

$\int_{R} \frac{\partial \theta}{\partial \theta} \int_{R} T(x) f(x, \theta) dx$ Life without numbers

 $-\ln f_{a,\sigma^2}(\xi_1) = \frac{(\xi_1 - a)}{\sigma^2}$

 $f(\mathbf{x}) \cdot \frac{\partial}{\partial \theta} f(\mathbf{x}, \theta) d\mathbf{x} = \mathbf{M} \left(\mathbf{x}, \theta \right) d\mathbf{x}$



It is believed that the early shepherds would call their sheep by name in order to determine if any of them were missing. There were no number names at first; so counters were used. For counters man used sticks or his fingers .The early shepherd learned that, instead of calling his sheep by name, he could lay aside a pebble for each sheep as he led them to the corral for the night and thus learned if any one of them had been lost.



$(S) = \frac{\partial}{\partial \theta} \int_{\mathbf{R}_n} T(x) f(x),$

$-\ln f_{a,\sigma^2}(\xi_1) = \frac{(\xi_1 - a)}{\sigma^2}$

 $f(\mathbf{x}) \cdot \frac{\partial}{\partial \theta} f(\mathbf{x}, \theta) d\mathbf{x} = \mathbf{M} \Big(\mathbf{x} \Big) d\mathbf{x} = \mathbf{M} \Big(\mathbf{x} \Big) \mathbf{x} \Big) \mathbf{x} = \mathbf{M} \Big(\mathbf{x} \Big) \mathbf{x} + \mathbf{M} \Big(\mathbf{x} \Big) \mathbf{x} + \mathbf{M} \Big) \mathbf{x} = \mathbf{M} \Big(\mathbf{x} \Big) \mathbf{x} + \mathbf{M} \Big) \mathbf{x} = \mathbf{M} \Big(\mathbf{x} \Big) \mathbf{x} + \mathbf{M} \Big) \mathbf{x} = \mathbf{M} \Big(\mathbf{x} \Big) \mathbf{x} + \mathbf{M} \Big) \mathbf{x} = \mathbf{M} \Big(\mathbf{x} \Big) \mathbf{x} + \mathbf{M} \Big) \mathbf{x} = \mathbf{M} \Big(\mathbf{x} \Big) \mathbf{x} + \mathbf{M} \Big) \mathbf{x} = \mathbf{M} \Big(\mathbf{x} \Big) \mathbf{x} + \mathbf{M} \Big) \mathbf{x} = \mathbf{M} \Big(\mathbf{x} \Big) \mathbf{x} + \mathbf{M} \Big) \mathbf{x} = \mathbf{M} \Big(\mathbf{x} \Big) \mathbf{x} + \mathbf{M} \Big) \mathbf{x} = \mathbf{M} \Big(\mathbf{x} \Big) \mathbf{x} + \mathbf{M} \Big) \mathbf{x} = \mathbf{M} \Big(\mathbf{x} \Big) \mathbf{x} + \mathbf{M} \Big) \mathbf{x} = \mathbf{M} \Big(\mathbf{x} \Big) \mathbf{x} + \mathbf{M} \Big) \mathbf{x} = \mathbf{M} \Big(\mathbf{x} \Big) \mathbf{x} + \mathbf{M} \Big) \mathbf{x} = \mathbf{M} \Big(\mathbf{x} \Big) \mathbf{x} + \mathbf{M} \Big) \mathbf{x} = \mathbf{M} \Big(\mathbf{x} \Big) \mathbf{x} + \mathbf{M} \Big) \mathbf{x} = \mathbf{M} \Big(\mathbf{x} \Big) \mathbf{x} + \mathbf{M} \Big) \mathbf{x} = \mathbf{M} \Big(\mathbf{x} \Big) \mathbf{x} + \mathbf{M} \Big) \mathbf{x} = \mathbf{M} \Big(\mathbf{x} \Big) \mathbf{x} + \mathbf{M} \Big) \mathbf{x} = \mathbf{M} \Big(\mathbf{x} \Big) \mathbf{x} + \mathbf{M} \Big) \mathbf{x} = \mathbf{M} \Big(\mathbf{x} \Big) \mathbf{x} + \mathbf{M} \Big) \mathbf{x} = \mathbf{M} \Big(\mathbf{x} \Big) \mathbf{x} + \mathbf{M} \Big) \mathbf{x} = \mathbf{M} \Big(\mathbf{x} \Big) \mathbf{x} + \mathbf{M} \Big) \mathbf{x} = \mathbf{M} \Big(\mathbf{x} \Big) \mathbf{x} + \mathbf{M} \Big) \mathbf{x} = \mathbf{M} \Big) \mathbf{x} = \mathbf{M} \Big) \mathbf{x} + \mathbf{M} \Big) \mathbf{x} = \mathbf{M} \Big) \mathbf{M} \Big) \mathbf{x} = \mathbf{M} \Big) \mathbf{M} \Big) \mathbf{x} = \mathbf{M} \Big) \mathbf{M} \Big) \mathbf$

