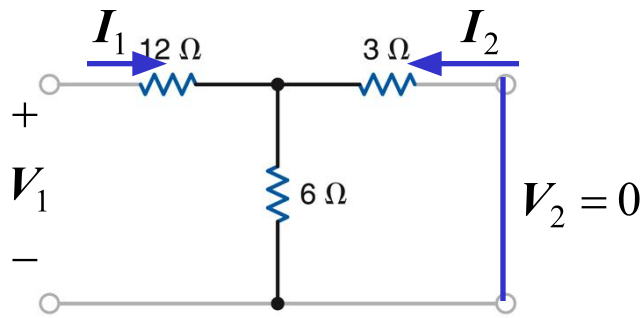
# LEARNING EXAMPLE

## Find the hybrid parameters for the network



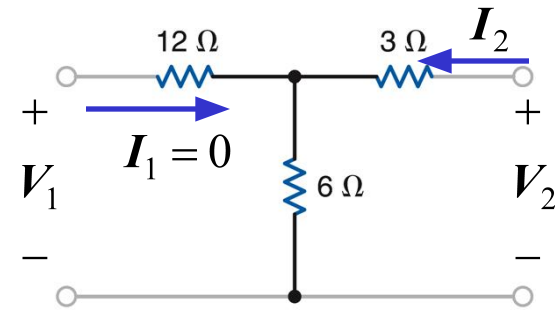
$$V_1 = h_{11}I_1 + h_{12}V_2$$

$$I_2 = h_{21}I_1 + h_{22}V_2$$



$$V_1 = (12 + (6 \parallel 3))I_1 \Rightarrow h_{11} = 14\Omega$$

$$I_2 = -\frac{6}{3+6}I_1 \Rightarrow h_{21} = -\frac{2}{3}$$



$$V_1 = \frac{6}{3+6}V_2 \Rightarrow h_{12} = \frac{2}{3}$$

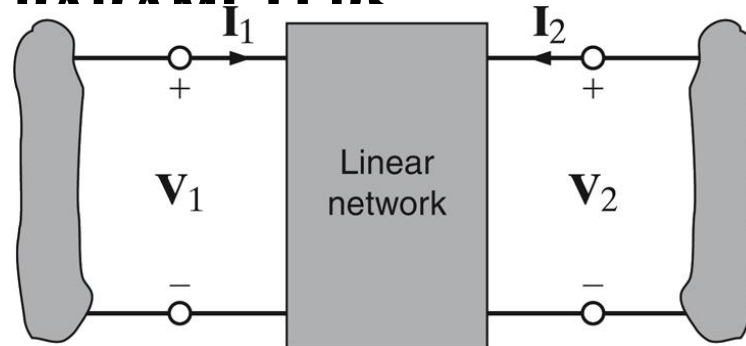
$$I_2 = \frac{V_2}{9} \Rightarrow h_{22} = \frac{1}{9}[S]$$

# TRANSMISSION

PARAMETERS

**ABCD**

**parameters**



**The network contains NO independent sources**

$$V_1 = AV_2 - BI_2$$

$$I_1 = CV_2 - DI_2$$

$$A = \left. \frac{V_1}{V_2} \right|_{I_2=0}$$

$$C = \left. \frac{I_1}{V_2} \right|_{I_2=0}$$

$$B = - \left. \frac{V_1}{I_2} \right|_{V_2=0}$$

$$D = - \left. \frac{I_1}{I_2} \right|_{V_2=0}$$

A = open circuit voltage ratio

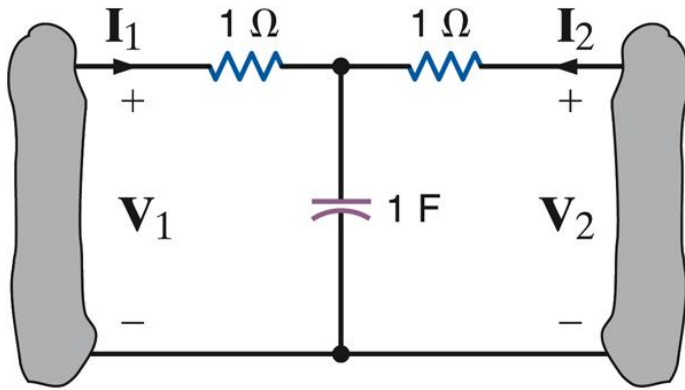
B = negative short -circuit transfer impedance

