

# Non-linear Regression Analysis with Fitter Software Application

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# Agenda

1. Introduction
2. TGA Example
3. NLR Basics
4. Multicollinearity
5. Prediction
6. Testing
7. Bayesian Estimation
8. Conclusions

# 1. Introduction



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# Linear and Non-linear Regressions

	Linear	Non Linear
Formula	$f = a_1\phi_1(x) + \dots + a_p\phi_p(x)$	any $f(a, x)$
Example	$f = a \exp(120x)$	$f = \exp(-ax)$
Source	Soft	Hard
Choice	Easy ?	Difficult ?
Dimension	Large	Small
Multicollinearity	Excess of parameters	Lack of data
Interpretation	Well-known	Uncommon
Purpose	Interpolation	Extrapolation
Soft Tools	Many	Few

**Close relatives?**

## 2. Thermo Gravimetric Analysis Example

**Object**

**PVC Cable Isolation**

**Goal**

**Let's see**

Service-Life Prediction

**it!**

**Experiment**

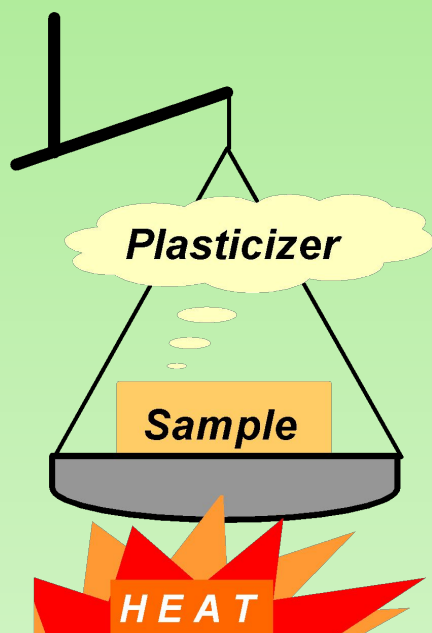
**Thermo Gravimetric Method**

**Tool**

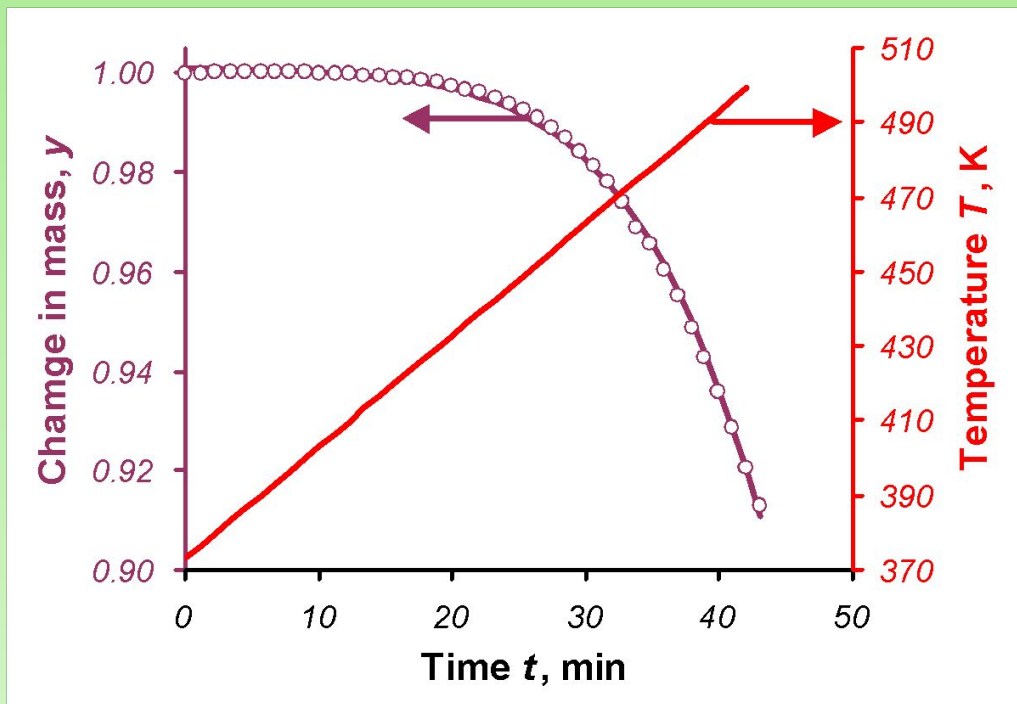
**Non-Linear Regression and Fitter**

# TGA Experiment and Data

TGA Experiment



TGA Data



**This is Experiment! Not a Hell of Flame!**

# TGA Example Variables

Measured

Estimated

**Response**

$y = m/m_0$  Change in mass

**Intermediate**

$C$  Plasticizer concentration

**Predictors**

$t$  Time

$C_0$  Initial concentration

$v$  Heating rate

$T_0$  Initial temperature

$F$  Sample specific surface

**Parameters**

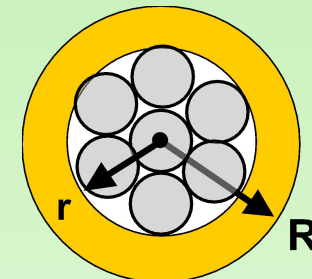
$y_0$  Initial value of  $y$

$k$  Evaporation rate constant

$E$  Activation energy

**Small size problem!**

Sample specific surface 
$$\bar{F} = \frac{S}{V} = \frac{2R}{R^2 - r^2}$$



# Plasticizer Evaporation Model

Evaporation Law

$$\frac{dy}{dt} = -kC, \quad y(0) = y_0$$

Volume Change

**Diffusion is not relevant!**

The Arrhenius law

$$k = F \exp\left(k_0 - \frac{E}{RT}\right)$$

Temperature growth

$$T = T_0 + vt$$



# Fitter Worksheet for TGA Example

	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O	
1																
2		<b>Data</b>														
3		<b>v</b>	<b>T0</b>	<b>C</b>	<b>F</b>	<b>t</b>	<b>y</b>	<b>f</b>	<b>Left</b>							
4		3	373	0.3	2.4	0.00	1.000	1.001	1.001							
5		3	373	0.3	2.4				0.001							
6		3	373	0.3	2.4				0.000							
7		3	373	0.3	2.4				0.000							
8		3	373	0.3	2.4				0.000							
9		3	373	0.3	2.4				0.000							
10		3	373	0.3	2.4				0.000							
11		3	373	0.3	2.4				0.000							
12		3	373	0.3	2.4				0.000							
13		3	373	0.3	2.4				0.000							
14																
15		0	293	0.4	2				0.915							
16		0	293	0.4	2	5E+06		0.877	0.844							
17		0	293	0.4	2	8E+06		0.821	0.788							
18		0	293	0.4	2	1E+07		0.781	0.746							
19		0	293	0.4	2	1E+07		0.748	0.714							
20																