 $f(\mathbf{x}) \cdot \left(\frac{\partial}{\partial \theta} \ln L(\mathbf{x}, \theta)\right)$

Archimedes

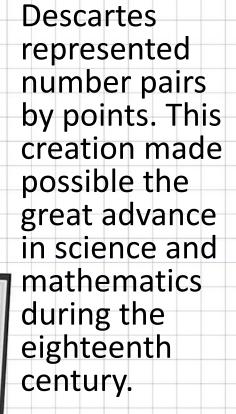
The greatest mathematicians of recorded history was the Greek Archimedes who developed a dynamic mathematics which could be applied to the laws of nature.

 $S = \frac{\partial}{\partial \theta} \int_{\mathbf{R}} T(x) f(x)$

 $-\ln f_{a,\sigma^2}(\xi_1) = \frac{(\xi_1 - a)}{\sigma^2}$

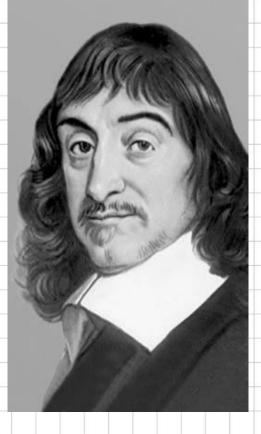
 $f(\mathbf{x}) \cdot \frac{\partial}{\partial \theta} f(\mathbf{x}, \theta) d\mathbf{x} = \mathbf{M}$

 $(\mathbf{x}) \cdot \left(\frac{\partial}{\partial \theta} \ln L(\mathbf{x}, \theta)\right)$



Rene

Rene Descartes



Isaac Newton

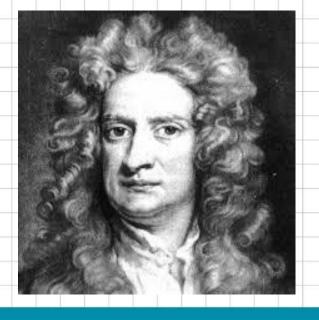
Newton was one of the inventors of the calculus which is now studied by college students who are seriously interested in mathematics or physical science.

 $f(x) \cdot \frac{\partial}{\partial \theta} f(x, \theta) dx = M \int_{T} \frac{dt}{dt} = M \int_{T} \frac{dt}{$

 $\int = \frac{\partial}{\partial \theta} \int_{\mathbf{R}} T(x) f(x)$

 $-\ln f_{a,\sigma^2}(\xi_1) = \frac{(\xi_1 - \xi_1)}{2}$

 $(\mathbf{x}) \cdot \left(\frac{\partial}{\partial \theta} \ln L(\mathbf{x}, \theta)\right)$



 $\int_{\partial \theta} \int_{R_n} T(x) f(x, \theta) d\theta = \int_{R_n} T(x) f(x) d\theta = \int_{R_n} T(x) f(x) d\theta = \int_{R_n} T(x) d\theta$

 $f(\mathbf{x}) \cdot \frac{\partial}{\partial \theta} f(\mathbf{x}, \theta) d\mathbf{x} = \mathbf{M} \left(f(\mathbf{x}, \theta) d\mathbf{x} = \mathbf{M} \right)$

 $(\mathbf{x}) \cdot \left(\frac{\partial}{\partial \theta} \ln L(\mathbf{x}, \theta)\right)$

Base of our number-system

Our number-system uses only the symbols 0, 1, ... 9; it has base ten. Ten is probably the base because we have ten fingers It is not known when or by whom

zero was invented.

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