C = open -circuit transfer admittance

D = negative short -circuit current ratio

# LEARNING EXAMPLE

## Determine the transmission parameters



$$V_1 = AV_2 - BI_2$$

$$I_1 = CV_2 - DI_2$$

$$A = \left. \frac{V_1}{V_2} \right|_{I_2=0}$$

$$C = \left. \frac{I_1}{V_2} \right|_{I_2=0}$$

$$B = - \left. \frac{V_1}{I_2} \right|_{V_2=0}$$

$$D = - \left. \frac{I_1}{I_2} \right|_{V_2=0}$$

when  $I_2 = 0$

$$V_2 = \frac{\frac{1}{j\omega}}{1 + \frac{1}{j\omega}} V_1 \Rightarrow A = 1 + j\omega$$

$$V_2 = \frac{1}{j\omega} I_1 \Rightarrow \frac{I_1}{V_2} = j\omega$$

when  $V_2 = 0$

$$I_2 = - \frac{\frac{1}{j\omega}}{1 + \frac{1}{j\omega}} I_1 = - \frac{1}{1 + j\omega} I_1 \Rightarrow D = 1 + j\omega$$

$$V_1 = \left[ 1 + \left( 1 \parallel \frac{1}{j\omega} \right) \right] I_1 = \left[ \frac{2 + j\omega}{1 + j\omega} \right] [-(1 + j\omega)] I_2$$

$$B = 2 + j\omega$$

# PARAMETER CONVERSIONS

**If all parameters exist, they can be related by conventional algebraic manipulations.**

**As an example consider the relationship between Z and Y parameters**

$$V_1 = z_{11}I_1 + z_{12}I_2$$

$$V_2 = z_{21}I_1 + z_{22}I_2$$

$$\begin{bmatrix} V_1 \\ V_2 \end{bmatrix} = \begin{bmatrix} z_{11} & z_{12} \\ z_{21} & z_{22} \end{bmatrix} \begin{bmatrix} I_1 \\ I_2 \end{bmatrix} \Rightarrow \begin{bmatrix} I_1 \\ I_2 \end{bmatrix} = \begin{bmatrix} z_{11} & z_{12} \\ z_{21} & z_{22} \end{bmatrix}^{-1} \begin{bmatrix} V_1 \\ V_2 \end{bmatrix} = \begin{bmatrix} y_{11} & y_{12} \\ y_{21} & y_{22} \end{bmatrix} \begin{bmatrix} V_1 \\ V_2 \end{bmatrix}$$

$$\begin{bmatrix} y_{11} & y_{12} \\ y_{21} & y_{22} \end{bmatrix} = \begin{bmatrix} z_{11} & z_{12} \\ z_{21} & z_{22} \end{bmatrix}^{-1} = \frac{1}{\Delta_Z} \begin{bmatrix} z_{22} & -z_{12} \\ -z_{21} & z_{11} \end{bmatrix}$$

$$\text{with } \Delta_Z = z_{11}z_{22} - z_{21}z_{12}$$

In the following conversion table, the symbol  $\Delta$  stands for the determinant of the corresponding matrix

$$\Delta_Z = \begin{vmatrix} z_{11} & z_{12} \\ z_{21} & z_{22} \end{vmatrix}, \Delta_Y = \begin{vmatrix} y_{11} & y_{12} \\ y_{21} & y_{22} \end{vmatrix}, \Delta_H = \begin{vmatrix} h_{11} & h_{12} \\ h_{21} & h_{22} \end{vmatrix}, \Delta_T = \begin{vmatrix} A & B \\ C & D \end{vmatrix}$$

**TABLE 16.1** Two-port parameter conversion formulas

$$\begin{bmatrix} \mathbf{z}_{11} & \mathbf{z}_{12} \\ \mathbf{z}_{21} & \mathbf{z}_{22} \end{bmatrix}$$

$$\begin{bmatrix} \frac{\mathbf{z}_{22}}{\Delta_Z} & \frac{-\mathbf{z}_{12}}{\Delta_Z} \\ \frac{-\mathbf{z}_{21}}{\Delta_Z} & \frac{\mathbf{z}_{11}}{\Delta_Z} \end{bmatrix}$$

$$\begin{bmatrix} \frac{\mathbf{z}_{11}}{\mathbf{z}_{21}} & \frac{\Delta_Z}{\mathbf{z}_{21}} \\ 1 & \frac{\mathbf{z}_{22}}{\mathbf{z}_{21}} \end{bmatrix}$$

