

Lecture 2: Metrics to Evaluate Systems

- Topics: Metrics: power, reliability, cost, benchmark suites, performance equation, summarizing performance with AM, GM, HM
- Sign up for the class mailing list!
 - Video 1: Using AM as a performance summary
 - Video 2: GM, Performance Equation
 - Video 3: AM vs. HM vs. GM

Power Consumption Trends

- Dyn power \propto activity x capacitance x voltage² x frequency
- Capacitance per transistor and voltage are decreasing, but number of transistors is increasing at a faster rate; hence clock frequency must be kept steady
- Leakage power is also rising; is a function of transistor count, leakage current, and supply voltage
- Power consumption is already between 100-150W in high-performance processors today
- Energy = power x time = (dynpower + lkgpower) x time

Problem 1

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$$\begin{aligned}\text{Total power} &= \text{dynamic power} + \text{leakage power} \\ &= 80\text{W} \times 50\% + 20\text{W} \\ &= 60\text{W}\end{aligned}$$

Power Vs. Energy

- Energy is the ultimate metric: it tells us the true “cost” of performing a fixed task
- Power (energy/time) poses constraints; can only work fast enough to max out the power delivery or cooling solution
- If processor A consumes 1.2x the power of processor B, but finishes the task in 30% less time, its relative energy is $1.2 \times 0.7 = 0.84$; Proc-A is better, assuming that 1.2x power can be supported by the system

Problem 2

- If processor A consumes 1.4x the power of processor B, but finishes the task in 20% less time, which processor would you pick:
 - (a) if you were constrained by power delivery constraints?
 - (b) if you were trying to minimize energy per operation?
 - (c) if you were trying to minimize response times?

Problem 2

- If processor A consumes 1.4x the power of processor B, but finishes the task in 20% less time, which processor would you pick:
 - (a) if you were constrained by power delivery constraints?
Proc-B
 - (b) if you were trying to minimize energy per operation?
Proc-A is $1.4 \times 0.8 = 1.12$ times the energy of Proc-B
 - (c) if you were trying to minimize response times?
Proc-A is faster, but we could scale up the frequency (and power) of Proc-B and match Proc-A's response time (while still doing better in terms of power and energy)

Reducing Power and Energy

- Can gate off transistors that are inactive (reduces leakage)
- Design for typical case and throttle down when activity exceeds a threshold
- DFS: Dynamic frequency scaling -- only reduces frequency and dynamic power, but hurts energy
- DVFS: Dynamic voltage and frequency scaling – can reduce voltage and frequency by (say) 10%; can slow a program by (say) 8%, but reduce dynamic power by 27%, reduce total power by (say) 23%, reduce total energy by 17%
(Note: voltage drop \square slow transistor \square freq drop)

Problem 3

- Processor-A at 3 GHz consumes 80 W of dynamic power and 20 W of static power. It completes a program in 20 seconds.
What is the energy consumption if I scale frequency down by 20%?

What is the energy consumption if I scale frequency and voltage down by 20%?

Problem 3

- Processor-A at 3 GHz consumes 80 W of dynamic power and 20 W of static power. It completes a program in 20 seconds.

What is the energy consumption if I scale frequency down by 20%?

New dynamic power = 64W; New static power = 20W

New execution time = 25 secs (assuming CPU-bound)

Energy = 84 W x 25 secs = 2100 Joules

What is the energy consumption if I scale frequency and voltage down by 20%?

New DP = 41W; New static power = 16W;

New exec time = 25 secs; Energy = 1425 Joules

Other Technology Trends

- DRAM density increases by 40-60% per year, latency has reduced by 33% in 10 years (the memory wall!), bandwidth improves twice as fast as latency decreases
- Disk density improves by 100% every year, latency improvement similar to DRAM
- Emergence of NVRAM technologies that can provide a bridge between DRAM and hard disk drives
- Also, growing concerns over reliability (since transistors are smaller, operating at low voltages, and there are so many of them)