$$\frac{dy}{dt} = -kC, \quad y(0) = y_0$$

$$C = 1 - \frac{1 - C_0}{y}$$

$$k = F \exp\left(k_0 - \frac{E}{RT}\right)$$

$$T = T_0 + vt$$

**Fitter** [X]

🔍 ⚙️  $\frac{dy}{dt}$   $f(x)$  📊

TGA Description Model

$[y]/D[t] = k * [1 - (1 - C_0)/y]; y(0) = y_0$

$k = \exp(k_0 - E/(R * T))$

$T = T_0 + v * t$

R = 0.98717

**y0=?**

**k0=?**

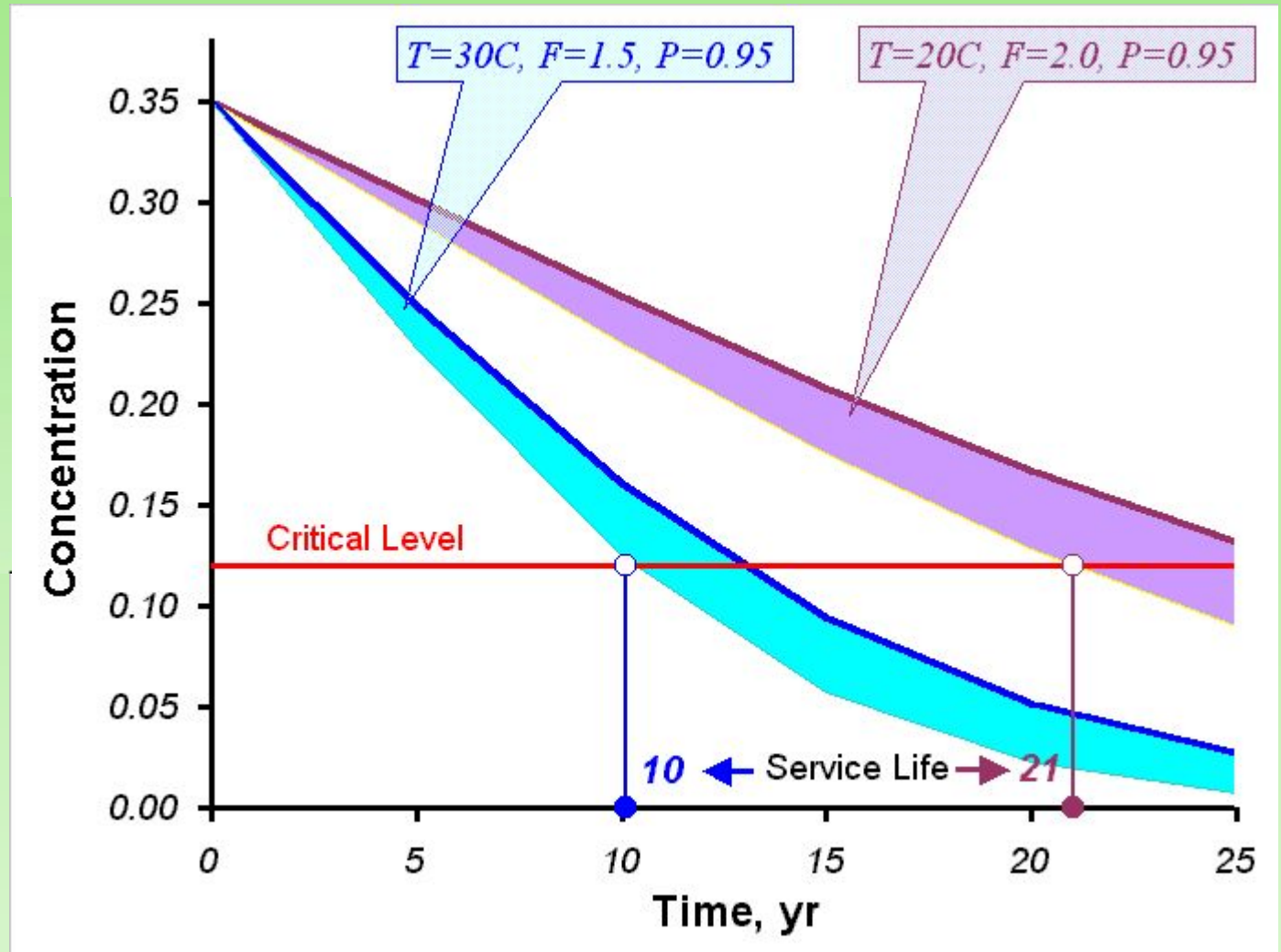
**E=?**

**Parameters estimation**

Name	Initial	Final	Deviation
y0	1	1.00088	0.0002
k0	10	13.9964	0.24016
E	10000	18052.3	225.424

# Service Life Prediction by TGA Data

By Science  
not  
by guess!



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# 3. NLR Basics



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# Data and Errors

Response

Predictors

Weights

Parameters

Fit

$$\begin{matrix} y_1 \\ y_2 \\ \vdots \\ y_N \end{matrix} \quad \mathbf{y}$$

$$\begin{matrix} x_{11} & x_{12} & \dots & x_{1m} \\ x_{21} & x_{22} & \dots & x_{2m} \\ \vdots & \vdots & \ddots & \vdots \\ \vdots & \vdots & \ddots & \vdots \\ x_{N1} & x_{N2} & \dots & x_{Nm} \end{matrix} \quad \mathbf{X}$$

$$\begin{matrix} w_1 \\ w_2 \\ \vdots \\ w_m \end{matrix} \quad \mathbf{w}$$

$$\begin{matrix} a_1 \\ a_2 \\ \vdots \\ a_p \end{matrix} \quad \mathbf{a}$$

$$\begin{matrix} f_1 \\ f_2 \\ \vdots \\ f_N \end{matrix} \quad \mathbf{f}$$

**Weight is an effective instrument!**

Absolute error

$$y_i = f_i + \varepsilon_i$$

Weight and variance

Relative error

$$y_i = f_i(1 + \varepsilon_i)$$

$$w_i^2 = \text{cov}(\varepsilon_i, \varepsilon_i) = \sigma_\varepsilon^2 = \text{Const}$$



# Data & Model Prepared for Fitter

Predictor

Response

Weight

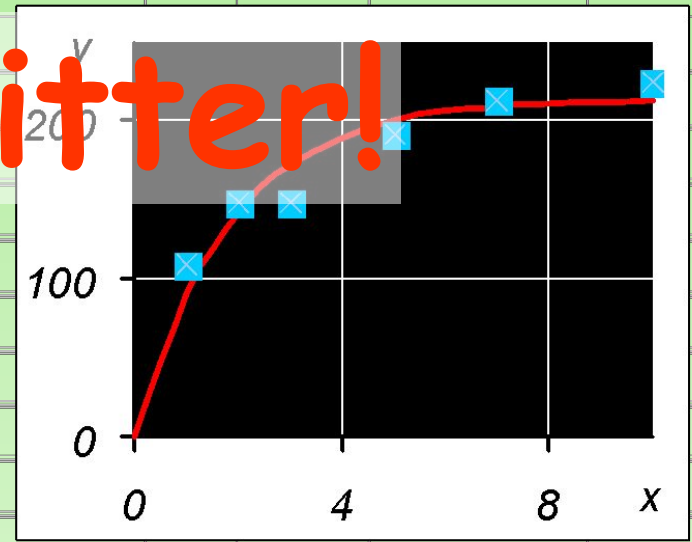
Values

Comment

	A	B	C	D	E	F	G	H	I	J	K	L	M
1													
2	<b>BoxBod Data</b>					<b>Parameters</b>							
3	<b>x</b>	<b>y</b>	<b>w</b>	<b>f</b>									
4	0		0	0.00									
5	1	109	1	90.11									
6	2	149	1	142.24									
7	3	149	1	172.41									
8	5	191	1	199.95									
9	7	213	1	209.17									
10	10	224	1	212.91									
11													

Apply Fitter!

'BoxBOD model  
 $y = a * [1 - \exp(-b * x)]$   
**a=?**  
**b=?**



Fitting

Parameters

Equation

# Objective Function $Q(a)$

Sum of squares

$$S(a) = \sum_{i=1}^N w_i^2 (y_i - f_i)^2 g_i^2$$

Bayesian term

Objective function  $Q$

is a sum of squares

Objective function

Parameter estimates

and may be more...