$$\begin{bmatrix} \frac{\Delta_Z}{\mathbf{z}_{22}} & \frac{\mathbf{z}_{12}}{\mathbf{z}_{22}} \\ \frac{-\mathbf{z}_{21}}{\mathbf{z}_{22}} & 1 \end{bmatrix}$$

$$\begin{bmatrix} \frac{\mathbf{y}_{22}}{\Delta_Y} & \frac{-\mathbf{y}_{12}}{\Delta_Y} \\ \frac{-\mathbf{y}_{21}}{\Delta_Y} & \frac{\mathbf{y}_{11}}{\Delta_Y} \end{bmatrix}$$

$$\begin{bmatrix} \mathbf{y}_{11} & \mathbf{y}_{12} \\ \mathbf{y}_{21} & \mathbf{y}_{22} \end{bmatrix}$$

$$\begin{bmatrix} \frac{-\mathbf{y}_{22}}{\mathbf{y}_{21}} & \frac{-1}{\mathbf{y}_{21}} \\ \mathbf{y}_{21} & \frac{\mathbf{y}_{11}}{\mathbf{y}_{21}} \end{bmatrix}$$

$$\begin{bmatrix} \frac{1}{\mathbf{y}_{11}} & \frac{-\mathbf{y}_{12}}{\mathbf{y}_{11}} \\ \mathbf{y}_{21} & \frac{\Delta_Y}{\mathbf{y}_{11}} \end{bmatrix}$$

$$\begin{bmatrix} \frac{\mathbf{A}}{\mathbf{C}} & \frac{\Delta_T}{\mathbf{C}} \\ 1 & \frac{\mathbf{D}}{\mathbf{C}} \end{bmatrix}$$

$$\begin{bmatrix} \frac{\mathbf{D}}{\mathbf{B}} & \frac{-\Delta_T}{\mathbf{B}} \\ -\frac{1}{\mathbf{B}} & \frac{\mathbf{A}}{\mathbf{B}} \end{bmatrix}$$

$$\begin{bmatrix} \mathbf{A} & \mathbf{B} \\ \mathbf{C} & \mathbf{D} \end{bmatrix}$$

$$\begin{bmatrix} \frac{\mathbf{B}}{\mathbf{D}} & \frac{\Delta_T}{\mathbf{D}} \\ -\frac{1}{\mathbf{D}} & \frac{\mathbf{C}}{\mathbf{D}} \end{bmatrix}$$

$$\begin{bmatrix} \frac{\Delta_H}{\mathbf{h}_{22}} & \frac{\mathbf{h}_{12}}{\mathbf{h}_{22}} \\ \frac{-\mathbf{h}_{21}}{\mathbf{h}_{22}} & \frac{1}{\mathbf{h}_{22}} \end{bmatrix}$$

$$\begin{bmatrix} \frac{1}{\mathbf{h}_{11}} & \frac{-\mathbf{h}_{12}}{\mathbf{h}_{11}} \\ \frac{\mathbf{h}_{21}}{\mathbf{h}_{11}} & \frac{\Delta_H}{\mathbf{h}_{11}} \end{bmatrix}$$

$$\begin{bmatrix} \frac{-\Delta_H}{\mathbf{h}_{21}} & \frac{-\mathbf{h}_{11}}{\mathbf{h}_{21}} \\ \frac{-\mathbf{h}_{22}}{\mathbf{h}_{21}} & \frac{-1}{\mathbf{h}_{21}} \end{bmatrix}$$

$$\begin{bmatrix} \mathbf{h}_{11} & \mathbf{h}_{12} \\ \mathbf{h}_{21} & \mathbf{h}_{22} \end{bmatrix}$$

# INTERCONNECTION OF

Interconnections permit the description of complex systems in terms of simpler

The basic interconnections to be considered are: *parallel*, *series* and *cascade*