Defining Reliability and Availability

- A system toggles between
 - Service accomplishment: service matches specifications
 - Service interruption: services deviates from specs
- The toggle is caused by *failures* and *restorations*
- Reliability measures continuous service accomplishment and is usually expressed as mean time to failure (MTTF)
- Availability measures fraction of time that service matches specifications, expressed as $MTTF / (MTTF + MTTR)$

Cost

- Cost is determined by many factors: volume, yield, manufacturing maturity, processing steps, etc.
- One important determinant: area of the chip
- Small area \square more chips per wafer
- Small area \square one defect leads us to discard a small-area chip, i.e., yield goes up
- Roughly speaking, half the area \square one-third the cost

Measuring Performance

- Two primary metrics: wall clock time (response time for a program) and throughput (jobs performed in unit time)
- To optimize throughput, must ensure that there is minimal waste of resources

Benchmark Suites

- Performance is measured with benchmark suites: a collection of programs that are likely relevant to the user
 - SPEC CPU 2006: cpu-oriented programs (for desktops)
 - SPECweb, TPC: throughput-oriented (for servers)
 - EEMBC: for embedded processors/workloads

Summarizing Performance

- Consider 25 programs from a benchmark set – how do we capture the behavior of all 25 programs with a single number?

	P1	P2	P3
Sys-A	10	8	25
Sys-B	12	9	20
Sys-C	8	8	30

- Sum of execution times (AM)
- Sum of weighted execution times (AM)
- Geometric mean of execution times (GM)

Problem 4

- Consider 3 programs from a benchmark set. Assume that system-A is the reference machine. How does the performance of system-C compare against that of system-B (for all 3 metrics)?

	P1	P2	P3
Sys-A	5	10	20
Sys-B	6	8	18
Sys-C	7	9	14

- Sum of execution times (AM)
- Sum of weighted execution times (AM)
- Geometric mean of execution times (GM)

Problem 4

- Consider 3 programs from a benchmark set. Assume that system-A is the reference machine. How does the performance of system-C compare against that of system-B (for all 3 metrics)?

	P1	P2	P3	S.E.T	S.W.E.T	GM
Sys-A	5	10	20	35	3	10
Sys-B	6	8	18	32	2.9	9.5
Sys-C	7	9	14	30	3	9.6

- Relative to C, B provides a speedup of 1.03 (S.W.E.T) or 1.01 (GM) or 0.94 (S.E.T)
- Relative to C, B reduces execution time by 3.3% (S.W.E.T) or 1% (GM) or -6.7% (S.E.T)

Sum of Weighted Exec Times – Example

- We fixed a reference machine X and ran 4 programs A, B, C, D on it such that each program ran for 1 second
- The exact same workload (the four programs execute the same number of instructions that they did on machine X) is run on a new machine Y and the execution times for each program are 0.8, 1.1, 0.5, 2
- With AM of normalized execution times, we can conclude that Y is 1.1 times slower than X – perhaps, not for all workloads, but definitely for one specific workload (where all programs run on the ref-machine for an equal #cycles)

GM Example

	Computer-A	Computer-B	Computer-C
P1	1 sec	10 secs	20 secs
P2	1000 secs	100 secs	20 secs

Conclusion with GMs: (i) A=B
(ii) C is ~1.6 times faster

- For (i) to be true, P1 must occur 100 times for every occurrence of P2
- With the above assumption, (ii) is no longer true

Hence, GM can lead to inconsistencies

Summarizing Performance

- GM: does not require a reference machine, but does not predict performance very well
 - So we multiplied execution times and determined that sys-A is 1.2x faster...but on what workload?
- AM: does predict performance for a specific workload, but that workload was determined by executing programs on a reference machine
 - Every year or so, the reference machine will have to be updated

CPU Performance Equation

- Clock cycle time = $1 / \text{clock speed}$
- CPU time = clock cycle time x cycles per instruction x number of instructions
- Influencing factors for each:
 - clock cycle time: technology and pipeline
 - CPI: architecture and instruction set design
 - instruction count: instruction set design and compiler
- CPI (cycles per instruction) or IPC (instructions per cycle) can not be accurately estimated analytically

Problem 5

- My new laptop has an IPC that is 20% worse than my old laptop. It has a clock speed that is 30% higher than the old laptop. I'm running the same binaries on both machines. What speedup is my new laptop providing?