Weighted variance estimate

$$\hat{a} = \arg \min Q(a) \quad s^2 = \frac{S(\hat{a})}{N_f} \quad N_f = N - p$$

# Very Important Matrix $A$

Hesse's  
matrix

$$A_{\alpha\beta} = \frac{1}{2} \frac{\partial^2 Q(\mathbf{a})}{\partial a_\alpha \partial a_\beta}, \quad \alpha, \beta = 1, \dots, p$$

Gauss'  
approximation

$$A \approx V^t V \quad (X^t X \text{ in linear regression})$$

**Matrix  $A$  is the  
cause of troubles..**

Model  
derivatives

$$V_{\alpha i} = w_i \frac{\partial f(x_i, \mathbf{a})}{\partial a_\alpha} \quad \alpha = 1, \dots, p; \quad i = 1, \dots, N$$

Covariance  
matrix

$$C = s^2 A^{-1} = F^{-1}$$

$$F = s^{-2} A = C^{-1}$$



# Quality of Estimation

Covariances Matrix

$$\text{cov}(\hat{\mathbf{a}}, \hat{\mathbf{a}}) = \mathbf{C} = s^2 \mathbf{A}^{-1}$$

Deviations Vector

$$\text{dev}(\hat{a}_\alpha) = \sqrt{C_{\alpha\alpha}}$$

Correlations Matrix

$$\text{cor}(\hat{a}_\alpha, \hat{a}_\beta) = \frac{C_{\alpha\beta}}{\sqrt{C_{\alpha\alpha} C_{\beta\beta}}}$$

Final Objective Value

$$s^2 = \frac{S(\hat{\mathbf{a}})}{N_f} \quad N_f = N - p$$

08. Error Variance and Number Degrees of Freedom

**Matrix A is the measure of quality!**

# Search by Gradient Method

$$Q(a) \approx Q(a_n) + \mathbf{b}_n^t (a - a_n) + \frac{1}{2} (a - a_n)^t A (a - a_n)$$