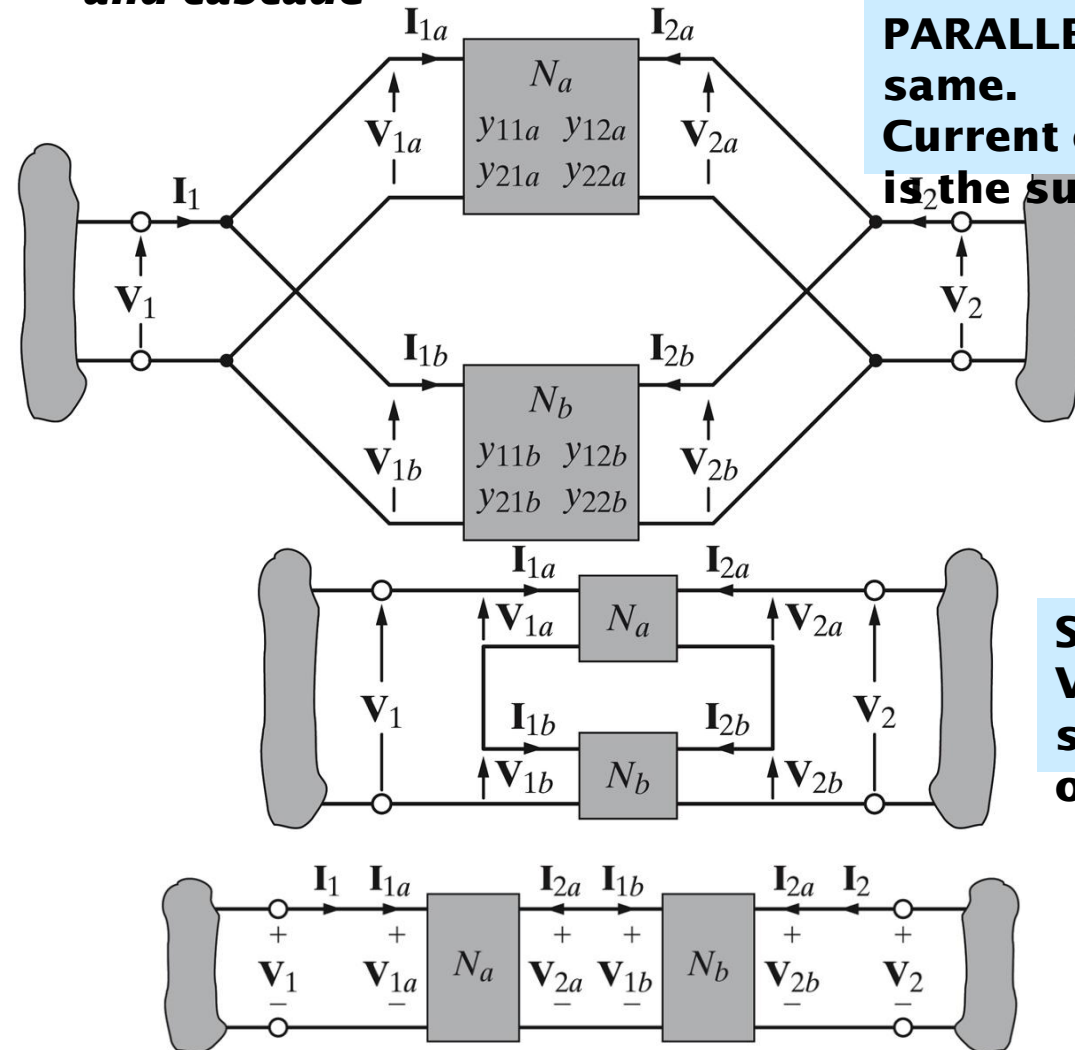
**PARALLEL:** Voltages are the same.  
Current of interconnection is the sum of currents

The rules used to derive models for interconnection assume that each subsystem behaves in the

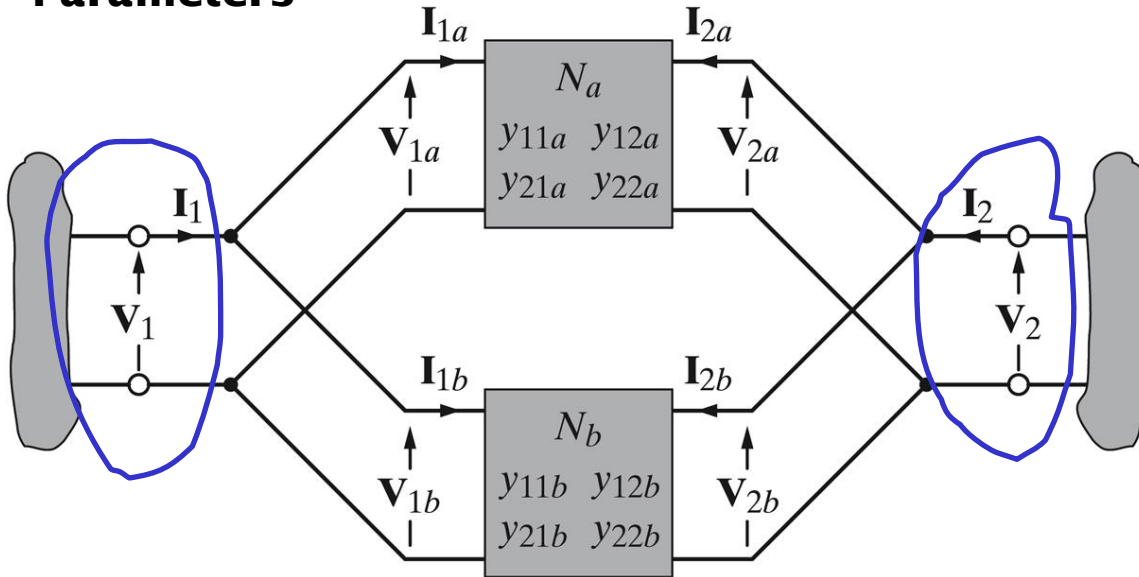
same manner before and after the interconnection