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Exec time = cycle time * CPI * instrs

Perf = clock speed * IPC / instrs

Speedup = new perf / old perf

= new clock speed * new IPC / old clock speed * old IPC

= 1.3 * 0.8 = 1.04

An Alternative Perspective - I

- Each program is assumed to run for an equal number of cycles, so we're fair to each program
- The number of instructions executed per cycle is a measure of how well a program is doing on a system
- The appropriate summary measure is sum of IPCs or
AM of IPCs = $\frac{1.2 \text{ instr}}{\text{cyc}} + \frac{1.8 \text{ instr}}{\text{cyc}} + \frac{0.5 \text{ instr}}{\text{cyc}}$
- This measure implicitly assumes that 1 instr in prog-A has the same importance as 1 instr in prog-B

An Alternative Perspective - II

- Each program is assumed to run for an equal number of instructions, so we're fair to each program
- The number of cycles required per instruction is a measure of how well a program is doing on a system
- The appropriate summary measure is sum of CPIs or
AM of CPIs = $\frac{0.8 \text{ cyc}}{\text{instr}} + \frac{0.6 \text{ cyc}}{\text{instr}} + \frac{2.0 \text{ cyc}}{\text{instr}}$
- This measure implicitly assumes that 1 instr in prog-A has the same importance as 1 instr in prog-B

AM and HM

- Note that $AM \text{ of IPCs} = 1 / HM \text{ of CPIs}$ and
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- So if the programs in a benchmark suite are weighted such that each runs for an equal number of cycles, then AM of IPCs or HM of CPIs are both appropriate measures
- If the programs in a benchmark suite are weighted such that each runs for an equal number of instructions, then AM of CPIs or HM of IPCs are both appropriate measures

AM vs. GM

- GM of IPCs = $1 / \text{GM of CPIs}$
- AM of IPCs represents thruput for a workload where each program runs sequentially for 1 cycle each; but high-IPC programs contribute more to the AM
- GM of IPCs does not represent run-time for any real workload (what does it mean to multiply instructions?); but every program's IPC contributes equally to the final measure

Problem 6

- My new laptop has a clock speed that is 30% higher than the old laptop. I'm running the same binaries on both machines. Their IPCs are listed below. I run the binaries such that each binary gets an equal share of CPU time. What speedup is my new laptop providing?

	P1	P2	P3
Old-IPC	1.2	1.6	2.0
New-IPC	1.6	1.6	1.6

Problem 6

- My new laptop has a clock speed that is 30% higher than the old laptop. I'm running the same binaries on both machines. Their IPCs are listed below. I run the binaries such that each binary gets an equal share of CPU time. What speedup is my new laptop providing?

	P1	P2	P3	AM	GM
Old-IPC	1.2	1.6	2.0	1.6	1.57
New-IPC	1.6	1.6	1.6	1.6	1.6

AM of IPCs is the right measure. Could have also used GM. Speedup with AM would be 1.3.

Speedup Vs. Percentage

- “Speedup” is a ratio = old exec time / new exec time
- “Improvement”, “Increase”, “Decrease” usually refer to percentage relative to the baseline
= (new perf – old perf) / old perf
- A program ran in 100 seconds on my old laptop and in 70 seconds on my new laptop
 - What is the speedup?
 - What is the percentage increase in performance?
 - What is the reduction in execution time?

Speedup Vs. Percentage

- “Speedup” is a ratio = old exec time / new exec time
- “Improvement”, “Increase”, “Decrease” usually refer to percentage relative to the baseline
= (new perf – old perf) / old perf
- A program ran in 100 seconds on my old laptop and in 70 seconds on my new laptop
 - What is the speedup? $(1/70) / (1/100) = 1.42$
 - What is the percentage increase in performance?
 $(1/70 - 1/100) / (1/100) = 42\%$
 - What is the reduction in execution time? 30%

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