$$\mathbf{a}_{n+1} = \mathbf{a}_n + A^+ \mathbf{b}_n$$

$$A^+ A = I$$

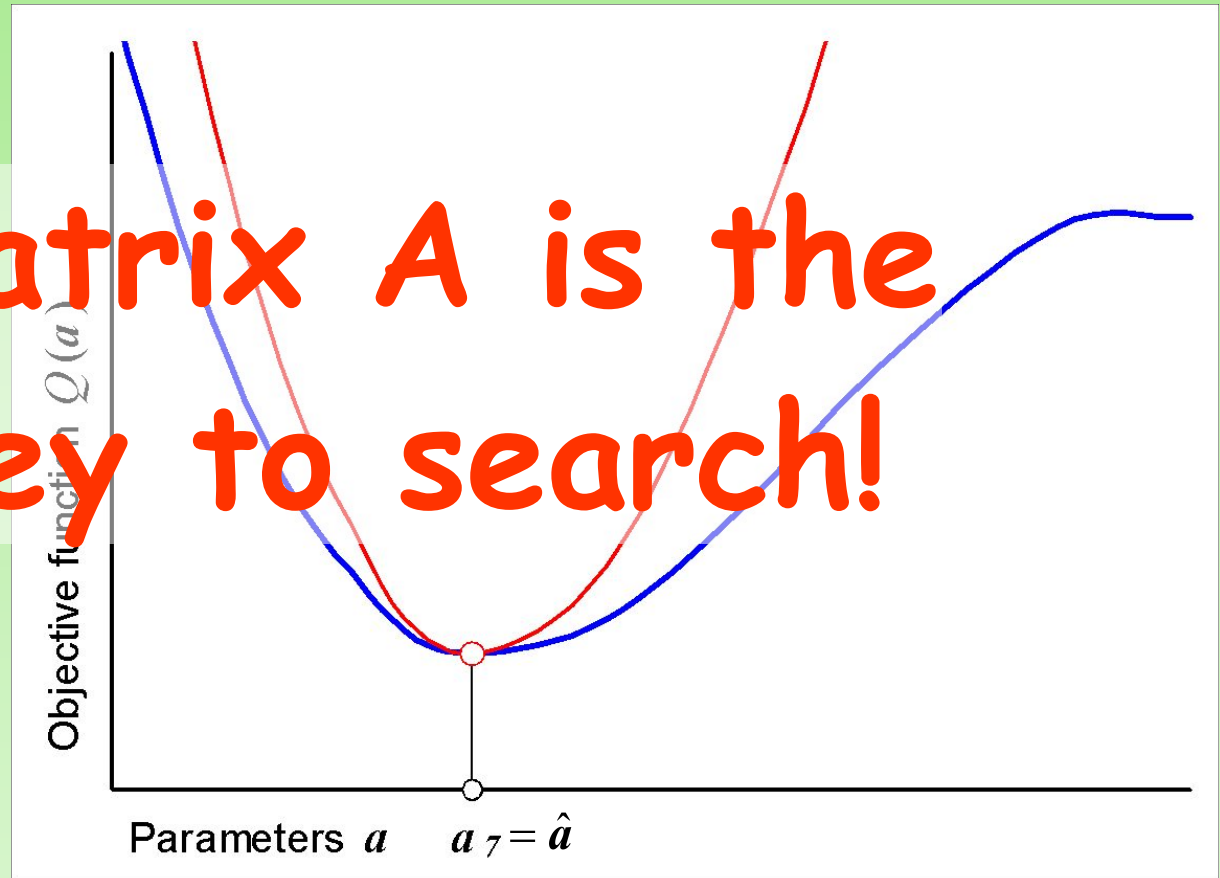
Search problems

Initial point  $\mathbf{a}_0$

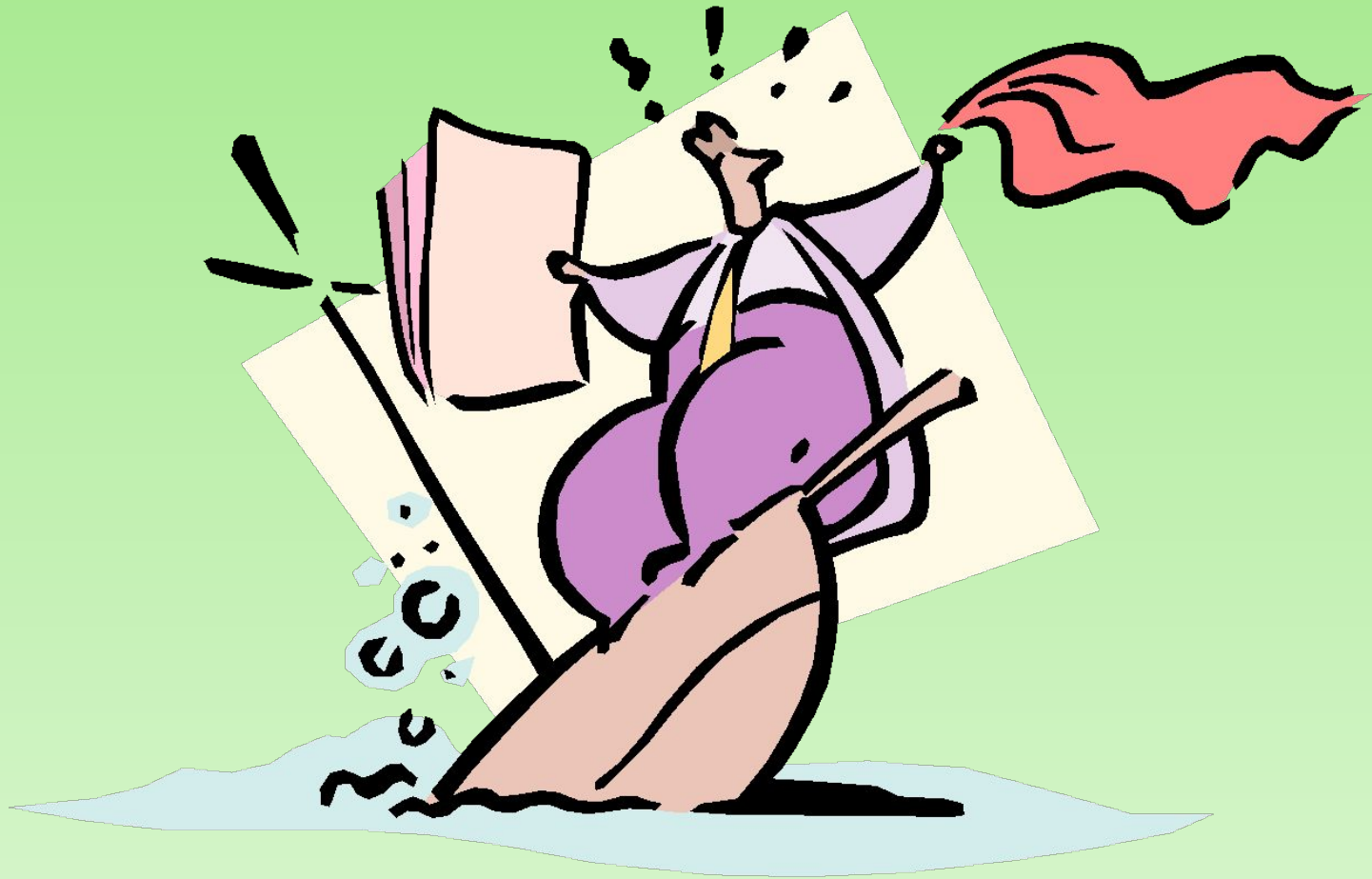
$$\det(A) \approx 0$$

Local minima

Matrix A is the  
key to search!



## 4. Multicollinearity



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# Multicollinearity: View

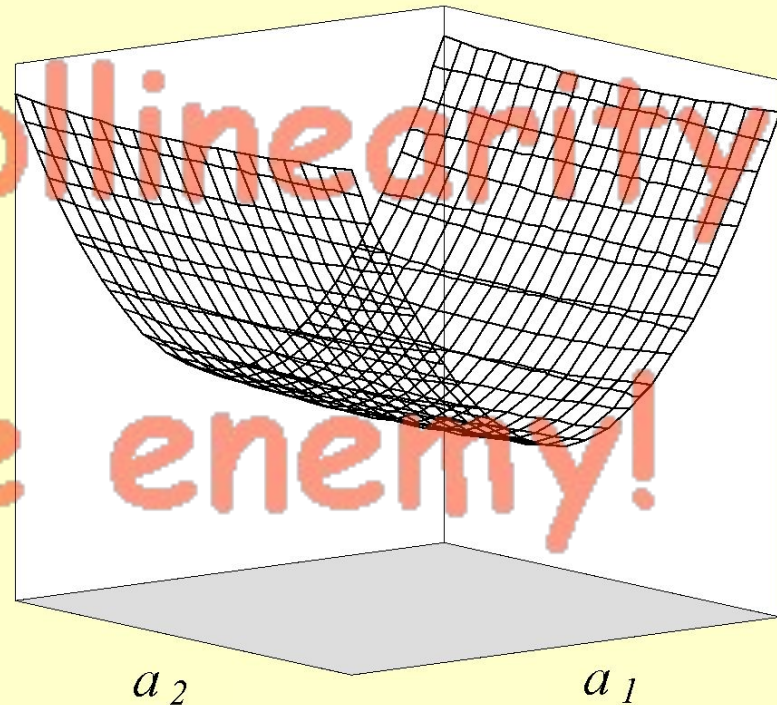
Multicollinearity is degradation of matrix  $A$

Spread of eigenvalues

$$N(A) = \log_{10} \left( \frac{\lambda_{\max}}{\lambda_{\min}} \right)$$

is a measure of  
degradation

Objective function  $Q(a)$



$$N(A) = 7$$

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# Multicollinearity: Source

“Hard” multicollinearity

$$y = a_1 a_2 x$$

“Soft” multicollinearity

$$y = a_1 \left(1 - e^{-a_2 x}\right) \approx a_1 a_2 x \text{ at } a_2 x \ll 1$$




# Data & Model Preprocessing

$$((a + b) + c) + d \neq a + (b + (c + d)) \quad \text{as} \quad 1 + 10^{-20} = 1$$

Representation of a number in computer with 64 bits

**This is a hard job!**



Target is to make Hesse matrix  $A$  regular and decrease  $N(A)$

**Release the Computer!**

Data Scaling

$$X \rightarrow mX$$

Data Centering

$$X \rightarrow X - X_0$$

Model Adjusting

$$a \rightarrow \phi(a) \quad x \rightarrow \psi(x) \quad y \rightarrow \chi(y)$$

M  
e  
a  
n  
s

(  
2)

# Example: The Arrhenius Law

Standard form

$$k \exp\left(-\frac{E}{RT}\right)$$

Adjusted form

$$\exp(a_1 - a_2 X)$$

Simple transformation  
with great effect!

Scaling & centering

$$X = \frac{1000}{T} - T_0 \quad \lambda_0 = \frac{1}{n} \sum_{i=1}^n \frac{1000}{T_i}$$

$$a_1 = 1000 \ln(k) - a_2 T_0 \quad a_2 = \frac{E}{1000R}$$

Adjusting

$$k \approx 10^{11} \quad E \approx 10^4$$

$$a_1 \approx 1 \quad a_2 \approx 10$$

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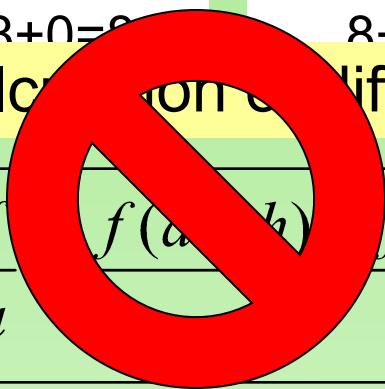
$$N(A) = 20$$

$$N(A) = 2$$

# Derivative Calculation and Precision


$N(A)$	$A^{-1}$	$y=f(a,x)$	$0=f(y,a,x)$	$dy/dx=f(y,a,x)$
10	$10+2=12$	$12+0=12$	$12+2=14$	$14+2=16$
6	$6+2=8$	$8+0=8$	$8+2=10$	$10+2=12$