**SERIES:** Currents are the same.  
Voltage of interconnection is the sum of voltages

**CASCADE:**  
Output of first subsystem acts as input for the



## Parallel Interconnection: Description Using Y Parameters



Interconnection description

$$\begin{bmatrix} I_1 \\ I_2 \end{bmatrix} = \begin{bmatrix} y_{11} & y_{12} \\ y_{21} & y_{22} \end{bmatrix} \begin{bmatrix} V_1 \\ V_2 \end{bmatrix}$$

$$I = YV$$

$$I_a = \begin{bmatrix} I_{1a} \\ I_{2a} \end{bmatrix}, V_a = \begin{bmatrix} V_{1a} \\ V_{2a} \end{bmatrix}, Y_a = \begin{bmatrix} y_{11a} & y_{12a} \\ y_{21a} & y_{22a} \end{bmatrix} \Rightarrow I_a = Y_a V_a$$

In a similar manner

$$I_b = Y_b V_b$$

Interconnection constraints:

$$I_1 = I_{1a} + I_{1b}, \quad I_2 = I_{2a} + I_{2b}$$

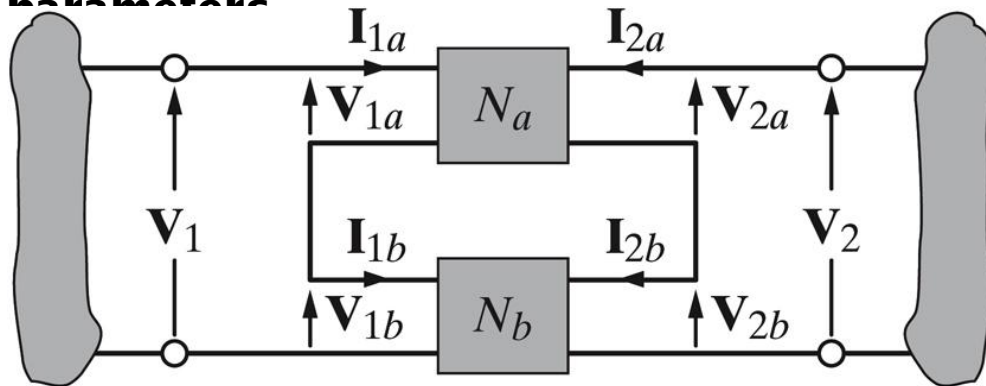
$$V_1 = V_{1a} = V_{1b}, \quad V_2 = V_{2a} = V_{2b}$$

$$\Rightarrow \begin{cases} I = I_a + I_b \\ V = V_a = V_b \end{cases} \Rightarrow I = Y_a V_a + Y_b V_b = (Y_a + Y_b) V$$

$$Y = Y_a + Y_b$$

## Series interconnection using Z

parameters



Interconnection constraints

$$I_a = I_b = I$$

$$V = V_a + V_b$$

$$\Rightarrow V = Z_a I + Z_b I = (Z_a + Z_b) I$$

**SERIES: Currents are the same. Voltage of interconnection is the sum of voltages**

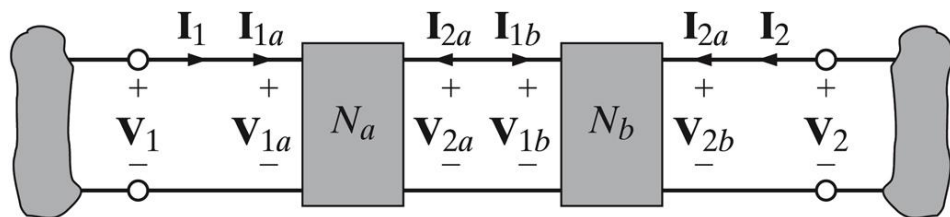
Description of each subsystem

$$V_a = Z_a I_a, \quad V_b = Z_b I_b$$

$$Z = Z_a + Z_b$$



## Cascade connection using transmission parameters



Interconnection constraints:

$$I_{2a} = -I_{1b} \quad V_{2a} = V_{1b}$$

$$V_1 = V_{1a} \quad V_2 = V_{2b}$$

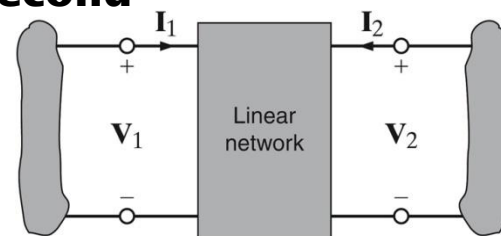
$$I_1 = I_{1a} \quad I_2 = I_{2b}$$

$$\begin{bmatrix} V_{1a} \\ I_{1a} \end{bmatrix} = \begin{bmatrix} A_a & B_a \\ C_a & D_a \end{bmatrix} \begin{bmatrix} V_{2a} \\ -I_{2a} \end{bmatrix}$$

$$\begin{bmatrix} V_{1b} \\ I_{1b} \end{bmatrix} = \begin{bmatrix} A_b & B_b \\ C_b & D_b \end{bmatrix} \begin{bmatrix} V_{2b} \\ -I_{2b} \end{bmatrix}$$

$$\begin{bmatrix} V_1 \\ I_1 \end{bmatrix} = \begin{bmatrix} A_a & B_a \\ C_a & D_a \end{bmatrix} \begin{bmatrix} A_b & B_b \\ C_b & D_b \end{bmatrix} \begin{bmatrix} V_2 \\ -I_2 \end{bmatrix}$$

**CASCADE:**  
Output of first subsystem acts as input for the second



$$V_1 = AV_2 - BI_2$$

$$I_1 = CV_2 - DI_2$$

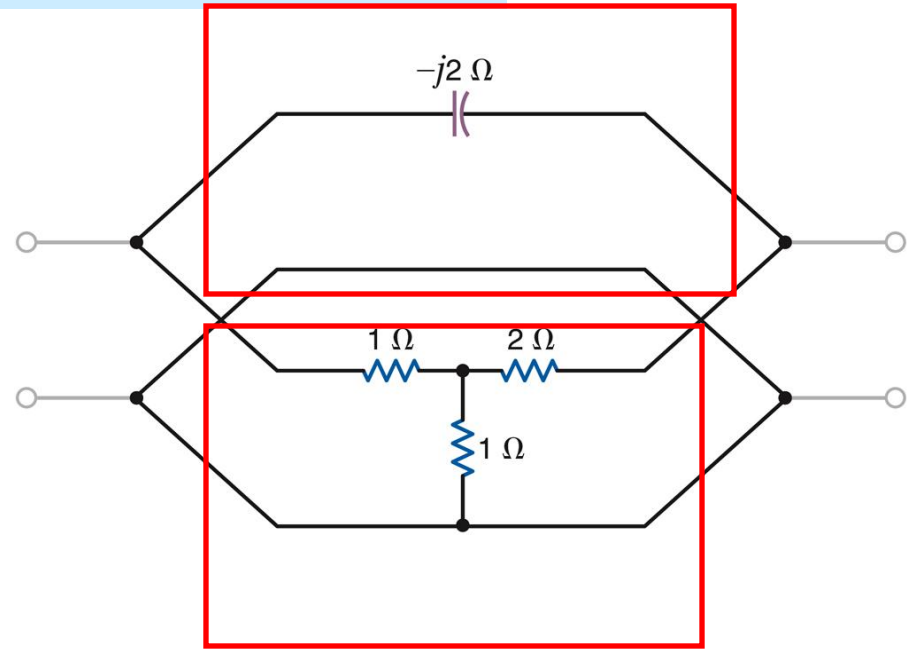
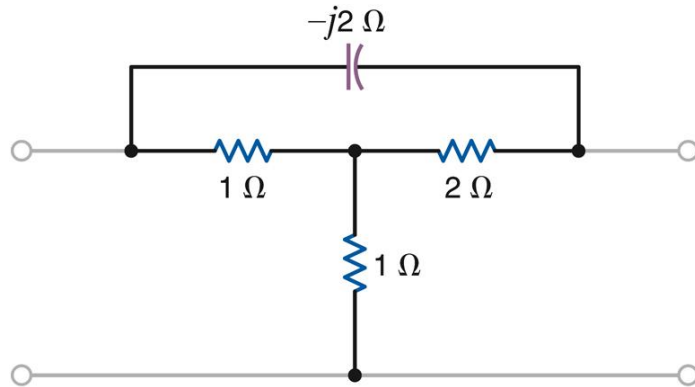
$$\begin{bmatrix} V_1 \\ I_1 \end{bmatrix} = \begin{bmatrix} A & B \\ C & D \end{bmatrix} \begin{bmatrix} V_2 \\ -I_2 \end{bmatrix}$$