1) Numerical calculation of difference derivatives

$$\frac{\partial f}{\partial a} \approx \frac{f(a+h) - f(a)}{h}$$


2) Auto calculation of analytical derivatives

$$f = \exp(-a * t)$$

$$df/da = -t * \exp(-a * t)$$




# 5. Prediction



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# Reliable Prediction

Estimate of response

$$\hat{y} = f(\mathbf{x}, \hat{\mathbf{a}})$$

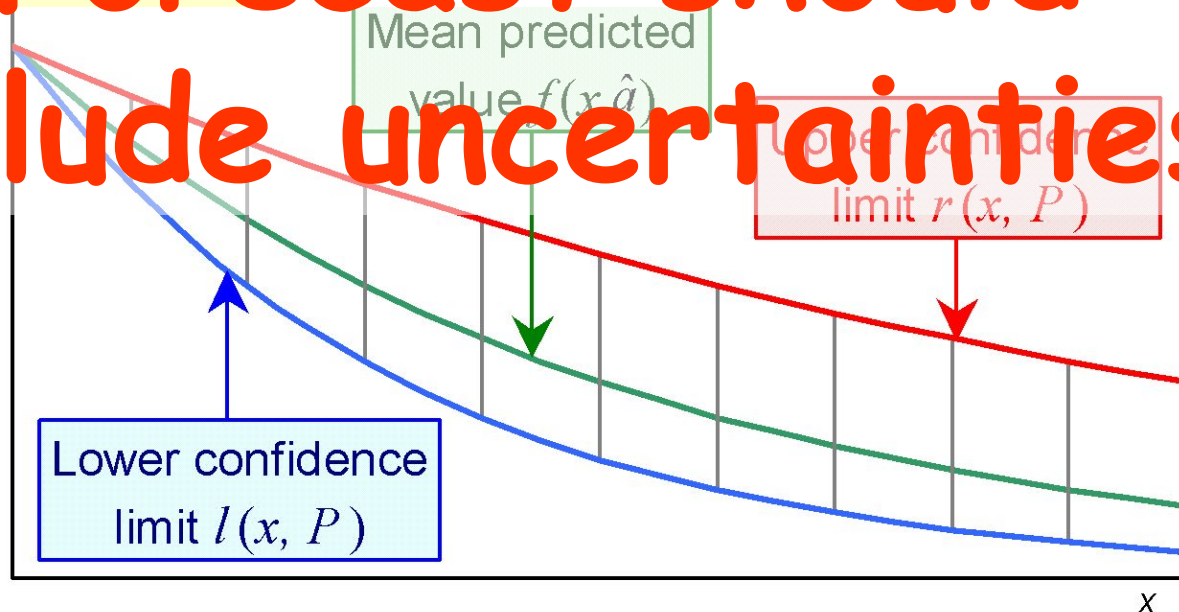
Confidence limits

$$\text{Prob}\{l(\mathbf{x}, P) < f(\mathbf{x}, \mathbf{a}) < r(\mathbf{x}, P)\} \geq P$$

$$r(\mathbf{x}, P) = f(\mathbf{x}, \hat{\mathbf{a}}) + g(P)\sqrt{\mathbf{v}^t \mathbf{C} \mathbf{v}}$$

Linearization

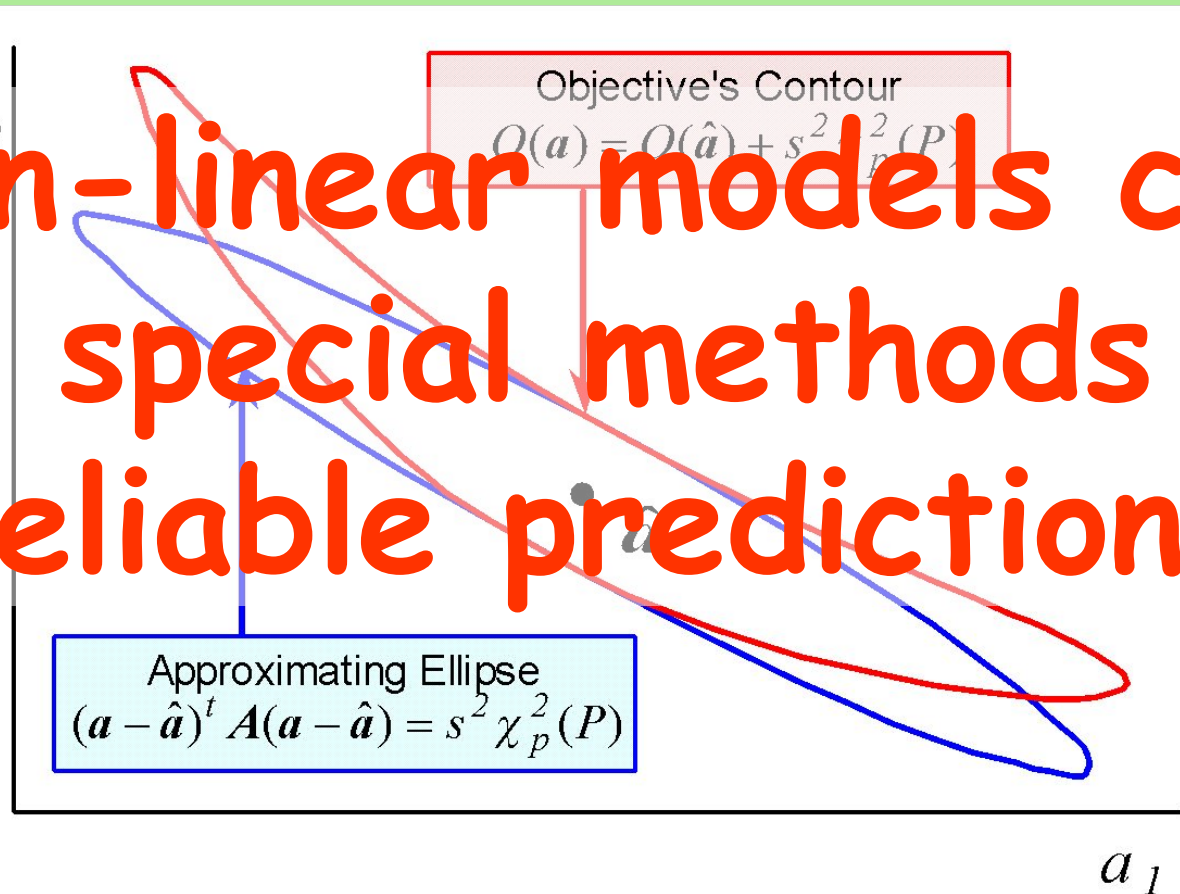
**Forecast should include uncertainties!**



# Nonlinearity and Simulation

$$\mathbf{a}^* \sim N(\hat{\mathbf{a}}, \mathbf{C}) \rightarrow \mathbf{a}_1^*, \dots, \mathbf{a}_M^* \rightarrow f_1^*, \dots, f_M^* \rightarrow r(P, \mathbf{x})$$