**Matrix multiplication does not commute.**

**Order of the interconnection is important**

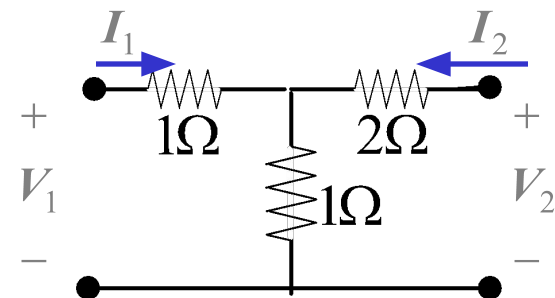
# LEARNING EXAMPLE

Find the Y parameters for the network



$$\begin{aligned} & \xrightarrow{I_1} \quad \quad \quad \xleftarrow{I_2} \\ & + \quad \quad \quad -j2 \quad \quad \quad + \\ & V_1 - V_2 = -j2I_1 \quad \quad \quad V_2 \\ & I_2 = -I_1 \quad \quad \quad - \end{aligned}$$

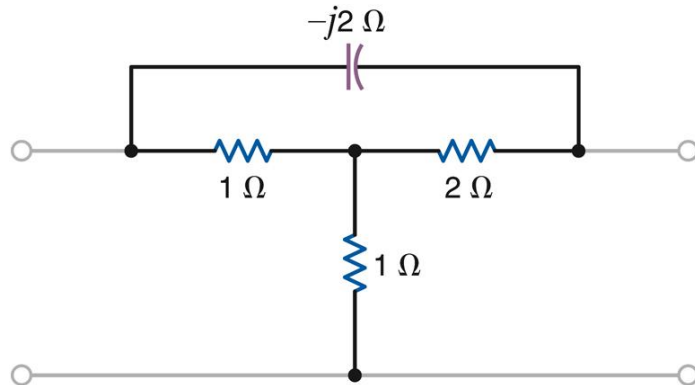
$$\begin{aligned} y_{11a} &= j\frac{1}{2}, \quad y_{12a} = -j\frac{1}{2} \\ y_{21a} &= -j\frac{1}{2}, \quad y_{22a} = j\frac{1}{2} \end{aligned} \quad \mathbf{Y} = \begin{bmatrix} \frac{3}{5} + j\frac{1}{2} & -\left(\frac{1}{5} + j\frac{1}{2}\right) \\ -\left(\frac{1}{5} + j\frac{1}{2}\right) & \frac{2}{5} + j\frac{1}{2} \end{bmatrix} [\mathbf{S}]$$



$$\begin{aligned} V_1 &= 2I_1 + I_2 \\ V_2 &= I_1 + 3I_2 \end{aligned} \quad \mathbf{Y}_b = \begin{bmatrix} 2 & 1 \\ 1 & 3 \end{bmatrix}^{-1} = \frac{1}{5} \begin{bmatrix} 3 & -1 \\ -1 & 2 \end{bmatrix}$$

## LEARNING EXAMPLE

Find the Z parameters of the  
network



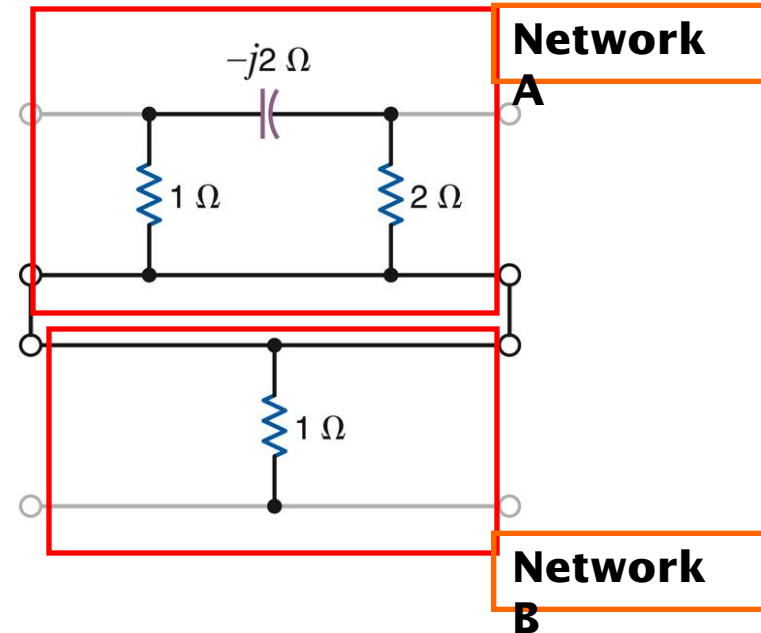
Use direct method,  
or given the Y parameters transform  
to Z  
... or decompose the network in a  
series

connection of simpler networks

$$\mathbf{Z}_a = \begin{bmatrix} \frac{2-2j}{3-2j} & \frac{2}{3-2j} \\ \frac{2}{3-2j} & \frac{2-4j}{3-2j} \end{bmatrix}$$

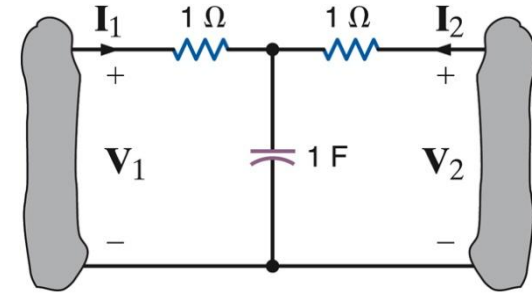
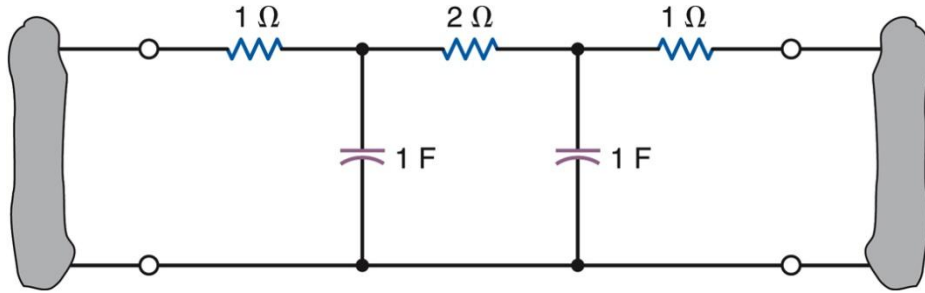
$$\mathbf{Z}_b = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$$

$$\mathbf{Z} = \mathbf{Z}_a + \mathbf{Z}_b = \begin{bmatrix} \frac{5-4j}{3-2j} & \frac{5-2j}{3-2j} \\ \frac{5-2j}{3-2j} & \frac{5-6j}{3-2j} \end{bmatrix}$$



## LEARNING EXAMPLE

### Find the transmission parameters



By splitting the 2-Ohm resistor,  
the network can be viewed as the  
cascade connection of two  
identical

networks

$$\begin{bmatrix} A & B \\ C & D \end{bmatrix} = \begin{bmatrix} 1 + j\omega & 2 + j\omega \\ j\omega & 1 + j\omega \end{bmatrix} \begin{bmatrix} 1 + j\omega & 2 + j\omega \\ j\omega & 1 + j\omega \end{bmatrix}$$

$$\begin{bmatrix} A & B \\ C & D \end{bmatrix} = \begin{bmatrix} 1 + j\omega & 2 + j\omega \\ j\omega & 1 + j\omega \end{bmatrix}$$

$$\begin{bmatrix} A & B \\ C & D \end{bmatrix} = \begin{bmatrix} (1 + j\omega)^2 + (2 + j\omega)j\omega & (1 + j\omega)(2 + j\omega) + (2 + j\omega)(1 + j\omega) \\ j\omega(1 + j\omega) + (1 + j\omega)(j\omega) & j\omega(2 + j\omega) + (1 + j\omega)^2 \end{bmatrix}$$

$$\begin{bmatrix} A & B \\ C & D \end{bmatrix} = \begin{bmatrix} 1 + 4j\omega - 2\omega^2 & 4 + 6j\omega - 2\omega^2 \\ 2j\omega - 2\omega^2 & 1 + 4j\omega - 2\omega^2 \end{bmatrix}$$