**Non-linear models call for special methods of reliable prediction!**



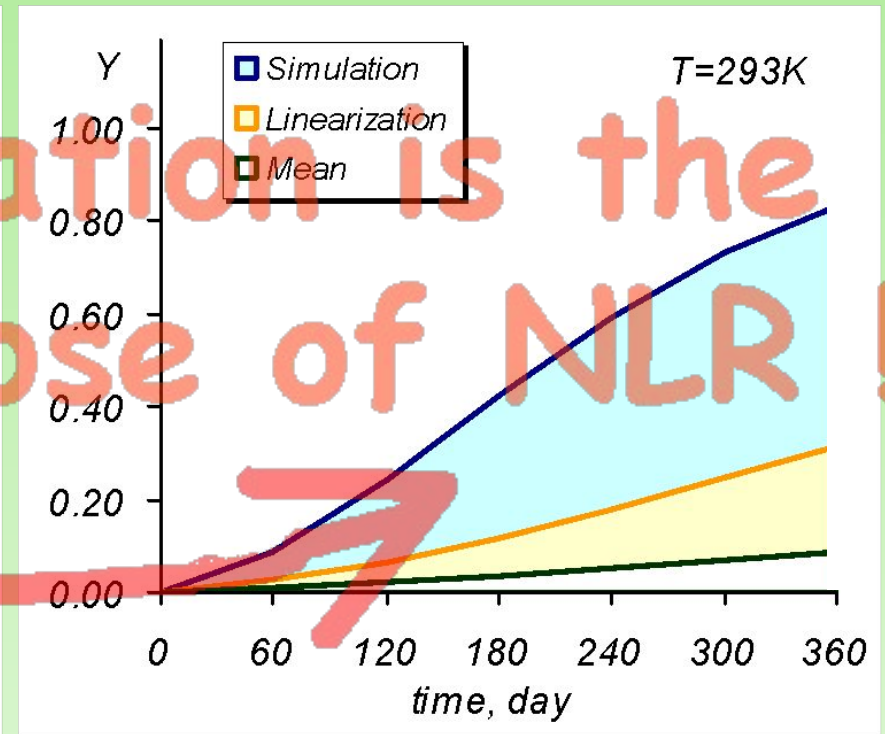
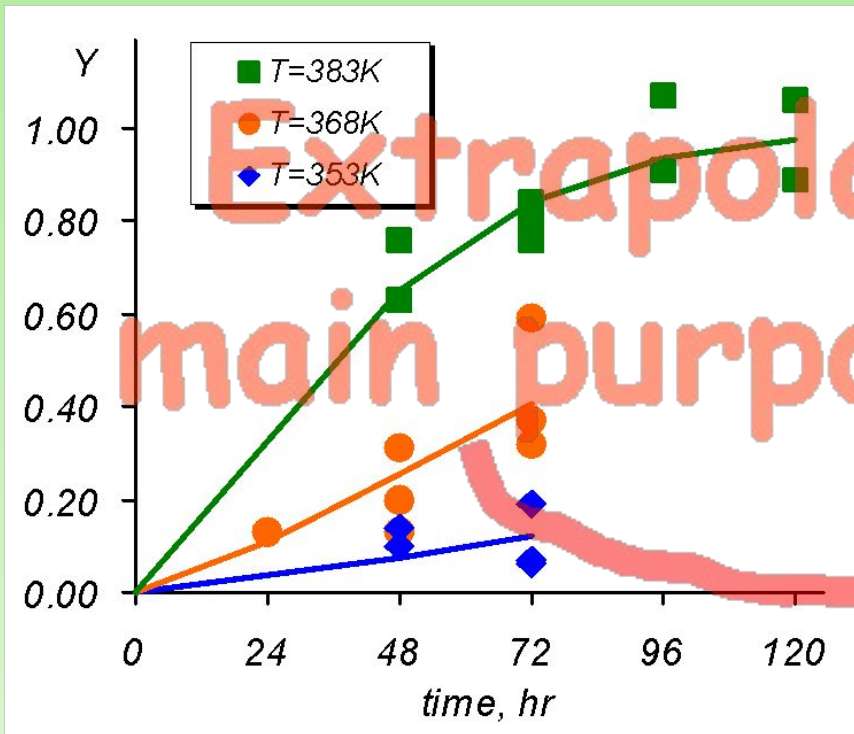
# Prediction: Example

Model of  
rubber aging

$$Y = 1 - e^{-(kt)^a}, \quad k = e^{k_0 - \frac{E}{RT}}$$

Accelerated aging tests

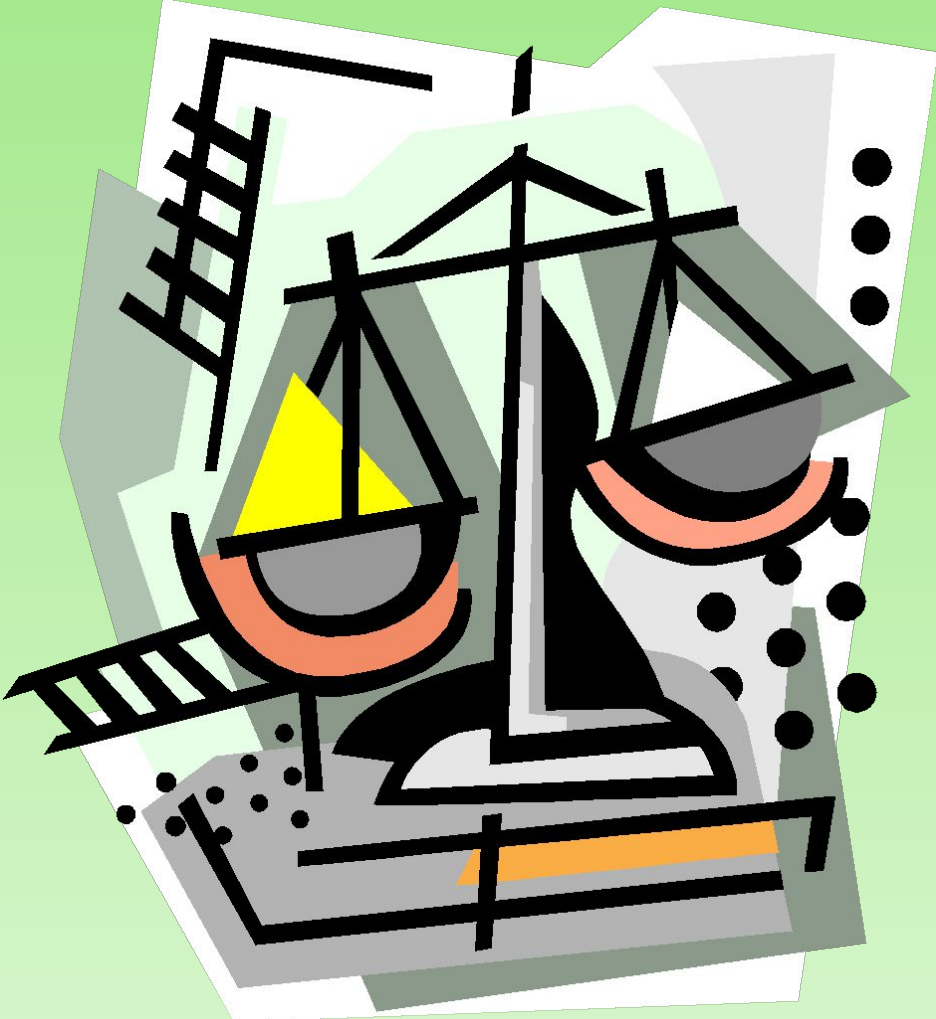
Upper confidence limits



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# 6. Testing



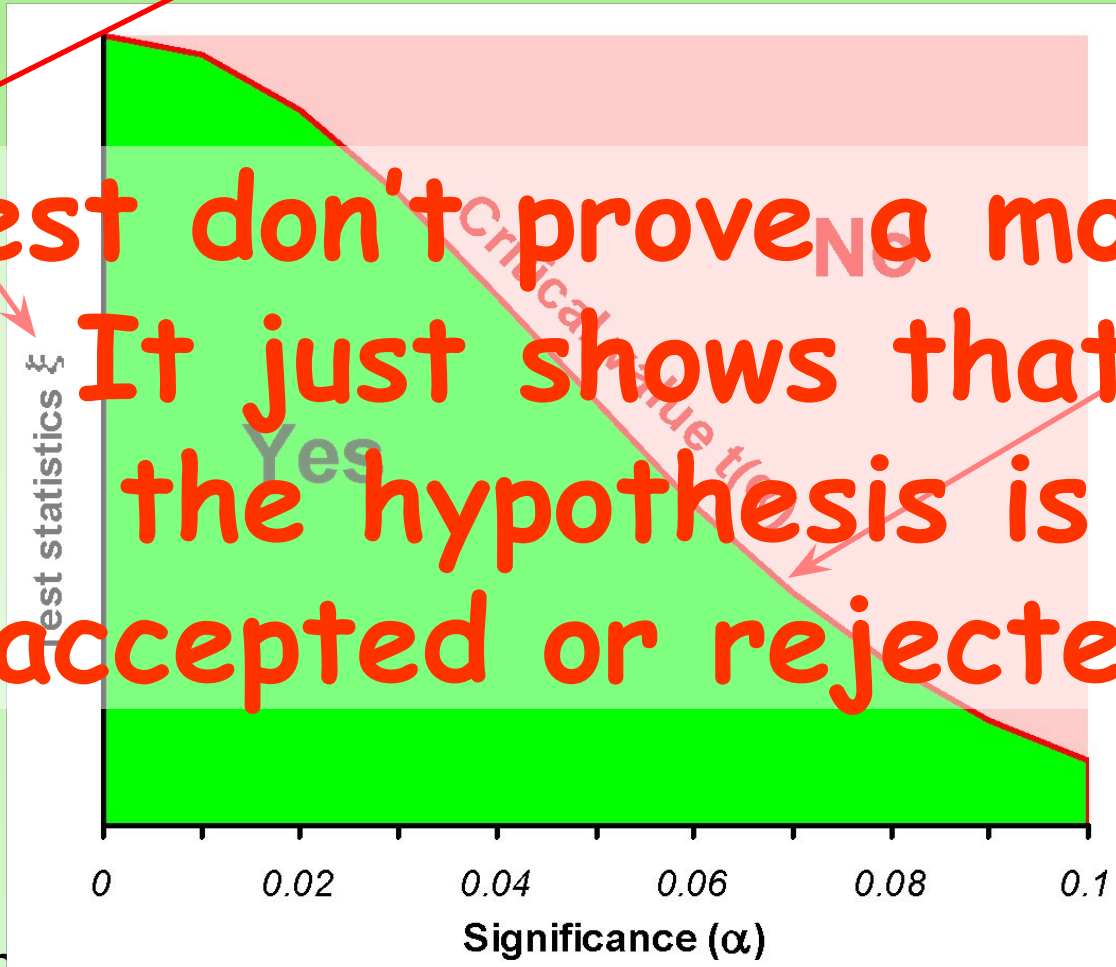
# Hypotheses Testing

Test statistics  $\xi$  is compared with critical value  $t(\alpha)$

From experiment

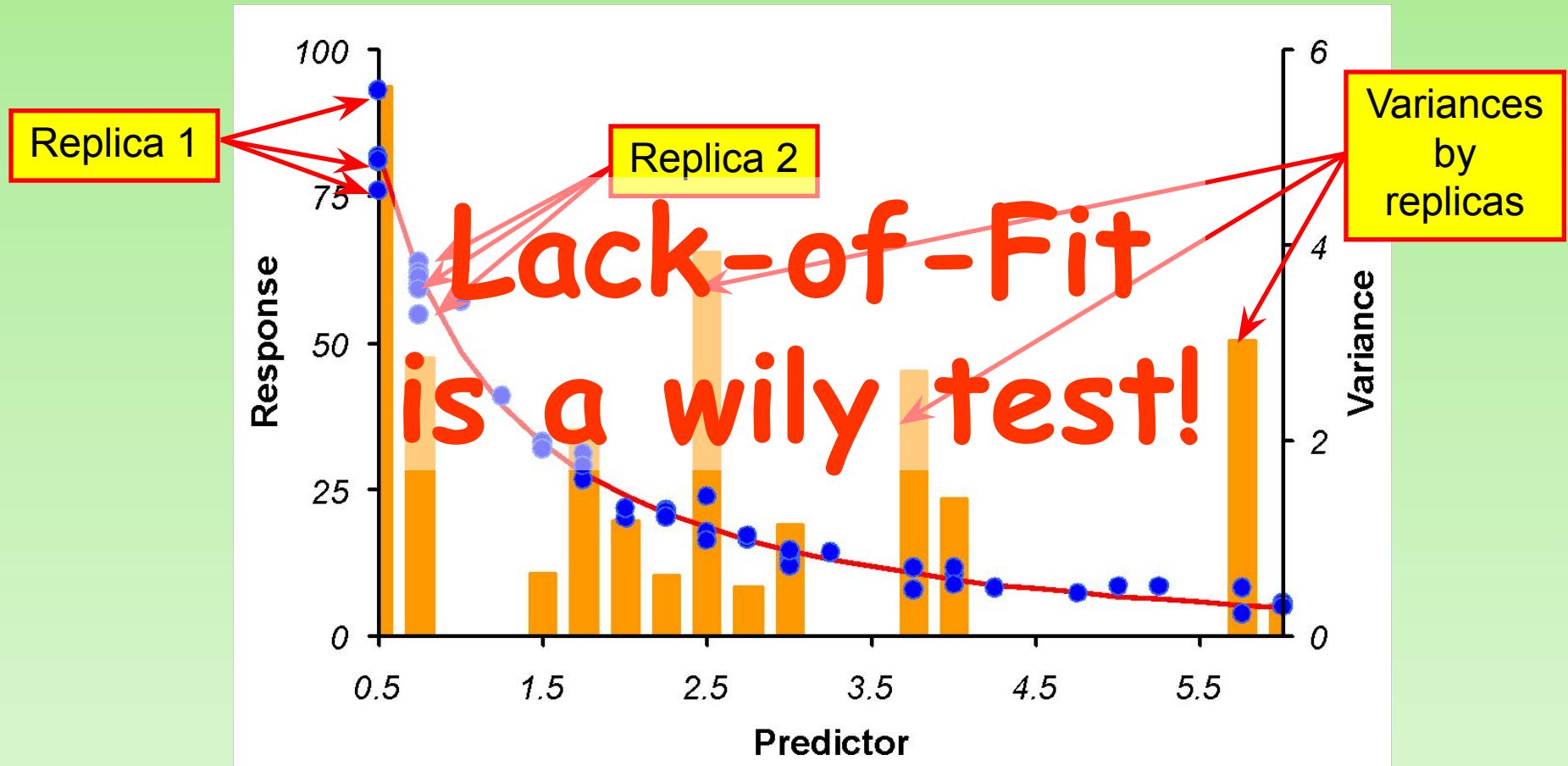
From theory

**Test don't prove a model!  
It just shows that  
the hypothesis is  
accepted or rejected!**



# Lack-of-Fit and Variances Tests

These hypotheses are based on variances and they can't be tested without **replicas**!



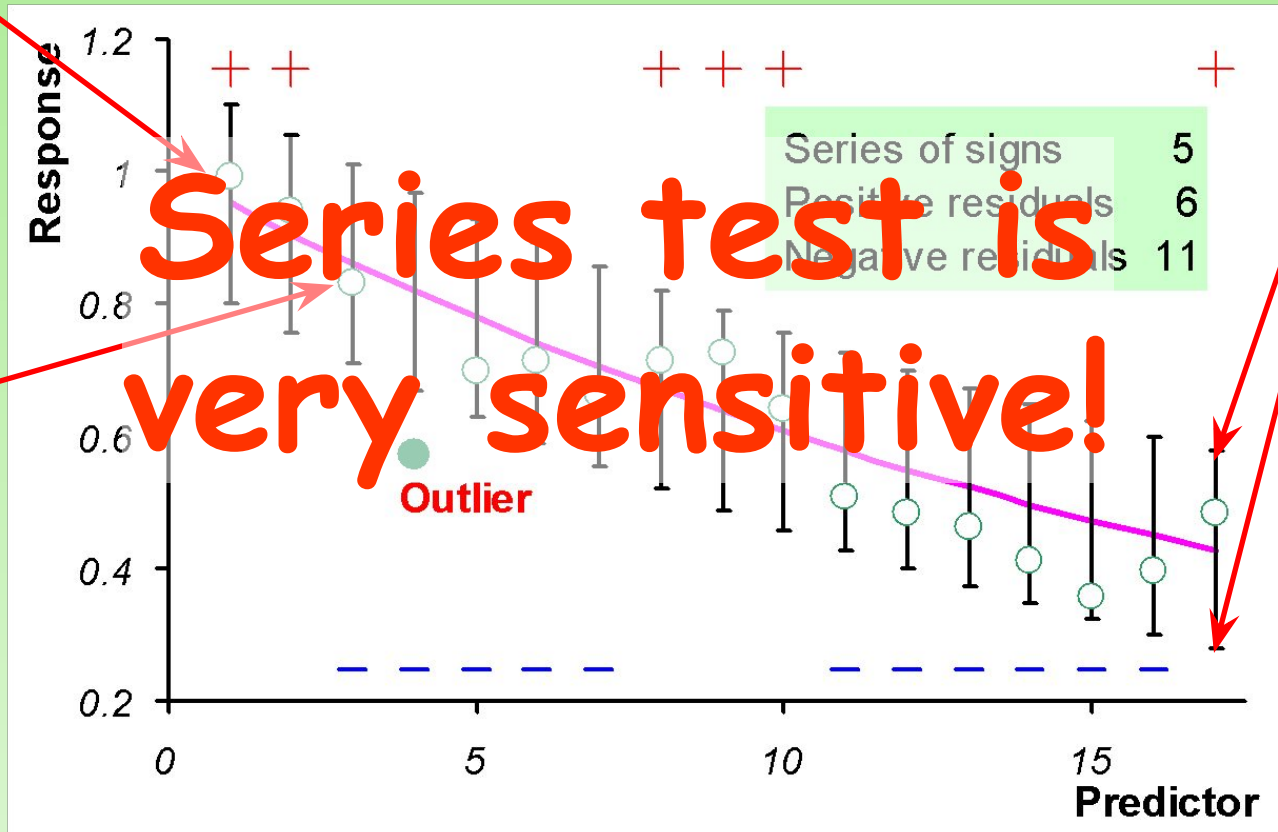
# Outlier and Series Tests

These hypotheses are based on residuals and they can be tested without replicas

Positive residual

Negative residual

Acceptable deviation



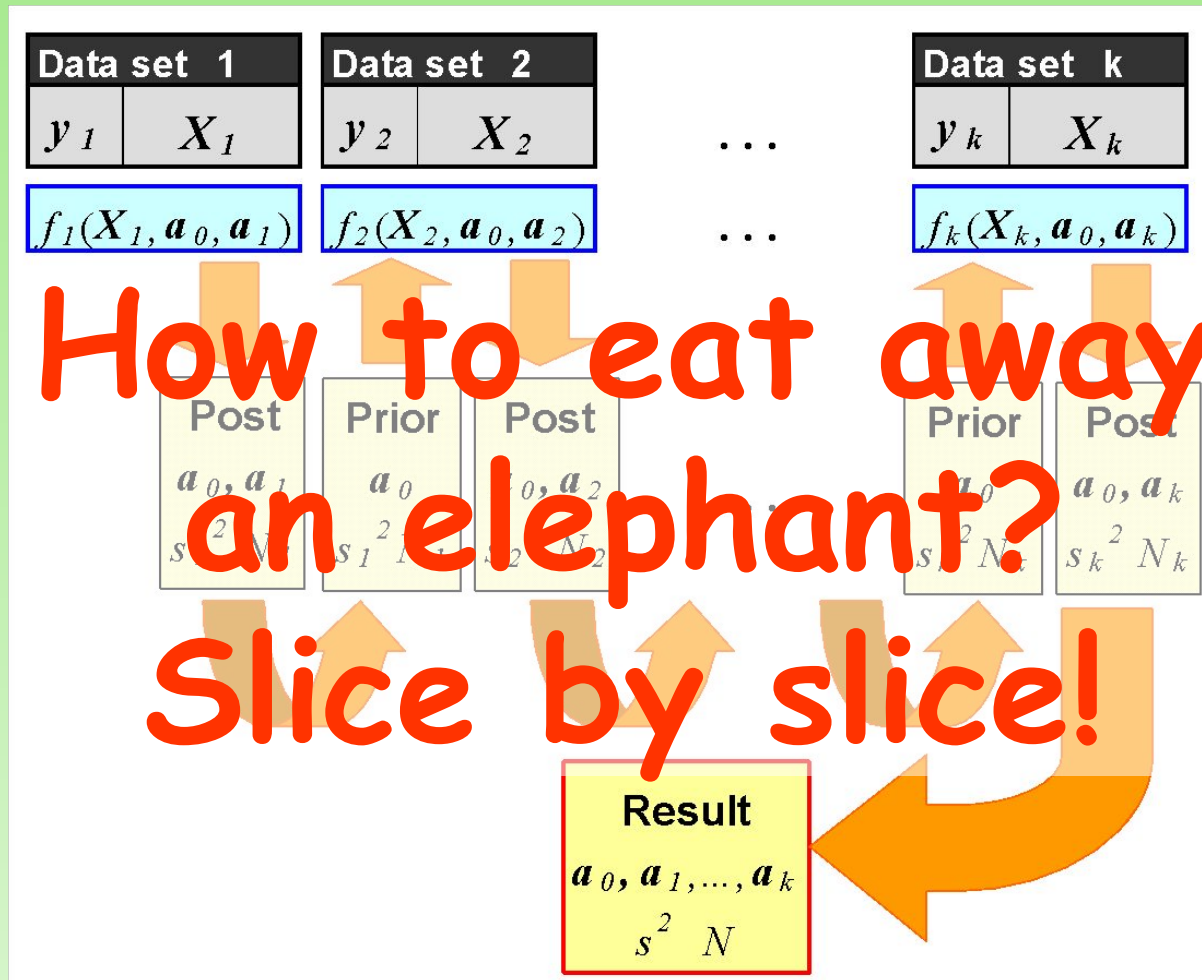


# 7. Bayesian Estimation



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# Bayesian Estimation



# Posterior and Prior Information. Type I

Posterior Information

Prior Information

$\hat{a}$

Parameter estimates

Prior parameter values  $b$

**The same error in each portion of data!**

Matrix  $F$

Recalculated matrix  $H$

Error variance  $s^2$

Prior variance value  $s_0^2$

NDF  $N_f$

$$Q(a) = S(a) + B(a) \quad \text{Prior NDF } N_0$$

$$B(a) = s_0^2 (N_0 + R(a)) \quad R(a) = (a - b)^t H (a - b)$$

Objective Function

# Posterior and Prior Information. Type II

Posterior Information

Prior Information

$\hat{a}$

Parameter estimates

Prior parameter values  $b$

Different errors in

each portion of data!

$$Q(a) = S(a)B(a)$$

Objective function

$$B(a) = \exp\left(\frac{R(a)}{N}\right) \quad R(a) = (a - b)^t H(a - b)$$

# 8. Conclusions

Mysterious Nature

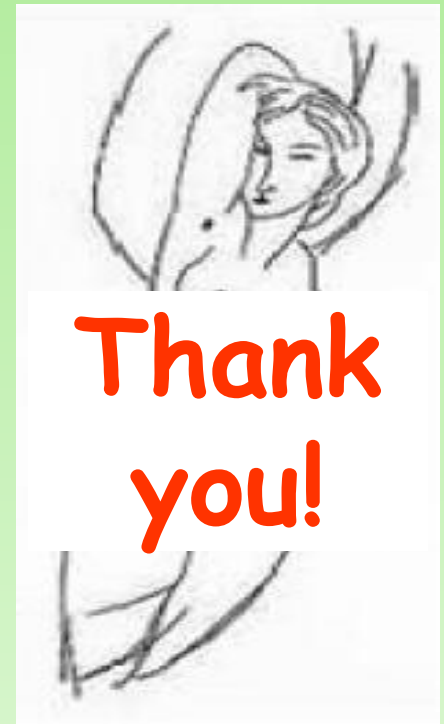
LR Model



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NLR Model



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